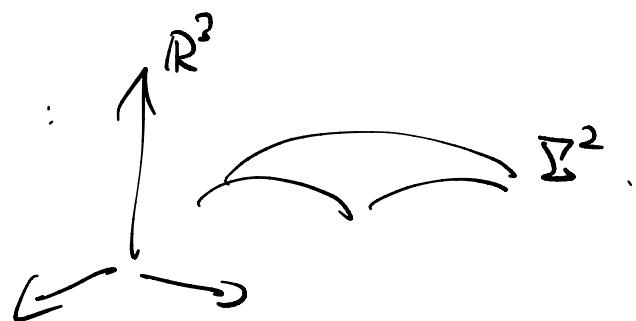


Week 3: Surfaces

Interested in 2D objects :



size 2-dm objects : regular surfaces
 ↓
 (no sharp points, no edge, no self intersections.)

Mathematically:

Defn: A subset $S \subseteq \mathbb{R}^3$ is a regular surface if & there exists $p \in S$, \exists open nbhd $V \subseteq \mathbb{R}^3$, open set $U \subseteq \mathbb{R}^2$, and a map $X: U \rightarrow V \cap S$ s.t.

① X is smooth;

② X is a homeomorphism;

③ If $g \in U$, $dX_g: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is injective.



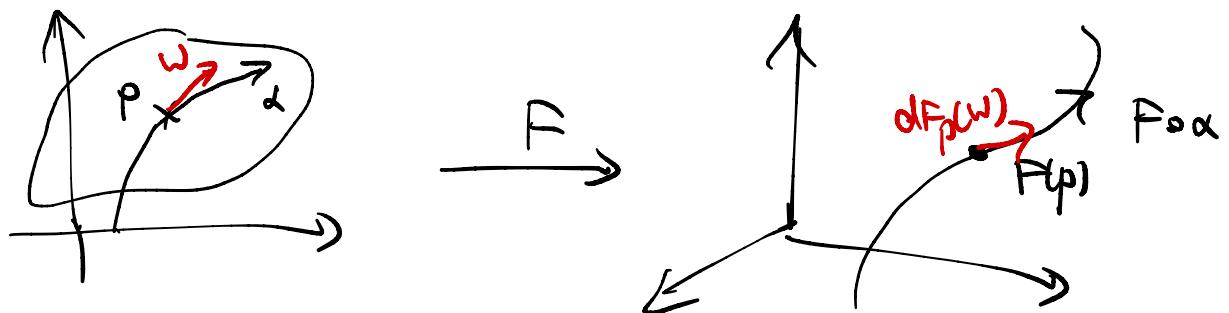
Here, the mapping X is called parametrization
 w.r.t. system of local coord.

* i.e. A regular surface $\Sigma \subset \mathbb{R}^3$ is a set $\subseteq \mathbb{R}^3$ which can be covered by family of coordinate charts.

Defn (differential of smooth map)

Let $F: V^{\text{open}} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$. $\forall p \in V$, we define a linear map $dF_p: \mathbb{R}^n \rightarrow \mathbb{R}^m$ (called differential of F at p)

as $dF_p(w) = \left. \frac{d}{dt} \right|_{t=0} F \circ \alpha(t)$ where $\alpha: (-\varepsilon, \varepsilon) \rightarrow V$
 is a differentiable curve s.t. $\begin{cases} \alpha(0) = p \\ \alpha'(0) = w. \end{cases}$



prop: The defn of dF_p is independent of choice of α . Hence, it is well-defined.

pf: WLOG, assume $n=2, m=3$ (the general case is similar)

Let $F(x, y) = (f_1, f_2, f_3) \in \mathbb{R}^3$.

