

Pullback of differential forms:

$$g: U \subset \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$\omega = \sum_I f_I dx_I \in \mathcal{A}^k(\mathbb{R}^n)$$

$$g^*(\omega) = \sum_I (f_I \circ g) dg_I \in \mathcal{A}^k(\mathbb{R}^m)$$

Remark: 1. We think functions on $\mathbb{R}^n$ are 0-forms. In this case

$$g^*(f) = f \circ g \in \mathcal{A}^0(\mathbb{R}^m) \quad \forall f \in \mathcal{A}^0(\mathbb{R}^n).$$

2. We think x_i is a function: $\mathbb{R}^n \rightarrow \mathbb{R}$. For example, let $p = (a, b, c) \in \mathbb{R}^3$. Then $x_1(p) = a$, $x_2(p) = b$, $x_3(p) = c$. Thus $x_i \in \mathcal{A}^0(\mathbb{R}^n)$ and $dx_i \in \mathcal{A}^1(\mathbb{R}^n)$.

3. Computing integrals in different coordinates is equivalent to pullback of differential forms

$$\text{Ex 1. } g: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\omega = xy dx + 2z dy - y dz \in \Omega^1(\mathbb{R}^3)$$

$$(u, v) \mapsto (uv, u^2, 3u+v)$$

$$g^*(\omega) = uv \cdot u^2 duv + 2(3u+v) du^2 - u^2 d(3u+v)$$

$$= u^3 v (u dv + v du) + (6u + 2v) \cdot 2u du - u^2 (3 du + dv)$$

$$= (u^3 v^2 + 9u^2 + 4uv) du + (u^4 v - u^2) dv$$

2. $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$ differentiable. $\omega = dy_1 \wedge \dots \wedge dy_n$

$$g^*(\omega) = \sum_{j_1, \dots, j_n} \frac{\partial g_1}{\partial x_{j_1}} \dots \frac{\partial g_n}{\partial x_{j_n}} dx_{j_1} \wedge \dots \wedge dx_{j_n} \quad (\text{in})$$

Note $dx_{j_1} \wedge \dots \wedge dx_{j_n} \neq 0$ iff $j_1, \dots, j_n$ are distinct, so

$$\begin{aligned} \textcircled{2} &= \sum_{\sigma \in S_n} \frac{\partial g_1}{\partial x_{\sigma(1)}} \dots \frac{\partial g_n}{\partial x_{\sigma(n)}} dx_{\sigma(1)} \wedge \dots \wedge dx_{\sigma(n)} \\ &= \sum_{\sigma \in S_n} \frac{\partial g_1}{\partial x_{\sigma(1)}} \dots \frac{\partial g_n}{\partial x_{\sigma(n)}} \text{sign}(\sigma) dx_1 \wedge \dots \wedge dx_n \\ &= (\det Dg) dx_1 \wedge \dots \wedge dx_n \end{aligned}$$

This implies the formula of change of variables:

$$\int_{g(u)} f \, dx_1 \wedge \dots \wedge dx_n = \int_u f \circ g \cdot |\det Dg| \, dx_1 \wedge \dots \wedge dx_n$$

$$3. \vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \vec{F} = (F_1, F_2, F_3)$$

$$\eta = F_1 \, dy \wedge dz - F_2 \, dx \wedge dz + F_3 \, dx \wedge dy$$

$$\begin{aligned} \text{Then } d\eta &= dF_1 \wedge dy \wedge dz - dF_2 \wedge dx \wedge dz + dF_3 \wedge dx \wedge dy \\ &= \frac{\partial F_1}{\partial x} dx \wedge dy \wedge dz - \frac{\partial F_2}{\partial y} dy \wedge dx \wedge dz + \frac{\partial F_3}{\partial z} dz \wedge dx \wedge dy \\ &= \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) dx \wedge dy \wedge dz \\ &= \text{div } \vec{F} \, dx \wedge dy \wedge dz \end{aligned}$$

Recall (Generalized Stokes' thm): $\int_{\partial M} \omega = \int_M d\omega$

$$\text{Let } \omega = \eta, \text{ We have } \int_{\partial M} F_1 \, dy \wedge dz - F_2 \, dx \wedge dz + F_3 \, dx \wedge dy = \int_M \text{div } \vec{F} \, dx \wedge dy \wedge dz$$

This is the Divergence Thm.

Similarly, by letting $w = F_1 dx + F_2 dy + F_3 dz$, we have

$$dw = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy \wedge dz + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) dz \wedge dx + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx \wedge dy.$$

This implies Stokes' Thm.