Vector Fields

In component form:  

$$R^{2} = \vec{F}(x,y) = M(x,y)\hat{i} + N(x,y)\hat{j}$$

$$R^{3} = \vec{F}(x,y,z) = M(x,y,z)\hat{i} + N(x,y,z)\hat{j} + L(x,y,z)\hat{k}$$
where M, N, L are functions on D called the components  
of  $\vec{F}$ .

 $\underline{eg_{36}} \quad (\underline{fradient vector field of a function})$   $(i) \quad f(x,y) = \frac{1}{2}(x^2 + y^2)$   $\overline{\nabla}f(x,y) \stackrel{dof}{=} (\underline{\partial}f, \underline{\partial}f) = (x,y) = xi + yj = \overline{r}(x,y)$   $\underline{position vector field}.$ 

(ij) 
$$f(x,y,z) = X$$
  
 $\overline{\nabla}f(x,y,z) \stackrel{\text{def}}{=} \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right) = (1,0,0) = \hat{\lambda}$   
(a constant vector field)

$$\underbrace{eg37}_{k} (\text{Vector field along a curve})$$
Let C be a curve in  $\mathbb{R}^2$  parametrised by
$$\overrightarrow{T} = [a, b] \rightarrow \mathbb{R}^2$$

$$\xrightarrow{T} = [a, b] \rightarrow \mathbb{R}^2$$

$$\xrightarrow{T} \to (X(t), y(t)) = \overrightarrow{r}(t)$$

$$\underbrace{Fas}_{k} = \underbrace{\overrightarrow{r}(t)}_{||\overrightarrow{r}(t)||}$$

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 $\frac{\text{Remark}}{\text{If we use } ds = ||\overline{r'(t)}|| dt, \text{ then}$ 

$$\hat{T} = \frac{\vec{r}(t)}{\|\vec{r}(t)\|} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{d\vec{r}}{ds} \quad (by \text{ Chain rule})$$

$$(af s is a function of t)$$

where "arc-lungth s" 
$$\vec{v}$$
 defined by  
 $S(t) = \int_{t_0}^{t} ||\vec{v}'(t)|| dt$ , (up to an additive constant)

A parametrization of a unit 
$$C$$
 by arc-length  $S$   
is called arc-length parametrization:  
 $\overline{\gamma}(S) = arc-length parametrization $\Rightarrow \|\frac{d\overline{\gamma}(S)}{dS}\| = 1$$ 

Def 11 A vector field is defined to be 
$$\frac{\text{continuous}}{\frac{\text{differentiable}}{\frac{\text{ch}}{2}}$$
 of the component functions are.

$$\frac{eq38}{F(X,y)} = F(X,y) = X\hat{i} + y\hat{j} \quad \& \quad C^{\infty} \quad (\text{position vector})$$

$$\frac{F(X,y)}{F(X,y)} = \frac{-y\hat{i} + X\hat{j}}{\sqrt{X^2 + y^2}} \quad \& \quad \text{not} \quad (\text{antiunon in } \mathbb{R}^2)$$

$$(\text{but cartinuon in } \mathbb{R}^2 \cdot \frac{3}{9}, 0, 0) \in \mathcal{F}$$

$$\begin{split} & [ \underbrace{ine \ integral \ of \ wecton \ field} \\ & \underline{Pef12}: \quad lot \ C \ be a \ couve \ with \ \vec{r}(t_{2} \neq 0, \ \forall t_{2}. \ Define \ the \\ & \underline{Parametrization} \ \vec{r}(t_{2}) \ with \ \vec{r}(t_{2} \neq 0, \ \forall t_{2}. \ Define \ the \\ & \underline{Parametrization} \ \vec{r}(t_{2}) \ with \ \vec{r}(t_{2} \neq 0, \ \forall t_{2}. \ Define \ the \\ & \underline{Parametrization} \ \vec{r}(t_{2}) \ with \ \vec{r}(t_{2} \neq 0, \ \forall t_{2}. \ Define \ the \\ & \underline{Parametrization} \ \vec{r}(t_{2}) \ with \ \vec{r}(t_{2} \neq 0, \ \forall t_{2}. \ Define \ the \\ & \underline{Parametrization} \ \vec{r}(t_{2}) \ \vec{r}($$