WLOG, assume $p = (0, 0)$

let $\omega = (a, b) \in \mathbb{R}^2$, $\alpha : (-\varepsilon, \varepsilon) \rightarrow \mathbb{R}^2$

where $\begin{cases} \alpha(0) = (0, 0) \\ \alpha'(\omega) = (a, b). \end{cases}$, $\alpha(t) = (x(t), y(t))$

Then

$$F \circ \alpha(t) = (f_1(x(t), y(t)), f_2(x(t), y(t)), f_3(x(t), y(t)))^T$$

$$\begin{aligned} \frac{d}{dt}|_{t=0} F \circ \alpha &= \left(\frac{\partial f_1}{\partial x} \cdot \frac{dx}{dt}|_0 + \frac{\partial f_1}{\partial y} \cdot \frac{dy}{dt}|_0, \right. \\ &\quad \left. \frac{\partial f_2}{\partial x} \cdot a + \frac{\partial f_2}{\partial y} \cdot b \right)^T \end{aligned}$$

$$\Downarrow dF_p = \begin{bmatrix} \frac{\partial f_1}{\partial x}|_p & \frac{\partial f_1}{\partial y}|_p \\ \frac{\partial f_2}{\partial x}|_p & \frac{\partial f_2}{\partial y}|_p \\ \frac{\partial f_3}{\partial x}|_p & \frac{\partial f_3}{\partial y}|_p \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \quad \#$$

$dF_p(e_1)$ $dF_p(e_2)$

where $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

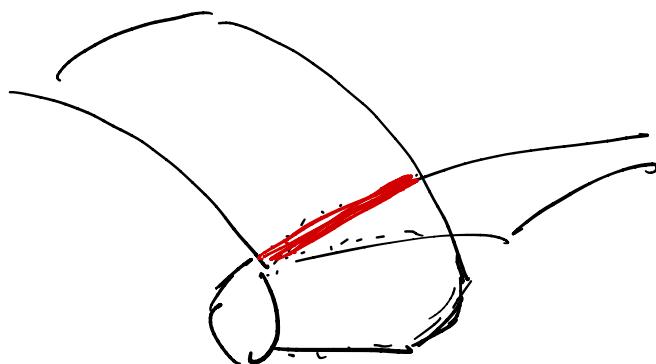
$\star: dX_p = -1$ in def of surface:

rank of matrix = 2

$\hookrightarrow \{dX_p(e_1), dX_p(e_2)\}$ are linearly
indep.

*: $X = \text{bijection} \Rightarrow \text{prevent self-intersection}$

counter-example



prop: If $f: U \rightarrow \mathbb{R}$ is a differentiable
fn on open subset $U \subseteq \mathbb{R}^2$. Then
 $S = \{(x, y, f(x, y)) \mid (x, y) \in U\}$ is
a regular surface.

pf: clearly, $X: U \rightarrow V$ given by

① $X(u, v) = (u, v, f(u, v))$ is smooth.

② $\begin{cases} dX_p(e_1) = (1, 0, f_u) & \text{linearly} \\ dX_p(e_2) = (0, 1, f_v) & \text{indep.} \end{cases}$

③ $\chi^1: V \rightarrow U$ given by

$$\chi^1(u, v, f(u, v)) = (u, v) \text{ is obs. } \cancel{\chi}$$

Example: $S^2 \subseteq \mathbb{R}^3$

$$\{(x, y, z) \mid x^2 + y^2 + z^2 = 1\}$$

local charts:

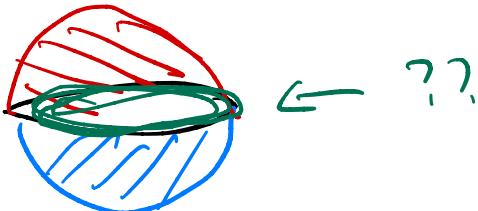
• $\chi_1: V_1 \rightarrow \mathbb{R}^3$ where

