

Convolution

Definition: Consider $k \in M_{N \times N}(\mathbb{R})$ and $f \in M_{N \times N}(\mathbb{R})$. Assume k and f are periodically extended. That is:

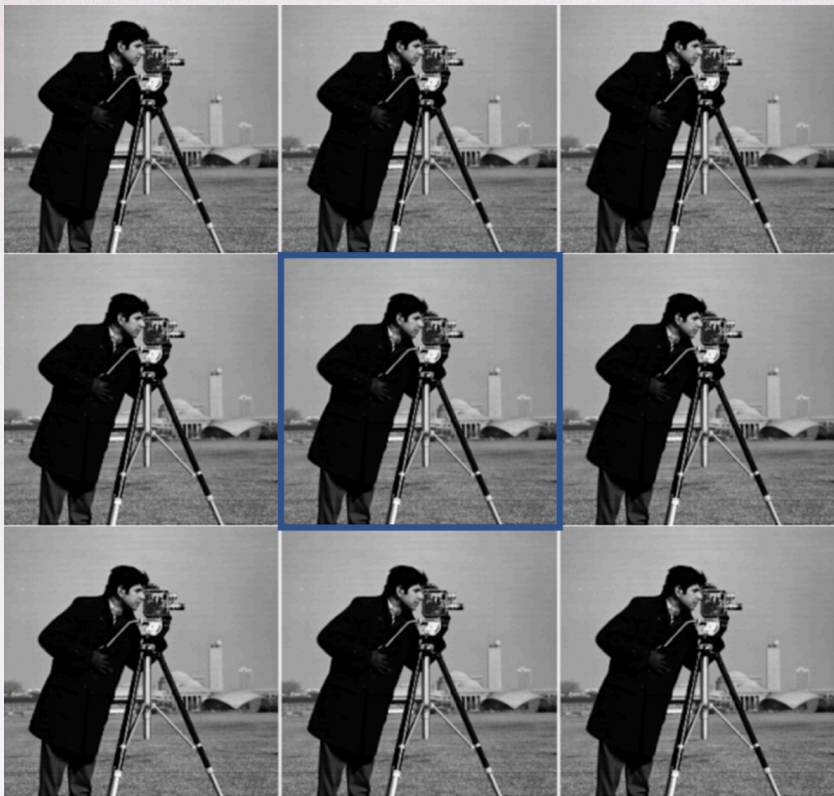
$$k(x, y) = k(x + pN, y + qN) \quad \text{where } p, q \text{ are integers.}$$

$$f(x, y) = f(x + pN, y + qN)$$

The convolution $k * f$ of k and f is a $N \times N$ matrix defined

as:

$$k * f(\alpha, \beta) = \sum_{x=1}^N \sum_{y=1}^N k(x, y) f(\alpha - x, \beta - y) \quad \text{for } 1 \leq \alpha, \beta \leq N$$



$f(3, 2)$

"

$f(0, -1)$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

← Row -2

← Row -1

← Row 0

$f =$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

← Row 1

← Row 2

← Row 3

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

← Row 4

← Row 5

← Row 6

↑ ↑ ↑
Col-2 Col-1 Col 0

↑ ↑ ↑
Col 1 Col 2 Col 3

↑ ↑ ↑
Col 4 Col 5 Col 6

Example: Let $k = \begin{pmatrix} \frac{1}{9} & \frac{1}{9} & \frac{1}{9} \\ \frac{1}{9} & \frac{1}{9} & \frac{1}{9} \\ \frac{1}{9} & \frac{1}{9} & \frac{1}{9} \end{pmatrix}$ and $f \in M_{3 \times 3}(\mathbb{R})$. Find $k * f(2, 2)$

$$k * f(2, 2) = \sum_{x=1}^3 \sum_{y=1}^3 k(x, y) f(2-x, 2-y)$$

$$= \frac{1}{9} f(1, 1) + \frac{1}{9} f(1, 0) + \frac{1}{9} f(1, -1) + \frac{1}{9} f(0, 1) + \frac{1}{9} f(0, 0) + \frac{1}{9} f(0, -1) \\ + \frac{1}{9} f(-1, 1) + \frac{1}{9} f(-1, 0) + \frac{1}{9} f(-1, -1)$$

$$= \frac{f(1, 1) + f(1, 2) + f(1, 3) + f(2, 1) + f(2, 2) + f(2, 3) + f(3, 1) + f(3, 2) + f(3, 3)}{9}$$

(Averaging the intensity values in the neighborhood of $f(2, 2)$)

Remark: Averaging is commonly used in image processing, which is related to convolution.

Theorem: Let $k \in M_{N \times N}(\mathbb{R})$. Define $\mathcal{O}: M_{N \times N}(\mathbb{R}) \rightarrow M_{N \times N}(\mathbb{R})$ by:

$$\mathcal{O}(f) = k * f \quad \text{for all } f \in M_{N \times N}(\mathbb{R}).$$

Then: \mathcal{O} is linear.

Pf: Followed from the definition of convolution.

Theorem: Let $k \in M_{N \times N}(\mathbb{R})$ and $f \in M_{N \times N}(\mathbb{R})$. Then: $k * f = f * k$.

