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(2) $\{y=0, 0 \leq x \leq 1\}: f(x,0) = -4x^3$

$$f(1,0) = -4 \leq f(x,0) \leq 0 = f(0,0)$$

(3) $\{x=1, 0 \leq y \leq 1\}: f(1,y) = 6y - 4 - 3y^2 = -3(y-1)^2 + 1$

$$f(1,0) = -4 \leq f(1,y) \leq 1 = f(1,1)$$

(4) $\{y=1, 0 \leq x \leq 1\}: f(x,1) = 6x - 4x^3 - 3$

$$0 = \frac{d}{dx} f(x,1) = 6 - 12x^2 \Rightarrow x = \frac{1}{\sqrt{2}}$$

$$f\left(\frac{1}{\sqrt{2}}, 1\right) = -3 - 2\sqrt{2} < 0$$

$$f(0,1) = -3, \quad f(1,1) = 1$$

$$\Rightarrow f(0,1) = -3 \leq f(x,1) \leq -3 - 2\sqrt{2} < f\left(\frac{1}{\sqrt{2}}, 1\right)$$

$$\max: f(0,0) = 0, \quad \min: f(1,0) = -4$$

Compare values

global max at $\left(\frac{1}{2}, \frac{1}{2}\right)$ with value $\frac{1}{4}$
 global min at $(1,0)$ with value -4

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Matrix form for 2nd order Taylor polynomial

Def: let $f: W \rightarrow \mathbb{R}$ be C^2 ($W \subseteq \mathbb{R}^n$, open),
then the Hessian matrix of f at $\vec{a} \in W$ is

$$Hf(\vec{a}) = \begin{bmatrix} f_{x_1 x_1}(\vec{a}) & \cdots & f_{x_1 x_n}(\vec{a}) \\ \vdots & & \vdots \\ f_{x_n x_1}(\vec{a}) & \cdots & f_{x_n x_n}(\vec{a}) \end{bmatrix}$$

Remarks

(1) $Hf(\vec{a})$ is $n \times n$ symmetric (by Clairaut's theorem)

(2) In textbook, Hessian of $f = \det(Hf(\vec{a}))$

So we emphasize our definition is a matrix

eg: $f(x,y)$ at $(0,0)$

$$Hf(0,0) = \begin{bmatrix} f_{xx}(0,0) & f_{xy}(0,0) \\ f_{yx}(0,0) & f_{yy}(0,0) \end{bmatrix}$$

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} f_{xx}(0,0) & f_{xy}(0,0) \\ f_{yx}(0,0) & f_{yy}(0,0) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = f_{xx}(0,0)x^2 + 2f_{xy}(0,0)xy + f_{yy}(0,0)y^2$$

2nd order term in Taylor Polynomials
(up to a factor $\frac{1}{2!}$)

2nd order Taylor Polynomial of f at $\vec{a}$ in matrix form

$$P_2(\vec{x}) = f(\vec{a}) + \vec{\nabla} f(\vec{a})(\vec{x} - \vec{a}) + \frac{1}{2}(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a})$$

where $\vec{\nabla} f(\vec{a})$ regarded as row vector $[f_{x_1}(\vec{a}), \dots, f_{x_n}(\vec{a})]$,
 $\vec{x} - \vec{a}$ regarded as column vector $\begin{bmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{bmatrix}$

& $(\vec{x} - \vec{a})^T$ is the transpose $[x_1 - a_1, \dots, x_n - a_n]$.

eg $g(x,y) = \frac{\ln x}{1-y}$ Find $P_2(x,y)$ at $(1,0)$ using matrix form

$$g(1,0) = 0$$

$$\vec{\nabla} g = \left[\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y} \right] = \left[\frac{1}{x(1-y)}, \frac{\ln x}{(1-y)^2} \right]$$

