## THE CHINESE UNIVERSITY OF HONG KONG Department of Mathematics MATH3310 2024-2025 Assignment 5 Due Date: December 7 before 11:59 PM

1. Below are the simultaneous iteration method with shift and the QR iteration method with shift.

 $\begin{array}{l} \textbf{Shifted Simultaneous Iteration} \\ \mbox{Let } Q^{(0)} = I \\ \mbox{For } k = 0, 1, 2, \dots \\ \bullet \mbox{ Choose shift } s_k \\ \bullet \ Y = (A - s_k I) \bar{Q}^{(k)} \\ \bullet \ QR \ factorization \ of \ Y : \ Y = \bar{Q}^{(k+1)} R^{(k+1)} \\ \mbox{Denote } \bar{R}^{(k)} = R^{(k)} R^{(k-1)} \cdots R^{(1)} \\ \hline \ \textbf{Shifted QR Iteration} \\ \mbox{Let } A^{(0)} = A \\ \mbox{For } k = 0, 1, 2, \dots \\ \bullet \ \mbox{Choose shift } s_k \\ \bullet \ Q^{(k+1)}_{QR} R^{(k+1)}_{QR} = A^{(k)} - s_k I \\ \bullet \ A^{(k+1)} = R^{(k+1)}_{QR} Q^{(k+1)}_{QR} + s_k I \\ \mbox{Denote } \bar{Q}^{(k)}_{QR} = Q^{(1)}_{QR} Q^{(2)}_{QR} \cdots Q^{(k)}_{QR}, \Bar{R}^{(k)}_{QR} = R^{(k)}_{QR} R^{(k-1)}_{QR} \cdots R^{(1)}_{QR} \end{array}$ 

(a) According to the definition of shifted QR iteration, directly prove  $A^{(k+1)} = \left(Q_{QR}^{(k+1)}\right)^T A^{(k)}Q_{QR}^{(k+1)}$ and  $A^{(k)} = \left(\bar{Q}_{QR}^{(k)}\right)^T A \bar{Q}_{QR}^{(k)}$ .

- (b) To prove the following properties, you may need mathematical induction.
  - i.  $(A s_k I)(A s_{k-1}I) \cdots (A s_0 I) = \bar{Q}^{(k+1)} \bar{R}^{(k+1)}$
  - ii.  $(A s_k I)(A s_{k-1}I) \cdots (A s_0 I) = \bar{Q}_{QR}^{(k+1)} \bar{R}_{QR}^{(k+1)}$ (Hint: using the conclusion in (a), show  $A - s_k I = \bar{Q}_{QR}^{(k+1)} (A^{(k+1)} - s_k I) (\bar{Q}_{QR}^{(k+1)})^T$ ) iii.  $\bar{Q}^{(k+1)} = \bar{Q}_{QR}^{(k+1)}$  and  $\bar{R}^{(k+1)} = \bar{R}_{QR}^{(k+1)}$
- 2. Suppose A is real symmetric positive definite, and let the nonzero  $\boldsymbol{p}_i$ 's be A-orthogonal, that is.  $\boldsymbol{p}_i^T A \boldsymbol{p}_j = 0$  if  $i \neq j$ . let  $\boldsymbol{x}_k = \boldsymbol{x}_0 + \sum_{i=0}^{k-1} \alpha_j \boldsymbol{p}_j$ , and  $f(\boldsymbol{x}) = \frac{1}{2} \boldsymbol{x}^T A \boldsymbol{x} - \boldsymbol{b}^T \boldsymbol{x}$ 
  - (a) show that  $p_i$ 's are linearly independent.
  - (b) Given a fixed integer k, show that if  $\boldsymbol{x}_k$  was chosen to minimize the  $f(\boldsymbol{x}), \forall \boldsymbol{x} \in \boldsymbol{x}_0 +$ span  $\{\boldsymbol{p}_0, \dots, \boldsymbol{p}_{k-1}\}$ , then determining the  $\alpha_k$  such that  $\boldsymbol{x}_k + \alpha_k \boldsymbol{p}_k$  minimizing  $f(\boldsymbol{x})$  is the same as choosing  $\boldsymbol{x}_{k+1}$  to minimize  $f(\boldsymbol{x}), \forall \boldsymbol{x} \in \boldsymbol{x}_0 +$ span  $\{\boldsymbol{p}_0, \dots, \boldsymbol{p}_{k-1}, \boldsymbol{p}_k\}$ . Moreover, what are the values of  $\alpha_0, \dots, \alpha_{k-1}$  such that  $\boldsymbol{x}_k = \underset{\alpha_0, \alpha_1, \dots, \alpha_{k-1}}{\operatorname{argmin}} f(\boldsymbol{x}_0 + \sum_{j=0}^{k-1} \alpha_j \boldsymbol{p}_j)$ ?
  - (c) Denote  $\mathcal{K}_{m+1}(A; r_0) = \text{span}\{r_0, Ar_0, A^2r_0, \dots, A^mr_0\}$ , and here is an equivalent statement of conjugate gradient method.