Proof: Assuming $\alpha, \beta > 1$,

$$k * f(\alpha, \beta) = \sum_{x=1}^{\alpha} \sum_{y=1}^{\beta} k(x, y) f(\alpha - x, \beta - y)$$

$$= \sum_{\tilde{x}=\alpha-N}^{\alpha-1} \sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha - \tilde{x}, \beta - \tilde{y}) f(\tilde{x}, \tilde{y}) \quad (\text{let } \tilde{x} = \alpha - x, \tilde{y} = \beta - y)$$

$$\stackrel{??}{=} \sum_{\tilde{x}=1}^{\alpha} \sum_{\tilde{y}=1}^{\beta} k(\alpha - \tilde{x}, \beta - \tilde{y}) f(\tilde{x}, \tilde{y}) = f * k(\alpha, \beta).$$

$$\sum_{\tilde{x}=\alpha-N}^{\alpha-1} \sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y})$$

$$= \sum_{\tilde{x}=\alpha-N}^0 \left(\sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y}) \right) + \sum_{\tilde{x}=1}^{\alpha-1} \left(\sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y}) \right)$$

$k(\alpha - \tilde{x} + N, \beta - \tilde{y}) \quad f(\tilde{x} + N, \tilde{y})$
 (periodic extension)

$$= \sum_{\tilde{x}=\alpha}^N \left(\sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y}) \right) + \sum_{\tilde{x}=1}^{\alpha-1} \left(\sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y}) \right)$$

$$= \sum_{\tilde{x}=1}^N \left(\sum_{\tilde{y}=\beta-N}^{\beta-1} k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y}) \right) = \sum_{\tilde{x}=1}^N \sum_{\tilde{y}=1}^N k(\alpha-\tilde{x}, \beta-\tilde{y}) f(\tilde{x}, \tilde{y})$$

$$= f \times k(\alpha, \beta)$$

The case when $\alpha=1$ or $\beta=1$ can be shown similarly.

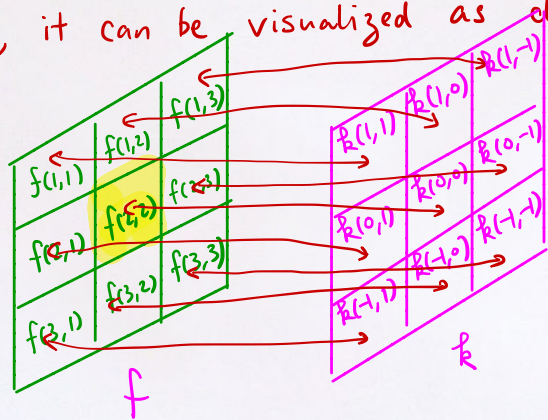
Geometric meaning of convolution

Consider $k \in M_{3 \times 3}(\mathbb{R})$ and $f \in M_{3 \times 3}(\mathbb{R})$.

$$\text{Consider: } k * f(2,2) = \sum_{x=1}^3 \sum_{y=1}^3 k(2-x, 2-y) f(x, y)$$

$$= k(1,1) f(1,1) + k(1,0) f(1,2) + k(1,-1) f(1,3) + k(0,1) f(2,1) + k(0,0) f(2,2) \\ + k(0,-1) f(2,3) + k(-1,1) f(3,1) + k(-1,0) f(3,2) + k(-1,-1) f(3,3)$$

Geometrically, it can be visualized as dot product:



Overlay k onto f
and take dot product.

Example: Let $\mathcal{O}: M_{N \times N}(\mathbb{R}) \rightarrow M_{N \times N}(\mathbb{R})$ be a linear image transformation defined by: $\mathcal{O}(f)(\alpha, \beta) = f(\alpha+1, \beta) + 2f(\alpha, \beta) - 2f(\alpha-1, \beta) + f(\alpha, \beta+1) - 2f(\alpha, \beta-1)$ for all $1 \leq \alpha, \beta \leq N$ and $f \in M_{N \times N}(\mathbb{R})$. Show that \mathcal{O} can be expressed in terms of a convolution.

Suppose $\mathcal{O}(f) = k * f$ for some $k \in M_{N \times N}(\mathbb{R})$. Then,

$$\begin{aligned} \text{Then: } \mathcal{O}(f)(\alpha, \beta) &= \sum_{x=1}^N \sum_{y=1}^N k(\alpha-x, \beta-y) f(x, y) \\ &= \dots + \overset{1}{k(-1, 0)} f(\alpha+1, \beta) + \overset{2}{k(0, 0)} f(\alpha, \beta) + \overset{-2}{k(1, 0)} f(\alpha-1, \beta) + \overset{1}{k(0, -1)} f(\alpha, \beta+1) \\ &\quad + \overset{-2}{k(0, 1)} f(\alpha, \beta-1) + \dots \end{aligned}$$

We set $k(-1, 0) = k(N-1, N) = 1$, $k(0, 0) = k(N, N) = 2$, $k(1, 0) = k(1, N) = -2$
 $k(0, -1) = k(N, N-1) = 1$, $k(0, 1) = k(N, 1) = -2$ and $k(x, y) = 0$ otherwise.

Then: $\mathcal{O}(f) = k * f$.

Definition: The point spread function $h^{\alpha, \beta}(x, y)$ of a linear image transformation is called **shift-invariant** if there exists a function \tilde{h}

Such that

$$h^{\alpha, \beta}(x, y) = \tilde{h}(\alpha - x, \beta - y)$$

for all $1 \leq x, y, \alpha, \beta \leq N$.

Remark: Given $k \in M_{N \times N}(\mathbb{R})$. Let \mathcal{O} be a linear image transformation defined by: $\mathcal{O}(f) = k * f$ for all $f \in M_{N \times N}(\mathbb{R})$.

Then: the point spread function of \mathcal{O} is shift-invariant.

Let $g = \mathcal{O}(f)$

$$g(\alpha, \beta) = \mathcal{O}(f)(\alpha, \beta) = \sum_{x=1}^N \sum_{y=1}^N \underbrace{k(\alpha - x, \beta - y)}_{h^{\alpha, \beta}(x, y)} f(x, y)$$