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$$H_g = \begin{bmatrix} \frac{\partial^2 g}{\partial x^2} & \frac{\partial^2 g}{\partial x \partial y} \\ \frac{\partial^2 g}{\partial y \partial x} & \frac{\partial^2 g}{\partial y^2} \end{bmatrix} = \begin{bmatrix} -\frac{1}{x^2(1-y)} & \frac{1}{x(1-y)^2} \\ \frac{1}{x(1-y)^2} & \frac{2 \ln x}{(1-y)^3} \end{bmatrix}$$

$$\begin{aligned} p_2(x, y) &= g(1, 0) + \vec{\nabla} g(1, 0) \begin{bmatrix} x-1 \\ y \end{bmatrix} \\ &= (x-1) - \frac{1}{2}(x-1)^2 + (x-1)y. \end{aligned}$$

Application to local max/min

If f is C^2 , and $\vec{a}$ is a critical point of f ,
then $\vec{\nabla} f(\vec{a}) = \vec{0}$.

$$\Rightarrow f(\vec{x}) \approx p_2(\vec{x}) = f(\vec{a}) + \vec{\nabla} f(\vec{a})(\vec{x} - \vec{a}) + \frac{1}{2}(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a})$$

$$\Rightarrow f(\vec{x}) - f(\vec{a}) \approx \frac{1}{2}(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a})$$

$$\text{If } (\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a}) < 0 \quad \forall \vec{x} \text{ near } \vec{a}$$

$$\text{then } f(\vec{x}) < f(\vec{a}) \quad \forall \vec{x} \text{ near } \vec{a}$$

$$\Rightarrow \vec{a} \text{ is a local max}$$

$$\text{If } (\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a}) > 0 \quad \forall \vec{x} \text{ near } \vec{a}$$

$$\text{then } f(\vec{x}) > f(\vec{a}) \quad \forall \vec{x} \text{ near } \vec{a}$$

$$\Rightarrow \vec{a} \text{ is a local min}$$

So we need to study when is a symmetric matrix H satisfies

$$\vec{v}^T H \vec{v} > 0 \quad \forall \text{ vector } \vec{v} \neq \vec{0}$$

$$\text{and } \vec{v}^T H \vec{v} < 0 \quad \forall \text{ vector } \vec{v} \neq \vec{0}.$$

Hence we make the following

Def. let H be a symmetric $n \times n$ matrix. Then H is said to be

(1) positive definite if $\vec{x}^T H \vec{x} > 0$

for all column vector $\vec{x} \in \mathbb{R}^n \setminus \{\vec{0}\}$

(2) negative definite if $\vec{x}^T H \vec{x} < 0$

for all column vector $\vec{x} \in \mathbb{R}^n \setminus \{\vec{0}\}$

(3) indefinite if $\exists$ column vectors $\vec{x}, \vec{y} \in \mathbb{R}^n \setminus \{\vec{0}\}$

such that $\vec{x}^T H \vec{x} > 0$ and $\vec{y}^T H \vec{y} < 0$.

Remark. These are not all possibilities: $\exists$ symmetric matrix which is not positive definite, negative definite, and indefinite

Then the discussion above implies
The (Second Derivative Test)

Let $\begin{cases} \cdot f: U \rightarrow \mathbb{R} \text{ be } C^2, U \subseteq \mathbb{R}^n, \text{ open} \\ \cdot a \in U \text{ such that } \nabla f(a) = 0 \end{cases}$

Then $Hf(a)$ is $\begin{cases} \text{positive definite} \Rightarrow a \text{ is a local min} \\ \text{negative definite} \Rightarrow a \text{ is a local max} \\ \text{indefinite} \Rightarrow a \text{ is a saddle point} \end{cases}$

Remark: A critical point which is neither local max nor local min is called a saddle point.