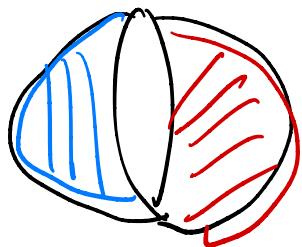
$$V_1 = \{(x, y) \mid x^2 + y^2 < 1\}$$

$$\chi_1(u, v) = (u, v, \sqrt{1-u^2-v^2})$$

• $\chi_2: V_1 \rightarrow \mathbb{R}^3$ by

$$\chi_2(u, v) = (u, v, -\sqrt{1-u^2-v^2})$$





$$X_3(u,v) = (u, \sqrt{1-u^2-v^2}, v)$$

$$X_4(u,v) = (u, -\sqrt{1-u^2-v^2}, v)$$

$$X_5 = (\sqrt{1-u^2-v^2}, u, v)$$

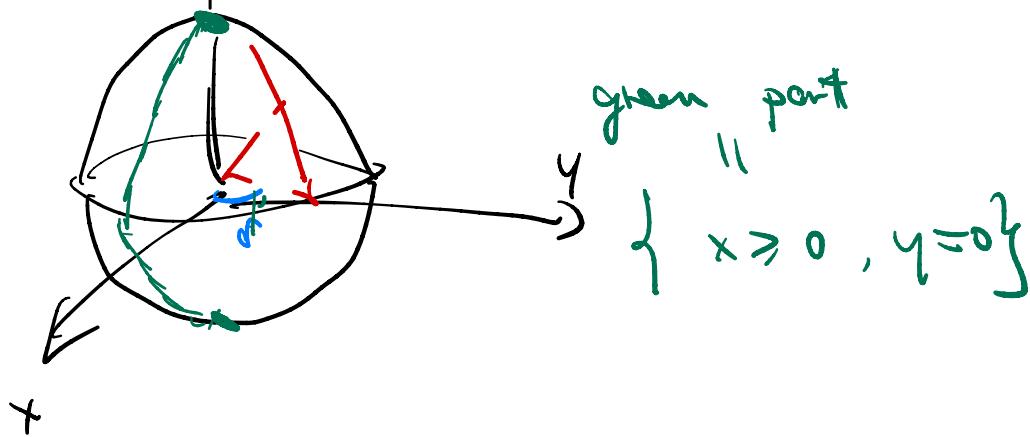
$$X_6 = (-\sqrt{1-u^2-v^2}, u, v)$$

Other coordination of S^2

Ⓐ spherical coordinate

$$X(\theta, \phi) = (\sin\theta \cos\phi, \sin\theta \sin\phi, \cos\theta)$$

$$U = \{(\theta, \phi) \mid 0 < \theta < \pi, 0 < \phi < 2\pi\}$$



Checking : local chart

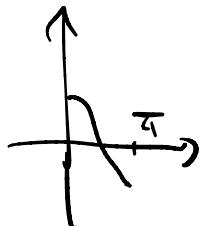
① differentiable ✓

$$\left\{ \begin{array}{l} \frac{\partial x}{\partial \theta} = (\cos \theta \cos \varphi, \cos \theta \sin \varphi, -\sin \theta) \\ \frac{\partial x}{\partial \varphi} = (-\sin \theta \sin \varphi, \sin \theta \cos \varphi, 0) \end{array} \right.$$

is linearly indep unless $\sin \theta = 0 \Rightarrow \theta \in \pi \mathbb{Z}$.
→ ↙.

③ given $(x, y, z) \in S^2 \setminus \{x \geq 0, y = 0\}$

take $\theta \in [0, \pi]$ s.t. $\cos \theta = z$. $\because |z| \leq 1$



If $\theta = 0$ or π ,
 $|z| = 1$

$\Rightarrow x = y = 0 \rightarrow \leftarrow$

$\therefore \theta \in (0, \pi)$ and is unique.

