

Ch 7 The Riemann Integral

§7.1 Riemann Integral

Def: If $I = [a, b]$ is a closed interval, then a partition of I is a finite, ordered set

$$\mathcal{P} = (x_0, x_1, \dots, x_n)$$

of points in I such that

$$a = x_0 < x_1 < \dots < x_n = b$$

Note: A partition $\mathcal{P} = (x_0, x_1, \dots, x_n)$ is used to divide I into (interior) non-overlapping subintervals:

$$I_1 = [x_0, x_1], I_2 = [x_1, x_2], \dots, I_n = [x_{n-1}, x_n]$$

Hence an alternate notation for \mathcal{P} is

$$\mathcal{P} = \{[x_{i-1}, x_i]\}_{i=1}^n$$

Def: The norm (or mesh) of $\mathcal{P} = \{[x_{i-1}, x_i]\}_{i=1}^n$ is defined

$$\text{by } \|\mathcal{P}\| = \max_{i=1, \dots, n} \{x_i - x_{i-1}\}$$

$$= \max \{x_1 - x_0, x_2 - x_1, \dots, x_n - x_{n-1}\}$$

(= length of largest subinterval)

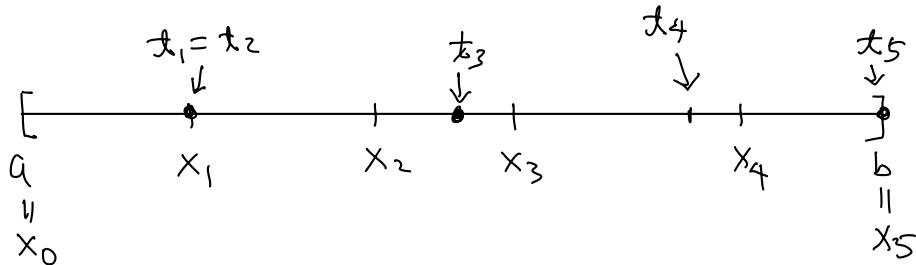
Def: (1) If $t_i \in I_i = [x_{i-1}, x_i]$, $\forall i=1, \dots, n$ has been selected

of each subinterval of a partition $\mathcal{P} = \{[x_{i-1}, x_i]\}_{i=1}^n$

of $I = [a, b]$, then t_i are called tags of I_i .

(2) The partition $\mathcal{P} = \{[x_{i-1}, x_i]\}_{i=1}^n$, together with tags t_i is called a tagged partition of $I = [a, b]$ and is denoted by

$$\overset{\bullet}{\mathcal{P}} = \{[x_{i-1}, x_i], t_i\}_{i=1}^n$$



Def: If $\overset{\bullet}{\mathcal{P}} = \{[x_{i-1}, x_i], t_i\}_{i=1}^n$ is a tagged partition

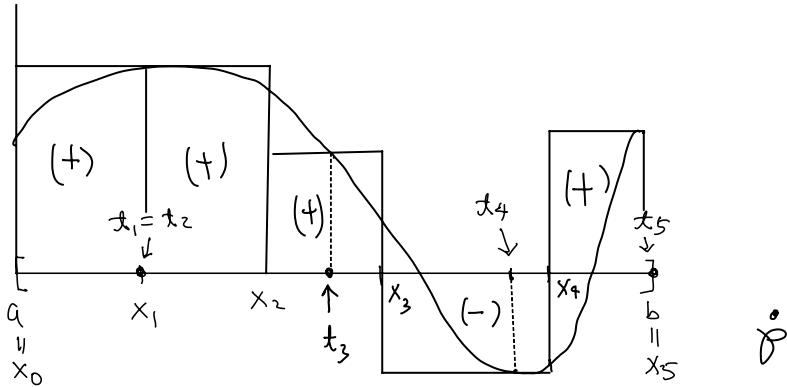
of $I = [a, b]$, then the Riemann sum of a

function $f: [a, b] \rightarrow \mathbb{R}$ is defined by

(may not "continuous")

$$S(f; \overset{\bullet}{\mathcal{P}}) = \sum_{i=1}^n f(t_i)(x_i - x_{i-1})$$

Remark: This definition works for the case that $\overset{\bullet}{\mathcal{P}}$ is a subset of a partition, and not the entire partition.



$S(f; \Delta^*)$ = sum of (signed) areas of the n rectangles with bases $[x_{i-1}, x_i]$ & heights $f(t_i)$, $i=1,\dots,n$.

Def 7.1.1(1) A function $f: [a, b] \rightarrow \mathbb{R}$ is said to be

Riemann integrable on $[a, b]$ if

$\exists L \in \mathbb{R}$ such that

$\forall \varepsilon > 0$, $\exists \delta_\varepsilon > 0$ such that

\forall tagged partition Δ^* of $[a, b]$ with $\|\Delta^*\| < \delta_\varepsilon$,

$$|S(f; \Delta^*) - L| < \varepsilon.$$

(2) The set of all Riemann integrable functions on $[a, b]$ will be denoted by $\mathcal{R}[a, b]$.