## Conjugate gradient method for solving Ax = b (not optimized)

Let  $\mathbf{x}_0$  be the initial vector and  $\mathbf{r}_0 = A\mathbf{x}_0 - \mathbf{b}, \mathbf{p}_0 = -\mathbf{r}_0$ . For  $k = 0, 1, \dots$ ,

$$\begin{aligned} \alpha_k &= -\frac{\mathbf{p}_k^T \mathbf{r}_k}{\mathbf{p}_k^T A \mathbf{p}_k} \\ \mathbf{x}_{k+1} &= \mathbf{x}_k + \alpha_k \mathbf{p}_k \\ \mathbf{r}_{k+1} &= A \mathbf{x}_{k+1} - \mathbf{b} \\ \beta_k &= -\frac{\mathbf{r}_{k+1}^T A \mathbf{p}_k}{\mathbf{p}_k^T A \mathbf{p}_k} \\ \mathbf{p}_{k+1} &= -\mathbf{r}_{k+1} - \beta_k \mathbf{p}_k. \end{aligned}$$

in the class, we have proven the following several properties by induction.

i. for k = 0, 1, ..., n,

span { $\mathbf{r}_0, \mathbf{r}_1, \dots, \mathbf{r}_k$ } = span { $\mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_k$ } =  $\mathcal{K}_{k+1}(A; \mathbf{r}_0)$ 

ii. for  $1 \leq i, j \leq n$  and  $i \neq j$ ,

$$\mathbf{r}_i^T \mathbf{r}_j = 0$$
 and  $\mathbf{p}_i^T A \mathbf{p}_j = 0$ 

Using these properties and conclusion in (b), prove that

$$oldsymbol{x}_k = \operatorname*{argmin}_{oldsymbol{x} \in oldsymbol{x}_0 + \mathcal{K}_k(A; oldsymbol{r}_0)} f(oldsymbol{x})$$

3. Suppose A is a real symmetric matrix and  $A = QDQ^T$  where  $Q^TQ = I$  and  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$ . Assume

$$|\lambda_1| \ge |\lambda_2| \ge \cdots \ge |\lambda_k| > |\lambda_{k+1}| \ge \cdots \ge |\lambda_n|.$$

Let  $E_k$  denote the subspace spanned by the first k columns of Q, equivalently, subspace spanned by eigenvectors associated with  $\lambda_1, \lambda_2, \ldots, \lambda_k$ , and let  $\cos \angle (\boldsymbol{x}^{(0)}, E_k) \neq 0$  We define

$$\cos \angle (\boldsymbol{x}, E_k) := \max \left\{ \cos \angle (\boldsymbol{x}, \boldsymbol{y}) : \boldsymbol{y} \in E_k \setminus \{0\} \right\},\\ \sin \angle (\boldsymbol{x}, E_k) := \min \left\{ \sin \angle (\boldsymbol{x}, \boldsymbol{y}) : \boldsymbol{y} \in E_k \setminus \{0\} \right\},\\ \tan \angle (\boldsymbol{x}, E_k) := \frac{\sin \angle (\boldsymbol{x}, E_k)}{\cos \angle (\boldsymbol{x}, E_k)}.$$

Let  $\boldsymbol{x}^{(m)} = A^m \boldsymbol{x}^{(0)} = A \boldsymbol{x}^{(m-1)},$ 

(a) Suppose  $\boldsymbol{x}^{(0)} = \sum_{i=1}^{n} a_i \vec{q_i}$ , where  $\vec{q_i}$  is the eigenvector associated with  $\lambda_i$ , show that

$$\tan^2 \angle (\boldsymbol{x}^{(m+1)}, E_k) = \frac{\sum_{i=k+1}^n (a_i)^2 |\lambda_i|^{2(m+1)}}{\sum_{i=1}^k (a_i)^2 |\lambda_i|^{2(m+1)}}$$

(b) prove that

$$\tan \angle (x^{(m+1)}, E_k) \le \frac{|\lambda_{k+1}|}{|\lambda_k|} \tan \angle (x^{(m)}, E_k)$$