$(\theta = \cos^{-1} z \text{ is differentiable here})$

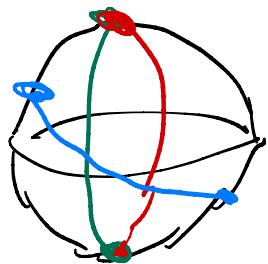
Now

$$\begin{cases} y = \sin \theta \cos \varphi \\ x = \sin \theta \sin \varphi \end{cases}$$

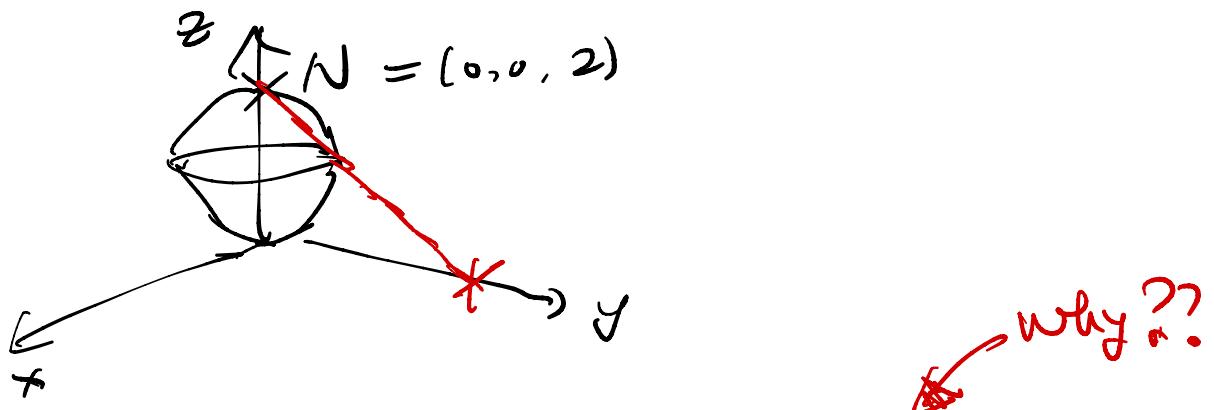
determine φ uniquely
by $x, y, \theta(z)$.

#.

Construct X_2, X_3 by (diff.) rotation.



Stereographic projection:



$$X(u,v) = \left(\frac{4u}{u^2+v^2+4}, \frac{4v}{u^2+v^2+4}, \frac{2(u^2+v^2)}{u^2+v^2+4} \right)$$

$$X: \mathbb{R}^2 \rightarrow S^2 \setminus N.$$

But $S^2 = \{(x,y,z) \mid f(x,y,z)=0\}$

$$\text{where } f(x,y,z) = x^2 + y^2 + z^2 - 1$$

* Level set of a very nice function!!

Q: If $S = \{(x, y, z) \mid F(x, y, z) = 0\}$
 for some smooth fun $F: \mathbb{R}^3 \rightarrow \mathbb{R}$,
 Is S always a regular surface??

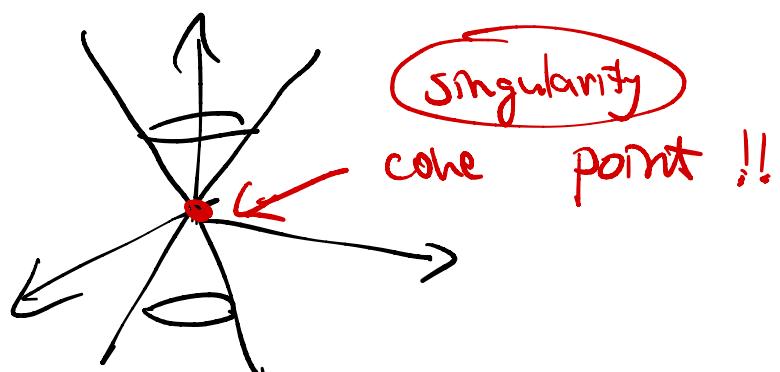
"Counter-example":

$$\textcircled{1} \quad S = \{(x, y, z) \mid x^2 + y^2 + z^2 = 0\}$$

then $S = \{(0, 0, 0)\} \neq \text{surface}$.