(3) If $f \in \mathcal{R}[a, b]$, the number L is uniquely determined (Thm 7.1.2), called the Riemann integral of f over $[a, b]$, & is

denoted by $\int_a^b f$ or $\int_a^b f(x) dx$

(x is a dummy variable, can be replaced by any other notation)

Remark: One often says that L is "the limit" of $S(f; \vec{\delta})$ as $\|\vec{\delta}\| \rightarrow 0$. However $S(f; \vec{\delta})$ is not a function of $\|\vec{\delta}\|$, it is not the limit (of functions) that defined before.
 (there are many $\vec{\delta}$ with same $\|\vec{\delta}\|$)

Thm 7.1.2 If $f \in \mathcal{R}[a, b]$, then the value of the integral is uniquely determined.

Pf: Suppose L' and L'' both satisfy the definition 7.1.1.

Then $\forall \varepsilon > 0$, $\exists \delta_{\frac{\varepsilon}{2}}' > 0$ such that

$$|S(f; \vec{\delta}_1) - L'| < \frac{\varepsilon}{2} \quad \forall \vec{\delta}_1 \text{ with } \|\vec{\delta}_1\| < \delta_{\frac{\varepsilon}{2}}'$$

and $\exists \delta_{\frac{\varepsilon}{2}}'' > 0$ such that

$$|S(f; \vec{\delta}_2) - L''| < \frac{\varepsilon}{2} \quad \forall \vec{\delta}_2 \text{ with } \|\vec{\delta}_2\| < \delta_{\frac{\varepsilon}{2}}''.$$

$$\text{let } \delta_\varepsilon = \min \left\{ \delta_{\frac{\varepsilon}{2}}', \delta_{\frac{\varepsilon}{2}}'' \right\} > 0.$$

If $\vec{\delta}$ is a tagged partition with $\|\vec{\delta}\| < \delta_\varepsilon$,

then $\|\vec{\delta}\| < \delta_{\frac{\varepsilon}{2}}'$ and $\|\vec{\delta}\| < \delta_{\frac{\varepsilon}{2}}''$.

$$\text{Hence } |S(f; \vec{\delta}) - L'| < \frac{\varepsilon}{2} \text{ and } |S(f; \vec{\delta}) - L''| < \frac{\varepsilon}{2}.$$

$$\Rightarrow |L' - L''| \leq |S(f; \vec{P}) - L'| + |S(f; \vec{P}) - L''| \\ < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon.$$

Since $\varepsilon > 0$ is arbitrary, we have $L' = L''$. $\#$

Thm F.1.3 If $\begin{cases} \bullet g \in R[a,b] & (\text{Riemann integrable}) \\ \bullet f(x) = g(x) \text{ except for a finite number of points.} \end{cases}$

Then $\bullet f \in R[a,b]$ and

$$\bullet S_a^b f = S_a^b g.$$

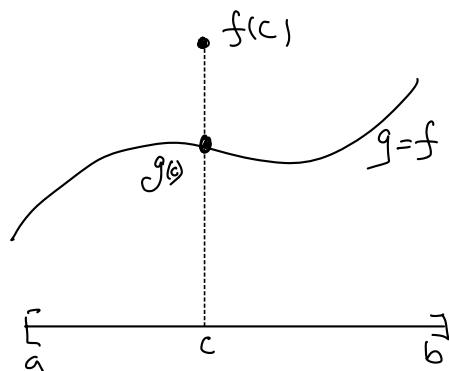
Pf: Only need to prove the case that

$f(x) = g(x)$ except for one point in $[a,b]$.

Then induction implies the theorem.

Let c be the point in $[a,b]$

s.t. $f(c) \neq g(c)$.



Then $f(x) = g(x), \forall x \in [a,b] \setminus \{c\}$.

Let $L = S_a^b g$. (By assumption that $g \in R[a,b]$, it exists)

For any tagged partition $\dot{\mathcal{P}} = \{(x_{i-1}, x_i], t_i\}_{i=1}^n$,

then (i) $c \in (x_{i_0-1}, x_{i_0})$ for some $i_0 \in \{1, 2, \dots, n\}$

or (ii) $c = x_{i_0}$ for some $i_0 \in \{1, 2, \dots, n\}$.