In particular for 2-variable, $\vec{v}^T H \vec{v}$ is of the function

$$g(x, y) = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = ax^2 + 2bxy + cy^2.$$

eg (1) $[x, y] \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 + 4y^2 > 0, \forall [x, y] \in \mathbb{R}^2 \setminus \{0\}$

$\therefore \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$ is positive definite

(2) $[x, y] \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -x^2 + 4y^2 < 0, \forall [x, y] \in \mathbb{R}^2 \setminus \{0\}$

$\therefore \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix}$ is negative definite

(3) $[x, y] \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -x^2 + 4y^2$

① If $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, then it is $4 > 0$.

② If $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, then it is $-1 < 0$.

$\therefore \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix}$ is indefinite.

(4) $[x, y] \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 \geq 0$

But $\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 \Rightarrow$ not positive definite

$\therefore \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ is not positive definite, negative definite, not indefinite.

$$(5) [x, y] \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 + 4xy + 5y^2 > 0$$

$\Rightarrow \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$ is Positive definite.

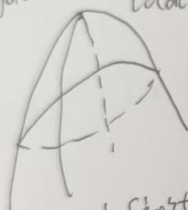
6 Geometrically (locally near the critical point)

(1) $Hf(\bar{a})$ positive definite

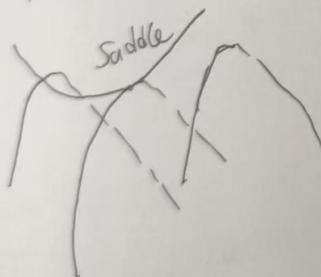
The graph of $z = [x, y] Hf(\bar{a}) \begin{bmatrix} x \\ y \end{bmatrix}$ looks like



(2) $Hf(\bar{a})$ negative definite local max



(3) $Hf(\bar{a})$ is indefinite



Theorem let $H = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$.

Then H is $\begin{cases} \text{Positive definite} \Leftrightarrow \det H = ac - b^2 > 0, \& a > 0 \\ \text{Negative definite} \Leftrightarrow \det H = ac - b^2 > 0, \& a < 0 \\ \text{Indefinite} \Leftrightarrow \det H = ac - b^2 < 0 \end{cases}$

Pf: If $a \neq 0$,
$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = ax^2 + 2bxy + cy^2$$
$$= a \left(x^2 + 2\frac{b}{a}xy + \frac{ac-b^2}{a^2}y^2 \right) = a \left[\left(x + \frac{b}{a}y \right)^2 + \frac{ac-b^2}{a^2}y^2 \right]$$

(1) $\det H = ac - b^2 > 0 \Leftrightarrow$
 $\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ has the same sign as a

$\therefore$ The 1st two statements are proved.

(2) $\det H = ac - b^2 < 0 \Leftrightarrow$ 2 terms have different sign

$\Leftrightarrow \begin{bmatrix} a & b \\ b & c \end{bmatrix}$ is indefinite

If $a = 0 \Rightarrow \det H = ac - b^2 = -b^2 < 0$

$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 2bxy + cy^2$

may be positive and may

eg 2: (Not every function has global max/min)

(i) $f(x) = e^x$ on $\mathbb{R}$ (Domain unbounded) $\rightarrow$ No global max / no global min

(ii) $f(x) = x$ on $(-1, 1]$ (Domain not closed) $\rightarrow$ has global max

(iii) $f(x) = \begin{cases} -x, & 0 < x \leq 1, \\ 0, & x = 0, \\ -1-x, & -1 \leq x < 0. \end{cases}$
No global max and global min

Extreme Value theorem

Let $\begin{cases} \bullet A \subseteq \mathbb{R}^n \text{ be closed and bounded,} \\ \bullet f: A \rightarrow \mathbb{R} \text{ be continuous} \end{cases}$

Then f has global max and min

Proof: If f is continuous on a bounded set, then we can know f is bounded. we let m and M be the upper bound and lower bound. (by least upper/lower bound of the real number). we also have there must be some $x \in A$ such that $M - f(x) < \epsilon$. If no $x \in A$ such that $f(x) > m$ holds, we have $m - f(x) > 0$ always hold

$\Rightarrow \frac{1}{\epsilon} > \frac{1}{m - f(x)}$, it is because $\frac{1}{m - f(x)}$ is still continuous in A (the co-construct a sequence $\frac{1}{m - f(x)} \rightarrow \infty$, it is a contradiction,

Def: let $f: A \rightarrow \mathbb{R}, A \in \mathbb{R}^n$ (not necessarily open)
 $a \in \text{Int}(A)$

Then a is called a critical point of f if

either (1) $\nabla f(a)$ DNE,

or (2) $\nabla f(a) = \vec{0}$.