and 
$$\int_{C} \vec{F} \cdot \vec{T} \, dS = \int_{C} \vec{F} \cdot d\vec{T}$$

$$eg_{3s} : \vec{F}(X, y, z) = z\vec{i} + xy\vec{j} - y^{2}\vec{k}$$

$$C : \vec{F}(x) = z\vec{i} + x\vec{j} + J\vec{x}\vec{k}, \quad o \le t \le 1$$

 $\underline{Som} = d\vec{r} = (zt\vec{\lambda} + j + \frac{1}{2\sqrt{t}}\hat{k})dt$ 

$$\begin{aligned} & \int_{C} \vec{F} \cdot \vec{T} dS = \int_{C} \vec{F} \cdot d\vec{r} \\ &= \int_{C} (Z(t)\vec{\lambda} + \chi(t)y(t)\vec{j} - y(t)\vec{h}) \cdot d\vec{r} \\ &= \int_{C}^{1} (I\vec{t}\vec{\lambda} + t^{3}\vec{j} - y^{2}\vec{k}) \cdot (zt\vec{i} + \vec{j} + \frac{1}{2\sqrt{t}}\vec{h}) dt \\ &= \int_{0}^{1} (I\vec{t}\vec{\lambda} + t^{3}\vec{j} - y^{2}\vec{k}) \cdot (zt\vec{i} + \vec{j} + \frac{1}{2\sqrt{t}}\vec{h}) dt \end{aligned}$$

In components from:  
Line integral of 
$$\vec{F} = M\vec{i} + N\vec{j}$$
 along  
 $C : \vec{r}(t) = g(t)\vec{i} + h(t)\vec{j}$ 

can be expressed as

$$\int_{C} \vec{F} \cdot \vec{f} \, ds = \int_{C} \vec{F} \cdot d\vec{r} = \int_{a}^{b} (\vec{F} \cdot \frac{d\vec{r}}{dt}) dt$$
$$= \int_{a}^{b} (Mg' + Nf') dt$$

(mue explicitly: 
$$\int_{a}^{b} [M(g(t), h(t))g(t) + N(g(t), h(t))h(t)]dt)$$

Note that, 
$$y = g(x)$$
  
 $y = f_1(t)$   
 $\Rightarrow \int dx = g'(x) dt$   
 $\Rightarrow \int dy = f_1'(t) dt$ 

$$\int_{C} \vec{F} \cdot \vec{f} \, dS = \int_{C} \vec{F} \cdot d\vec{r} = \int_{a}^{b} M \, dx + N \, dy$$

Subsiditly, for 3-dim  

$$\int_{C} \vec{F} \cdot \vec{T} dS = \int_{C} \vec{F} \cdot d\vec{F} = \int_{a}^{b} M dx + N dy + L dz$$

$$(for \vec{F} = M_{a}^{T} + N_{j}^{T} + L\vec{k})$$
Another way to justify the notation:  

$$\vec{F} = (X, Y, z) \quad \text{the paintion vector}$$

$$\Rightarrow \quad d\vec{F} = (dx, dy, dz) \quad (natural notation)$$
Then  

$$\int_{C} \vec{F} \cdot \vec{T} dS = \int_{C} \vec{F} \cdot d\vec{r} = \int_{C} (M_{j}N_{j}L) \cdot (dx, dy, dz)$$

$$= \int_{C} M dx + N dy + L dz.$$

$$\frac{\log 39}{2}: \text{Evaluate } I = \int_{C} -y \, dx + z \, dy + 2x \, dz$$
where  $C: F(t) = \cot i + \sin t \, j + t \, k$  (ostszm)  
 $= (\cot , \sin t, t)$ 

$$\frac{\text{Sohn}:}{I} = \int_{C} (-\sin t) d(\cot) + t \, d(\operatorname{suit}) + 2 \cot dt$$