For case (i), $f(x) = g(x)$ for all $[x_{i-1}, x_i]$, $i \neq i_0$

$$\Rightarrow f(t_{i_0}) = g(t_{i_0})$$

And hence

$$\begin{aligned} S(f; \dot{\mathcal{P}}) - S(g; \dot{\mathcal{P}}) &= \sum_{i \neq i_0} f(t_i)(x_i - x_{i-1}) - \sum_{i \neq i_0} g(t_i)(x_i - x_{i-1}) \\ &\quad + f(t_{i_0})(x_{i_0} - x_{i_0-1}) - g(t_{i_0})(x_{i_0} - x_{i_0-1}) \\ &= (f(t_{i_0}) - g(t_{i_0}))(x_{i_0} - x_{i_0-1}) \end{aligned}$$

$$\begin{aligned} \Rightarrow |S(f; \dot{\mathcal{P}}) - S(g; \dot{\mathcal{P}})| &\leq |f(t_{i_0}) - g(t_{i_0})| |x_{i_0} - x_{i_0-1}| \\ &\leq (|f(c)| + |g(c)|) \|\dot{\mathcal{P}}\|. \end{aligned}$$

Similarly for case (ii)

$$\begin{aligned} S(f; \dot{\mathcal{P}}) - S(g; \dot{\mathcal{P}}) &= \sum_{\substack{i \neq i_0 \\ i_0+1}} [f(t_i) - g(t_i)](x_i - x_{i-1}) \\ &\quad + f(t_{i_0})(x_{i_0} - x_{i_0-1}) - g(t_{i_0})(x_{i_0} - x_{i_0-1}) \\ &\quad + f(t_{i_0+1})(x_{i_0+1} - x_{i_0}) - g(t_{i_0+1})(x_{i_0+1} - x_{i_0}) \\ &= (f(t_{i_0}) - g(t_{i_0}))(x_{i_0} - x_{i_0-1}) + (f(t_{i_0+1}) - g(t_{i_0+1}))(x_{i_0+1} - x_{i_0}) \end{aligned}$$

$$\begin{aligned} \therefore |S(f; \vec{\delta}) - S(g; \vec{\delta})| &\leq (|f(c)| + |g(c)|) \|\vec{\delta}\| + (|f(c)| + |g(c)|) \|\vec{\delta}\| \\ &= 2(|f(c)| + |g(c)|) \|\vec{\delta}\|. \end{aligned}$$

Hence, in both cases,

$$|S(f; \vec{\delta}) - S(g; \vec{\delta})| \leq 2(|f(c)| + |g(c)|) \|\vec{\delta}\|$$

Therefore, $\forall \varepsilon > 0$, for $\delta_1 = \frac{\varepsilon}{5(|f(c)| + |g(c)|)}$, we have

$\forall \vec{\delta}$ with $\|\vec{\delta}\| < \delta_1$,

$$|S(f; \vec{\delta}) - S(g; \vec{\delta})| \leq 2(|f(c)| + |g(c)|) \cdot \frac{\varepsilon}{5(|f(c)| + |g(c)|)} < \frac{\varepsilon}{2}.$$

Now, by $g \in \mathcal{R}[a, b]$ & $L = \int_a^b g$, $\exists \delta_2 > 0$ s.t.,

$\forall \vec{\delta}$ with $\|\vec{\delta}\| < \delta_2$,

$$|S(g; \vec{\delta}) - L| < \frac{\varepsilon}{2}.$$

Letting $\delta = \min\{\delta_1, \delta_2\} > 0$, we have

$\forall \vec{\delta}$ with $\|\vec{\delta}\| < \delta$,

$$\begin{aligned} |S(f; \vec{\delta}) - L| &\leq |S(f; \vec{\delta}) - S(g; \vec{\delta})| + |S(g; \vec{\delta}) - L| \\ &< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \end{aligned}$$

$\therefore f \in \mathcal{R}[a, b]$ and $S_a^b f = L = S_a^b g$. \times

Eg 7.1.4

(a) If $f \equiv \text{const.}$, then $f \in R[a, b]$

Pf: Let the const. be k .

$$\text{Then } f(x) = k \quad \forall x \in [a, b]$$

If $\dot{\mathcal{P}} = \{[x_{i-1}, x_i], t_i\}_{i=1}^n$ be a tagged partition of $[a, b]$,

then corresponding Riemann sum

$$\begin{aligned} S(f; \dot{\mathcal{P}}) &= \sum_{i=1}^n f(t_i)(x_i - x_{i-1}) \\ &= \sum_{i=1}^n k(x_i - x_{i-1}) = k(b-a) \end{aligned}$$

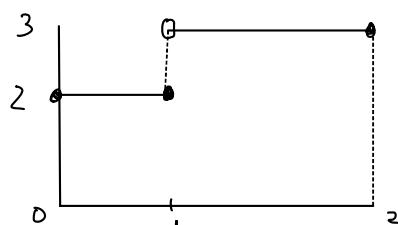
$\therefore \forall \varepsilon > 0$, we can just pick any $\delta > 0$ and have

$$|S(f; \dot{\mathcal{P}}) - k(b-a)| = 0 < \varepsilon, \quad \forall \dot{\mathcal{P}} \text{ with } \|\dot{\mathcal{P}}\| < \delta$$

$\therefore f \equiv k \in R[a, b]$.