Theorem (First Derivative Test)

Suppose $f: A \rightarrow \mathbb{R} (A \subset \mathbb{R}^n)$ attains a local extreme at $a \in \text{Int}(A)$, then a is a critical point of f .

proof: Suppose f has a local extremum at $a \in \text{Int}(A)$, then a is a critical point of f .

proof: Suppose f has a local extremum at $a \in \text{Int}(A)$, if $\nabla f(a)$ DNE, then a is a critical point.

If $\nabla f(a)$ exists, then $\frac{\partial f}{\partial x_i}(a)$ exists $\forall i=1, \dots, n$

$\forall i$, Consider the 1-variable function
 $g_i(t) = f(a + te_i)$

Where $g_i(0) = f(a) \leq f(a + te_i)$
 or $\geq$

$\Rightarrow t=0$ is a local max/min

$$\Rightarrow \frac{dg_i}{dt} \Big|_{t=0} = \frac{df(a+te_i)}{dt} \Big|_{t=0} = \frac{\partial f}{\partial x_i}(a) = 0$$

$\frac{df(a+te_i)}{dt} = \frac{f(a+te_i) - f(a)}{t}$

$\begin{cases} \geq 0 & \text{if } t > 0 \\ \leq 0 & \text{if } t < 0 \end{cases}$

Strategy for finding extreme

$$f: A \rightarrow \mathbb{R}$$

(1) Find critical points of f in $\text{Int}(A)$.

(2) study f on boundary ∂A

Find maximum of f on ∂A .

(3) Compare values of f at points found in steps (1) & (2).

eg 1: Find global max/min of $f(x,y) = x^2 + 2y^2 - x + 3$ for $x^2 + y^2 \leq 1$

Solution:

Critical points in $\text{Int}(A)$

$$= \text{Int} \{x^2 + y^2 < 1\}$$

$$= \{x^2 + y^2 < 1\}$$

We know the polynomials always have derivatives, $\nabla f = (2x-1, 4y)$.

$$\vec{0} = \nabla f \Leftrightarrow \begin{cases} 2x-1=0 \\ 4y=0 \end{cases} \Leftrightarrow (x,y) = (\frac{1}{2}, 0)$$

$$f(\frac{1}{2}, 0) = \frac{11}{4}$$

Step 2: study f on $\partial\{x^2+y^2 \leq 1\} = \{x^2+y^2=1\}$

$$\begin{aligned} f(x,y) &= x^2 + 2y^2 - x + 3 = 4 + y^2 - x \\ &= 5 - x^2 - x \\ &= 5 - (x + \frac{1}{2})^2 + \frac{1}{4} \\ &= \frac{21}{4} - (x + \frac{1}{2})^2 \end{aligned}$$

max value of f on $\partial D = \frac{21}{4}$

min value of f on $\partial D: \frac{21}{4} - \frac{9}{4} = \frac{12}{4} = 3$.

Step 3: Compare value of f at points from steps (1) & (2).

$$f(\frac{1}{2}, 0) = \frac{11}{4}$$

$$f(-\frac{1}{2}, \pm \frac{\sqrt{3}}{2}) = \frac{21}{4}$$

$$f(1, 0) = 3$$

$$\Rightarrow \begin{cases} \text{max value} = \frac{21}{4} \\ \text{min value} = \frac{11}{4} \end{cases}$$