$$= \int_{C}^{2\pi} (\sin^{2} t + t \cot t + 2 \cot t) \, dt$$

$$= \cdots = \pi$$
 (check!) ×

 $(d\vec{r} = (-sint, ost, 1)dt \in \vec{r}(t) = (-sint, ost, 1))$ 

M	<u>ote</u> :	$\mathbf{S}$			
_	sungle	ND	Yes	NO	Yes
	closed	Yes	No	NO	Tes



Famula for 
$$\hat{n}$$
 (with the parametrization  $\hat{F}(t) = X(t)\hat{i} + y(t)\hat{j}$ )  
Recall  $\hat{T} = \frac{\hat{F}(t)}{||\hat{F}(t)||} = \frac{x(t)\hat{i} + y(t)\hat{j}}{||\hat{F}(t)||}$   
(in an - lungth parametrization =  $\hat{T} = \frac{d\hat{T}}{ds} = \frac{dx}{ds}\hat{i} + \frac{dy}{ds}\hat{j}$ )  
Anti-clockwise:  
 $\hat{n} = \hat{T} \times \hat{k} = \begin{vmatrix} \hat{x} & \hat{j} & \hat{k} \\ \frac{x'}{||\hat{F}'||} & \frac{y'}{||\hat{F}'||} & 0 \\ 0 & 0 & 1 \end{vmatrix}$   
 $\Rightarrow \hat{n} = \frac{y(t)\hat{x} - x(t)\hat{j}}{||\hat{F}'|t|||} (\alpha - \hat{n} = \frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j})$   
Clockwise:  $\hat{n} = -\frac{y'(t)\hat{i} + x'(t)\hat{j}}{||\hat{F}'|t|||} (\alpha - \hat{n} = \frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j})$   
Elux of  $\vec{F}$  across  $\hat{C} = \frac{def}{ds} \int_{C} \vec{F} \cdot \hat{n} ds$  (and  $\hat{f}(t) = x(t)\hat{i} + y(t)\hat{j}$   $\hat{g} = \frac{auti-clockwise}{autochization} = \frac{dt}{ds}\hat{j}$   
Then

Flux of 
$$\vec{F}$$
 across  $\vec{C}$   
=  $(M\hat{i}+N\hat{j})\cdot(\frac{dy}{ds}\hat{i}-\frac{dx}{ds}\hat{j})ds$   
=  $(Mdy - Ndx)$ 

$$\frac{eg}{6} + 0: Let \vec{F} = (x-y)\hat{i} + x\hat{j}$$

$$C : x^{2}+y^{2} = 1$$
Find the flow (auti-clochnisely) along C and  
flux across C.  
Soln: Let  $\vec{F}(t) = (0 \text{ st } \hat{i} + a \text{ int } \hat{j}, 0 \le t \le 2\pi)$   
Note: correct orientation - autificant  
Then  $flow = \oint_{C} \vec{F} \cdot \hat{T} ds$   

$$= \oint_{C} \vec{F} \cdot d\hat{r} (= \oint_{C} M dx + N dy)$$

$$= \int_{0}^{2\pi} [(cost - autif)\hat{i} + cost\hat{j}][-aut\hat{i} + (cost\hat{j}]] dt$$

$$= \int_{0}^{2\pi} [aut(au \pm - cost) + cos^{2}t] dt$$

$$= \dots = 2\pi \qquad (check!)$$
flux =  $\int_{0}^{2\pi} [cost - aut + )d(aut) - (aut d cost)$ 

$$= \int_{0}^{2\pi} [cost - aut + )d(aut) - (aut d cost)$$

$$= \int_{0}^{2\pi} [cost - aut + )d(aut) + aut cost] dt$$

$$= \int_{0}^{2\pi} [cost - aut + )d(aut) + aut cost] dt$$



• If f is a scalar function  

$$\int_C f ds = \int_{-C} f ds$$
 as "ds" is not oriented,  
 $\int_C f ds = \int_{-C} f ds$  just "length"

• If 
$$\vec{F}$$
 is a vecta field  
flow  $\int_{C} \vec{F} \cdot \hat{T} dS = -\int_{-C} \vec{F} \cdot \hat{T} dS$   
this  $\hat{T}$  is the " $\hat{T}$  funct"

More precise formula :  $\int_{C} \vec{F} \cdot \hat{T}_{C} \, dS = - \int_{-C} \vec{F} \cdot \hat{T}_{-C} \, dS$ 

· But fa flux

 $\oint_{\mathcal{C}} \vec{\mathsf{F}} \cdot \hat{\mathsf{n}} d\mathsf{S} = \oint_{\mathcal{C}} \vec{\mathsf{F}} \cdot \hat{\mathsf{n}} d\mathsf{S}$   $\hat{\mathsf{n}}$  always outward

<u>Summary:</u>

<u>scalar</u>	Sit des indep. of crientation	ds trave no direction
<u>vecta È</u> Flow	$\int_{\mathcal{C}} \vec{F} \cdot \vec{F}  ds$ depends on mentation	7 depends on direction
flux	Sc F. nds indep. of mentation	n always outward