

Matrix form for 2nd order Taylor Polynomial

Def: Let $f: \Omega \rightarrow \mathbb{R}$ be C^2 ($\Omega \subseteq \mathbb{R}^n$, open).

Then the Hessian matrix of f at $\vec{a} \in \Omega$ is

$$Hf(\vec{a}) = \begin{bmatrix} f_{x_1 x_1}(\vec{a}) & \cdots & f_{x_1 x_n}(\vec{a}) \\ \vdots & & \vdots \\ f_{x_n x_1}(\vec{a}) & \cdots & f_{x_n x_n}(\vec{a}) \end{bmatrix}$$

Remarks (1) $Hf(\vec{a})$ is $n \times n$ symmetric (by Clairaut's Thm)

(2) In Textbook, Hessian of $f = \det(Hf(\vec{a}))$

So we emphasize our definition is a
matrix (More common in advanced level math)

Eg: $f(x,y)$ at $(0,0)$

$$Hf(0,0) = \begin{bmatrix} f_{xx}(0,0) & f_{xy}(0,0) \\ f_{yx}(0,0) & f_{yy}(0,0) \end{bmatrix} \quad (f_{xy} = f_{yx})$$

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} f_{xx}(0,0) & f_{xy}(0,0) \\ f_{yx}(0,0) & f_{yy}(0,0) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \underbrace{f_{xx}(0,0)x^2 + 2f_{xy}(0,0)xy + f_{yy}(0,0)y^2}_{\text{2nd order term in Taylor polynomials (up to a factor } \frac{1}{2!})}$$

2nd order term in Taylor polynomials (up to a factor $\frac{1}{2!}$)

2nd order Taylor polynomial of f at \vec{a} in matrix form

$$P_2(\vec{x}) = f(\vec{a}) + \vec{\nabla}f(\vec{a})(\vec{x}-\vec{a}) + \frac{1}{2} (\vec{x}-\vec{a})^T Hf(\vec{a})(\vec{x}-\vec{a})$$

where $\vec{\nabla}f(\vec{a})$ regarded as row vector $[f_{x_1}(\vec{a}) \dots f_{x_n}(\vec{a})]$,

$\vec{x}-\vec{a}$ regarded as column vector $\begin{bmatrix} x_1-a_1 \\ \vdots \\ x_n-a_n \end{bmatrix}$

& $(\vec{x}-\vec{a})^T$ is the transpose $[x_1-a_1 \dots x_n-a_n]$
(row vector)

Q $g(x,y) = \frac{\ln x}{1-y}$. Find $P_2(x,y)$ at $(1,0)$ using matrix form.

Soh : $g(1,0) = 0$

$$\vec{\nabla}g = \left[\frac{\partial g}{\partial x} \quad \frac{\partial g}{\partial y} \right] = \left[\frac{1}{x(1-y)} \quad \frac{\ln x}{(1-y)^2} \right]$$

$$Hg = \begin{bmatrix} g_{xx} & g_{xy} \\ g_{yx} & g_{yy} \end{bmatrix} = \begin{bmatrix} -\frac{1}{x^2(1-y)} & \frac{1}{x(1-y)^2} \\ \frac{1}{x(1-y)^2} & \frac{\ln x}{(1-y)^3} \end{bmatrix}$$

$$\Rightarrow \vec{\nabla}g(1,0) = [1, 0], \quad Hg(1,0) = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{aligned} \therefore P_2(x,y) &= g(1,0) + \vec{\nabla}g(1,0) \begin{bmatrix} x-1 \\ y \end{bmatrix} + \frac{1}{2} [x-1 \ y] Hg(1,0) \begin{bmatrix} x-1 \\ y \end{bmatrix} \\ &= 0 + [1 \ 0] \begin{bmatrix} x-1 \\ y \end{bmatrix} + \frac{1}{2} [x-1 \ y] \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x-1 \\ y \end{bmatrix} \\ &= (x-1) - \frac{1}{2}(x-1)^2 + (x-1)y \quad (\text{check!}) \quad \times \end{aligned}$$

Application to local max/min

If $f \in C^2$, and \vec{a} is a critical point of f .

Then $\vec{\nabla}f(\vec{a}) = \vec{0}$

$$\Rightarrow f(\vec{x}) \approx P_2(\vec{x}) = f(\vec{a}) + \vec{\nabla}f(\vec{a})(\vec{x} - \vec{a}) + \frac{1}{2}(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a})$$
$$f(\vec{x}) - f(\vec{a}) \approx \frac{1}{2}(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a})$$

\therefore If $(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a}) < 0 \quad \forall \vec{x} \text{ near } \vec{a}$

then $f(\vec{x}) < f(\vec{a}) \quad \forall \vec{x} \text{ near } \vec{a}$

$\Rightarrow \vec{a}$ is a local max

If $(\vec{x} - \vec{a})^T Hf(\vec{a})(\vec{x} - \vec{a}) > 0 \quad \forall \vec{x} \text{ near } \vec{a}$

then $f(\vec{x}) > f(\vec{a}) \quad \forall \vec{x} \text{ near } \vec{a}$

$\Rightarrow \vec{a}$ is a local min

So we need to study when is a sym matrix H satisfies

$$\vec{v}^T H \vec{v} > 0 \quad \forall \text{ vector } \vec{v} \neq \vec{0}$$

$$\text{and } \vec{v}^T H \vec{v} < 0 \quad \forall \text{ vector } \vec{v} \neq \vec{0}$$

Hence we make the following