## Math 3360: Mathematical Imaging Assignment 4 Solution

1. Consider a  $2N \times 2N$  image  $I = (I(m, n))_{-N \le m, n \le N-1}$ . The Butterworth high-pass filter H of squared radius  $D_0$  and order n is applied on  $DFT(I) = (\hat{I}(u, v))_{-N \le u, v \le N-1}$  to give G(u, v). Suppose  $\hat{I}(1, 1) \ne 0$  and  $\hat{I}(2, 2) \ne 0$ , and

$$G(1,1) = \frac{1}{37}\hat{I}(1,1)$$
 and  $G(2,2) = \frac{1}{10}\hat{I}(2,2).$ 

Find  $D_0$  and n.

Solution: The given information implies

$$H(1,1) = \frac{1}{37}$$
 and  $H(2,2) = \frac{1}{10}$ 

Hence

$$\begin{cases} 1 - \frac{D_0^n}{D_0^n + 2^n} &= \frac{1}{37}, \\ 1 - \frac{D_0^n}{D_0^n + 8^n} &= \frac{1}{10}, \end{cases} \text{ and thus } \begin{cases} 36 \cdot 2^n &= D_0^n, \\ 9 \cdot 8^n &= D_0^n. \end{cases}$$

Then  $8^n = 4 \cdot 2^n$ . Hence n = 1 and then  $D_0 = 72$ .

- 2. (a) Consider a  $(2M + 1) \times (2N + 1)$  image  $I = (I(m, n))_{0 \le m \le 2M, 0 \le n \le 2N}$ , where M, N > 200. The Gaussian high-pass filter with standard deviation  $\sigma$  is applied to  $DFT(I) = (\hat{I}(u, v))_{0 \le m \le 2M, 0 \le n \le 2N}$ . Suppose  $H(2, 2) = \frac{1}{MN}$ . Find  $\sigma^2$ .
  - (b) Consider a Gaussian low-pass filter

$$H(u,v) = exp\left(-\frac{u^2 + v^2}{2\sigma^2}\right).$$

Suppose  $H(4,2) = \frac{1}{\sqrt{e}}H(1,-3)$ . Find  $\sigma^2$ .

Solution:

(a) The given information implies

$$1 - exp\left(-\frac{2^2 + 2^2}{2\sigma^2}\right) = \frac{1}{MN},$$

hence  $\sigma^2 = \frac{4}{\ln(MN) - \ln(MN - 1)}.$ 

(b) The given information implies

$$exp\left(-\frac{10}{\sigma^2}\right) = exp\left(-\frac{1}{2}\right)exp\left(-\frac{5}{\sigma^2}\right),$$

hence  $\frac{10}{\sigma^2} = \frac{1}{2} + \frac{5}{\sigma^2}$  and so  $\sigma^2 = 10$ .

3. Suppose  $g \in M_{N \times N}(\mathbb{R})$  is a blurred image capturing a static scene. Assume that g is given by:

$$g(u, v) = \frac{1}{\lambda} \sum_{k=0}^{\lambda-1} f(u-k, v) \text{ for } 0 \le u, v \le N-1,$$

where  $\lambda \in \mathbb{N} \cap [1, N]$  and f is the underlying image (periodically extended). Show that DFT(g)(u, v) = H(u, v)DFT(f)(u, v) for all  $0 \le u, v \le N - 1$ , where H(u, v) is the degradation function in the frequency domain given by:

$$H(u,v) = \begin{cases} \frac{1}{\lambda} \frac{\sin \frac{\lambda \pi u}{N}}{\sin \frac{\pi u}{N}} e^{-\pi j \frac{(\lambda-1)u}{N}} & \text{if } u \neq 0, \\ 1 & \text{if } u = 0. \end{cases}$$

**Solution:** Note that g = h \* f, where

$$h(u,v) = \begin{cases} \frac{1}{\lambda} & \text{if } u \le \lambda - 1, v = 0\\ 0 & \text{otherwise.} \end{cases}$$

