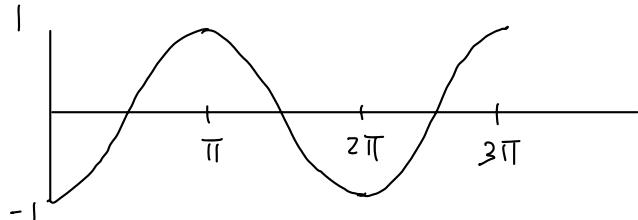


supplementary exs

$$(1) \begin{cases} x = u & , u \in [0, 1] \\ y = -\cos \theta & , \theta \in [0, 3\pi] \end{cases}$$

onto, but not one-to-one

$$[0, 1] \times [0, 3\pi] \longrightarrow [0, 1] \times [-1, 1]$$



covers $[-1, 1]$ 3 times:
with 2 positive direction
1 negative direction

$$\begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial \theta} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & \sin \theta \end{pmatrix} \Rightarrow \frac{\partial(x, y)}{\partial(u, \theta)} = \sin \theta$$

- $\iint_{[0,1] \times [-1,1]} dA = \iint_{[0,1] \times [-1,1]} dx dy = \text{Area}([0,1] \times [-1,1]) = 2$

- $\iint_{[0,1] \times [0, 3\pi]} \left| \frac{\partial(x, y)}{\partial(u, \theta)} \right| du d\theta = \int_0^{3\pi} \int_0^1 |\sin \theta| du d\theta$
 $= \int_0^{2\pi} |\sin \theta| d\theta$
 $= \int_0^\pi \sin \theta d\theta + \int_\pi^{2\pi} (-\sin \theta) d\theta + \int_{2\pi}^{3\pi} \sin \theta d\theta$
 $= 6 \quad (3 \times |\pm \text{Area}|)$
 $\neq \text{Area}([0,1] \times [-1,1])$

- $\iint_{[0,1] \times [0, 3\pi]} \frac{\partial(x, y)}{\partial(u, \theta)} du d\theta = \int_0^{3\pi} \int_0^1 \sin \theta du d\theta = \int_0^{3\pi} \sin \theta d\theta$
 $= 2 \quad (2 \times (+\text{Area}) + 1 \times (-\text{Area}))$

In general, if $(u, v) \mapsto (x, y)$ is not 1-1 onto,

$$\iint f(x, y) dx dy \neq \iint f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv,$$

but may still have (under suitable conditions)

$$\iint f(x, y) dx dy = \iint f(x(u, v), y(u, v)) \frac{\partial(x, y)}{\partial(u, v)} du dv.$$

$$(2) \quad \begin{cases} x = u \\ y = v \end{cases} \quad (u, v) \in [0, 1] \times [0, 1] \quad (\text{one-to-one \& onto})$$

$$[0, 1] \times [0, 1] \rightarrow [0, 1] \times [0, 1]$$

$$\begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow \frac{\partial(x, y)}{\partial(u, v)} = -1$$

- $\iint_{[0,1] \times [0,1]} dA = \iint_{[0,1] \times [0,1]} dx dy = \text{Area}([0,1] \times [0,1]) = 1$ || change of variables formula is verified.

- $\iint_{[0,1] \times [0,1]} \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv = \iint_{[0,1] \times [0,1]} |-1| du dv = 1$

- $\iint_{[0,1] \times [0,1]} \frac{\partial(x, y)}{\partial(u, v)} du dv = \iint_{[0,1] \times [0,1]} (-1) du dv = -1$

New formula

$$\iint_{[0,1] \times [0,1]} dx dy = \iint_{[0,1] \times [0,1]} \frac{\partial(x, y)}{\partial(u, v)} du dv = \iint_{[0,1] \times [0,1]} -du dv = \iint_{[0,1] \times [0,1]} dv du$$

Reason : (1) $dxdy$ or $dydx$ in double integrals represent the same area element , and

$dxdydz$, $dydxdz$, ... etc in triple integrals represent the same volume element.

No orientation (in the definition)

(Perhaps also represent the "order" of iterated integrals using Fubini's Thm.)

(2) However, $dxdy$ and $dydx$ can be used to represent the area element and the orientation

of the "surfaces" in one notation . (see later remark)

Similarly , for $dxdydz$ & etc.

Exterior differentiation "d" on a form " ω ".

(0-form) f	df	(1-form)
(1-form) $\omega = \omega_1 dx + \omega_2 dy + \omega_3 dz$	$d\omega = d\omega_1 \wedge dx + d\omega_2 \wedge dy + d\omega_3 \wedge dz$	(2-form)
$\zeta = \zeta_1 dy \wedge dz + \zeta_2 dz \wedge dx + \zeta_3 dx \wedge dy$	$d\zeta = d\zeta_1 \wedge dy \wedge dz + d\zeta_2 \wedge dz \wedge dx + d\zeta_3 \wedge dx \wedge dy$	(3-form)
(3-form) $f dx \wedge dy \wedge dz$	$df \wedge dx \wedge dy \wedge dz = 0$	(4-form) in \mathbb{R}^3

eg 0 : $d(dx) = d(dy) = d(dz) = 0$

eg 1 (in \mathbb{R}^2) $\omega = M dx + N dy$ ($M = M(x, y)$, $N = N(x, y)$)

then $d\omega = dM \wedge dx + dN \wedge dy$

$$= (M_x dx + M_y dy) \wedge dx + (N_x dx + N_y dy) \wedge dy$$

$$= (N_x - M_y) dx \wedge dy$$

\uparrow (+ve) oriented area element

In this notation, Green's Thm

$$\oint_{C=\partial R} M dx + N dy = \iint_R (N_x - M_y) dA \quad (C \text{ is anti-clockwise})$$

can be written as

$$\oint_{\partial R} \omega = \iint_R d\omega$$