$$\textcircled{2} \quad S = \{(x, y, z) \mid x^2 + y^2 - z^2 = 0\}$$

then S :



More . . .

from eg 2:

$$S^+ = \{F = 0, z \geq 0\}$$

$$= \{(x, y, z) \mid z = \sqrt{x^2 + y^2}\}$$

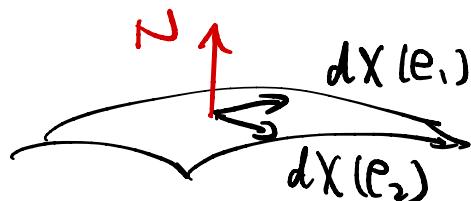
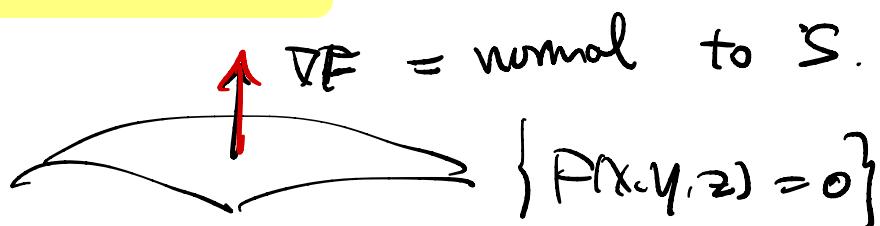
Viewed as graph, then $z = f(x, y)$

$$\frac{\partial f}{\partial x} = \frac{x}{\sqrt{x^2+y^2}}, \quad \frac{\partial f}{\partial y} = \frac{y}{\sqrt{x^2+y^2}}$$

singular at $(0,0)$

$$\nabla F = (2x, 2y, -2z) \underset{\text{failure?}}{=} 0 \text{ at } (0,0,0) !!$$

geometrically,



$$N = dX(e_1) \times dX(e_2)$$

is well defined when

dX = full rank.

prop: Let $U \subseteq \mathbb{R}^3$ be open set.

Let $F: U \rightarrow \mathbb{R}$ be differentiable fun.

If $a \in \mathbb{R}$ is a regular value of F
 (i.e. $\nexists (x, y, z) \stackrel{\neq p}{\sim}$ s.t. $F(x, y, z) = a$,)
 we have $dF(p) \neq 0$
 $\Leftrightarrow dF(p) = \text{full rank}$

then $S = F^{-1}(a)$ is a regular surface.

Tof: let $p_0 \in S$ (i.e. $F(p_0) = a$)

$$\nabla F(p_0) = (F_x, F_y, F_z)|_{p_0} \neq 0$$

assume $F_z(p_0) \neq 0$.

Define $G(x, y, z) = (x, y, F(x, y, z))$ s.t.

$$dG = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ F_x & F_y & F_z \end{bmatrix} \Rightarrow \det(dG(p_0)) \neq 0$$

IFT $\Rightarrow \exists$ nbd V of p_0 ,

nbd U of $G(p_0)$ s.t.

G has a C^∞ inverse on U .

$$G^{-1}(u, v, w) = (u, v, \tilde{F}(u, v, w))$$

Recall : looking for $X(u,v) \in S$

Taking $X : U \rightarrow \mathbb{R}^3$ given by

$$X(u,v) = G^{-1}(u,v,a)$$

$$= (u,v, \tilde{F}(u,v,a)) \text{ s.t.}$$

Since

$$(u,v,a) = G \circ G^{-1}(u,v,a)$$

$$= G(u,v, \tilde{F}(u,v,a))$$

$$= (u,v, F(u,v,\tilde{F}))$$

$$\Rightarrow F(X(u,v)) = a \quad (\text{i.e. } X(u,v) \in S)$$

$\therefore S$ is locally a graph over U .

\Rightarrow regular surface !!