Let  $0 \le u, v \le N - 1$ . Then

$$DFT(h)(u,v) = \frac{1}{\lambda N^2} \sum_{k=0}^{\lambda-1} e^{-2\pi j \frac{ku}{N}}$$

$$= \begin{cases} \frac{1}{\lambda N^2} \frac{1 - e^{-2\pi j \frac{\lambda u}{N}}}{1 - e^{-2\pi j \frac{u}{N}}} & \text{if } e^{-2\pi j \frac{u}{N}} \neq 1 \\ \frac{1}{N^2} & \text{if } e^{-2\pi j \frac{u}{N}} = 1 \end{cases}$$

$$= \begin{cases} \frac{1}{\lambda N^2} \frac{e^{-\pi j \frac{\lambda u}{N}} (e^{\pi j \frac{\lambda u}{N}} - e^{-\pi j \frac{\lambda u}{N}})}{e^{-\pi j \frac{u}{N}} (e^{\pi j \frac{u}{N}} - e^{-\pi j \frac{\lambda u}{N}})} & \text{if } u \notin N\mathbb{Z} \\ \frac{1}{N^2} & \text{if } u \in N\mathbb{Z} \end{cases}$$

$$= \begin{cases} \frac{1}{\lambda N^2} \frac{\sin \frac{\lambda \pi u}{N}}{\sin \frac{\pi u}{N}} e^{-\pi j \frac{(\lambda-1)u}{N}} & \text{if } u \neq 0 \\ \frac{1}{N^2} & \text{if } u \neq 0. \end{cases}$$

Since  $DFT(h * f) = N^2 DFT(h) \odot DFT(f)$ ,

$$H(u,v) = N^2 DFT(h)(u,v) = \begin{cases} \frac{1}{\lambda} \frac{\sin \frac{\lambda \pi u}{N}}{\sin \frac{\pi u}{N}} e^{-\pi j \frac{(\lambda-1)u}{N}} & \text{if } u \neq 0\\ 1 & \text{if } u = 0 \end{cases}$$

4. Consider a  $4 \times 4$  periodically extended image  $I = (I(k, l))_{0 \le k, l \le 3}$  given by:

where  $a, b, c \ge 0$ .

Consider the modified direct filter  $T_1$  with squared radius a and order b, which is defined by

$$T_1(u,v) = \frac{B(u,v)}{H_1(u,v) + \epsilon \cdot sgn(H_1(u,v))}$$

Consider the constrained least square filter  $T_2$  with parameter c, which is defined by

$$T_2(u,v) = \frac{1}{N^2} \frac{H_2(u,v)}{|H_2(u,v)|^2 + c|P(u,v)|^2}$$

Let  $I_2(u, v) = T_2(u, v)DFT(I)(u, v)$ . Suppose  $DFT(I)(0, 0) = \frac{1}{2}$ ,  $T_1(0, 2) = \frac{8}{17}$ ,  $DFT(I)(1, 1) \neq 0$  and  $I_2(1, 1) = \frac{3j}{73}DFT(I)(1, 1)$ . Find a, b, c. (Here,  $j = \sqrt{-1}$ .) Solution: First, from

$$DFT(I)(0,0) = \frac{1}{4^2} \sum_{k,l=0}^{3} I(k,l) = \frac{a + (a - 2c) + (b - 2c) + b}{4^2} = \frac{a + b - 2c}{8} = \frac{1}{2},$$

we know that a + b - 2c = 4. Secondly, recall that

$$H_1(u,v) = DFT(h_1)(u,v) = \frac{1}{4^2} \sum_{k,l=0}^3 h_1(k,l) e^{-2\pi j \frac{k \cdot u + l \cdot v}{4}}$$

we can compute

$$H_1(0,2) = \frac{1}{4^2} \sum_{k,l=0}^3 h_1(k,l) e^{-2\pi j \frac{2l}{4}} = \frac{1}{4^2} (\frac{1}{2} + \frac{1}{2}) = \frac{1}{16}$$

From

$$T_1(0,2) = \frac{B(0,2)}{H_1(0,2) + \epsilon \cdot sgn(H_1(0,2))} = \frac{1}{1 + (\frac{4}{a})^b} \bigg/ \left(\frac{1}{16} + sgn(\frac{1}{16})\right) = \frac{16}{17} \frac{1}{1 + (\frac{4}{a})^b} = \frac{8}{17} \frac{1}{1 + (\frac{4}{a})^b} = \frac{16}{17} \frac{1}{1 + (\frac{4}{a})^b}$$

Therefore,  $(\frac{4}{a})^b = 1$ . Besides,

$$H_2(1,1) = DFT(h_2)(1,1)$$
  
=  $\frac{1}{4^2} \sum_{k,l=0}^{3} h_2(k,l) e^{-2\pi j \frac{k+l}{4}}$   
=  $\frac{1}{16} \cdot \frac{1}{3} (1 + e^{-\frac{1}{2}\pi j} + e^{-\pi j})$   
=  $-\frac{1}{48} j$ 

Similarly,  $P(1,1) = DFT(\tilde{h})(1,1) = -\frac{1}{4}$ . Hence

$$T_2(1,1) = \frac{1}{4^2} \frac{\overline{H_2(1,1)}}{|H_2(1,1)|^2 + c|P(1,1)|^2} = \frac{1}{16} \frac{\frac{1}{48}j}{\frac{1}{48^2} + c\frac{1}{4^2}} = \frac{3j}{1+144c} = \frac{3j}{73}$$

From  $\begin{cases} a+b-2c = 4\\ (\frac{4}{a})^b = 1 & \text{and } a, b, c \ge 0,\\ 73 = 1+144c & \end{cases}$ 

we know that either  $a = 4, b = 1, c = \frac{1}{2}$  or  $a = 5, b = 0, c = \frac{1}{2}$ 

- 5. The constrained least square filtering aims to find a vectorized image  $\vec{f}$  of a  $N \times N$  image f that minimizes:  $E(\vec{f}) = (L\vec{f})^T (L\vec{f})$  subject to the constraint:  $[\vec{g} H\vec{f}]^T [\vec{g} H\vec{f}] = \epsilon$ , for some block-circulant matrices H and L.  $\epsilon$  is a fixed parameter greater than 0.
  - (a) Let  $W = W_2 \otimes W_2$ , where  $W_2(k,n) = \frac{1}{\sqrt{2}}e^{\pi j k n}$  for  $0 \le k, n \le 1$  and  $\otimes$  is the Kronecker product. Given that  $H = W \Lambda_H W^{-1}$  and  $L = W \Lambda_L W^{-1}$ , where

$$\Lambda_{H} = \begin{pmatrix} h_{0} & 0 & 0 & 0 \\ 0 & h_{1} & 0 & 0 \\ 0 & 0 & h_{2} & 0 \\ 0 & 0 & 0 & h_{3} \end{pmatrix} \text{ and } \Lambda_{L} = \begin{pmatrix} l_{0} & 0 & 0 & 0 \\ 0 & l_{1} & 0 & 0 \\ 0 & 0 & l_{2} & 0 \\ 0 & 0 & 0 & l_{3} \end{pmatrix}.$$

where  $h_i, l_i \in \mathbb{R}^+, 0 \le i \le 3$ 

- Let  $\vec{g} = \mathcal{S}(g)$ , where g is a 2 × 2 image and  $\mathcal{S}$  is the stacking operator.
  - i. Show that H is block-circulant
- ii. Show that  $W^{-1}\mathcal{S}(h) = 2\mathcal{S}(\hat{h})$  for any  $2 \times 2$  image h.
- (b) Show that the optimal solution  $\vec{f} = S(f)$  that solves the constrained least square problem satisfies  $[\lambda H^T H + L^T L]\vec{f} = \lambda H^T \vec{g}$  for some parameter  $\lambda$ . Hence, find DFT(f) in term of DFT(g),  $h_i, l_i, 0 \leq i \leq 3$  and  $\lambda$ . You may assume  $\lambda > 0$ . Please show your answer with details.

## Solution:

- (a) Here we prove the general case for any  $N \in \mathbb{N}^+$ .
  - i. Consider  $W, W^{-1}, H$  and  $\Lambda_H$  as  $N \times N$  block matrices and every block of them is a  $N \times N$  matrix. We have

$$W = W_N \otimes W_N = \frac{1}{\sqrt{N}} \left( e^{\frac{2\pi j}{N}kl} W_N \right)_{0 \le k, l \le N-1},$$
  

$$W^{-1} = W_N^{-1} \otimes W_N^{-1} = \frac{1}{\sqrt{N}} \left( e^{-\frac{2\pi j}{N}kl} W_N^{-1} \right)_{0 \le k, l \le N-1},$$
  

$$H = (H_{k,l})_{0 \le k, l \le N-1},$$
  

$$\Lambda_H = \begin{pmatrix} \Lambda_0 & 0 & \cdots & 0 \\ 0 & \Lambda_1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \Lambda_{N-1} \end{pmatrix},$$

where

$$\Lambda_i = \begin{pmatrix} h_{iN} & 0 & \cdots & 0\\ 0 & h_{iN+1} & \cdots & 0\\ \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & \cdots & h_{(i+1)N-1} \end{pmatrix}$$

for any  $i = 0, 1, \dots, N - 1$ . Then compute

$$\begin{split} H &= W \Lambda_H W^{-1} \\ &= \frac{1}{N} \left( e^{\frac{2\pi j}{N} k l} W_N \right)_{0 \le k, l \le N-1} \Lambda_H \left( e^{-\frac{2\pi j}{N} l k} W_N \right)_{0 \le k, l \le N-1} \\ &= \frac{1}{N} \left( e^{\frac{2\pi j}{N} k l} W_N \Lambda_l \right)_{0 \le k, l \le N-1} \left( e^{-\frac{2\pi j}{N} l k} W_N \right)_{0 \le k, l \le N-1} \\ &= \frac{1}{N} \left( \sum_{m=0}^{N-1} e^{\frac{2\pi j}{N} k m} e^{-\frac{2\pi j}{N} m l} W_N \Lambda_m W_N^{-1} \right)_{0 \le k, l \le N-1} \\ &= \frac{1}{N} \left( W_N \left( \sum_{m=0}^{N-1} e^{\frac{2\pi j}{N} m (k-l)} \Lambda_m \right) W_N^{-1} \right)_{0 \le k, l \le N-1} . \end{split}$$

So  $H_{k,l} = \frac{1}{N} W_N \left( \sum_{m=0}^{N-1} e^{\frac{2\pi i}{N} m(k-l)} \Lambda_m \right) W_N^{-1}$  and  $H_{k+1,l+1} = H_{k,l}$ , which means H is block-circulant.

ii. We know that  $\hat{h} = UhU$ , where  $U = (u_{kl})_{0 \le k, l \le N-1}$  and  $u_{kl} = \frac{1}{N}e^{-\frac{2\pi j}{N}kl}$ . It's easy to find  $u_{kl} = \frac{1}{\sqrt{N}}W_N^{-1}(k,l)$ , so  $W_N^{-1} = \sqrt{N}U$ . By the property of sperable image transformation, we have

$$W^{-1}\mathcal{S}(h) = W_N^{-1} \otimes W_N^{-1}\mathcal{S}(h)$$
  
=  $\mathcal{S}(W_N^{-1}h(W_N^{-1})^T)$   
=  $\mathcal{S}(W_N^{-1}hW_N^{-1})$   
=  $\mathcal{S}(NUhU)$   
=  $N\mathcal{S}(\hat{h})$ 

(b) We know the minimizer must satisfy

$$\mathcal{D} = \frac{\partial}{\partial \vec{f}} [\vec{f}^T L^T L \vec{f} + \lambda (\vec{g} - H \vec{f})^T (\vec{g} - H \vec{f})] = 0$$

where  $\lambda$  is the Lagrange multiplier. Easy to check

$$\begin{aligned} \mathcal{D} &= 0 \\ \Rightarrow (2L^T L)\vec{f} + \lambda (-H^T \vec{g} - H^T \vec{g} + 2H^T H \vec{f}) = 0 \\ \Rightarrow (\lambda H^T H + L^T L)\vec{f} &= \lambda H^T \vec{g}. \end{aligned}$$

Since L is also block-circulant, it is also diagonalizable by W. Then

$$\begin{split} \lambda H^T H + L^T L &= \lambda H^* H + L^* L \\ &= \lambda (W \Lambda_H W^{-1})^* (W \Lambda_H W^{-1}) + (W \Lambda_L W^{-1})^* (W \Lambda_L W^{-1}) \\ &= \lambda W \Lambda_H^* \Lambda_H W^{-1} + W \Lambda_L^* \Lambda_L W^{-1} \end{split}$$

and  $\lambda H^T = \lambda H^* = \lambda (W \Lambda_H W^{-1})^* = \lambda W \Lambda_H^* W^{-1}$ . Hence

$$\begin{aligned} (\lambda W \Lambda_H^* \Lambda_H W^{-1} + W \Lambda_L^* \Lambda_L W^{-1}) \mathcal{S}(f) &= \lambda W \Lambda_H^* W^{-1} \mathcal{S}(g), \\ (\lambda \Lambda_H^* \Lambda_H + \Lambda_L^* \Lambda_L) \mathcal{S}(DFT(f)) &= \lambda \Lambda_H^* \mathcal{S}(DFT(g)) \end{aligned}$$

and thus

$$DFT(f)(u,v) = \frac{\lambda h_{u+2v}}{\lambda h_{u+2v}^2 + l_{u+2v}^2} DFT(g)(u,v).$$