In fact, we have proved that $\int_a^b k = k(b-a)$. ~~✓~~

(b) $g: [0, 3] \rightarrow \mathbb{R}$ defined by $g(x) = \begin{cases} 3, & 1 < x \leq 3 \\ 2, & 0 \leq x \leq 1 \end{cases}$



is (Riemann) integrable $\Leftrightarrow \int_0^3 g = 8$

Pf: Let $\dot{\mathcal{P}} = \{ [x_{i-1}, x_i], t_i \}_{i=1}^n$

Let $k=1, \dots, n$ such that

$0 \leq t_1 \leq \dots \leq t_k \leq 1$ and

$1 < t_{k+1} \leq \dots \leq t_n \leq 3$

let $\dot{\mathcal{P}}_1 = \{ [x_{i-1}, x_i], t_i \}_{i=1}^k$

and $\dot{\mathcal{P}}_2 = \{ [x_{i-1}, x_i], t_i \}_{i=k+1}^n$

(Using the remark of the definition of Riemann Sum)

We have

$$\begin{aligned} S(g; \dot{\mathcal{P}}) &= \sum_{i=1}^k g(t_i)(x_i - x_{i-1}) + \sum_{i=k+1}^n g(t_i)(x_i - x_{i-1}) \\ &= S(g; \dot{\mathcal{P}}_1) + S(g; \dot{\mathcal{P}}_2) \end{aligned}$$

Suppose that $\|\dot{\mathcal{P}}\| < \delta$ for some $\delta > 0$.

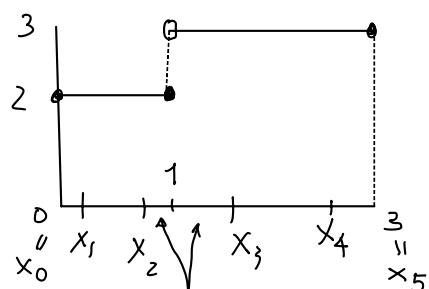
Then $t_k \leq 1$, $x_{k-1} \leq t_k \leq x_k$ and $x_k - x_{k-1} < \delta$,

we have $x_k < \delta + x_{k-1} \leq \delta + t_k \leq 1 + \delta$

(notation in Textbook) $\rightarrow U_1 = \bigcup_{i=1}^k [x_{i-1}, x_i] = [0, x_k] \subset [0, 1 + \delta]$.

On the other hand, we claim that $1 - \delta \leq x_k$.

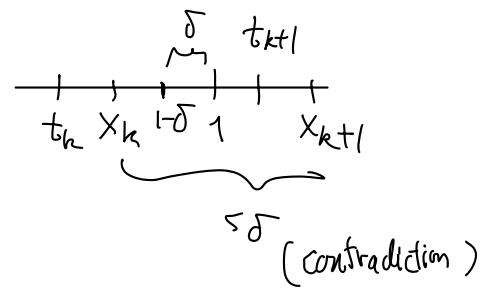
Suppose not, then $1 - \delta > x_k$.



2 possible situations
of tag $t_k \geq 1$

From the choice of k , $t_{k+1} > 1$.

$$\therefore x_{k+1} \geq t_{k+1} > 1$$



$$\text{Hence } \delta > x_{k+1} - x_k > 1 - (1 - \delta) = \delta,$$

which is a contradiction.

$$\therefore 1 - \delta \leq x_k.$$

Together we have

$$[0, 1 - \delta] \subset U_1 = \bigcup_{i=1}^k [x_{i-1}, x_i] = [0, x_k] \subset [0, 1 + \delta]$$

Therefore

$$S(g; \dot{\mathcal{P}}_1) = \sum_{i=1}^k g(t_i)(x_i - x_{i-1}) = 2x_k \quad (t_i \leq 1 \Rightarrow g(t_i) = 2)$$

$$\Rightarrow 2(1 - \delta) \leq S(g; \dot{\mathcal{P}}_1) \leq 2(1 + \delta) \quad (\text{--- } (\star)_1).$$

Similarly,

$$S(g; \dot{\mathcal{P}}_2) = \sum_{i=k+1}^n g(t_i)(x_i - x_{i-1}) = 3(3 - x_k) \quad (t_i > 1 \Rightarrow g(t_i) = 3)$$

$$\Rightarrow 3(3 - (1 + \delta)) \leq S(g; \dot{\mathcal{P}}_2) \leq 3(3 - (1 - \delta))$$

$$3(2 - \delta) \leq S(g; \dot{\mathcal{P}}_2) \leq 3(2 + \delta) \quad (\text{--- } (\star)_2)$$

By $(\star)_1 + (\star)_2$, we have, for $\dot{\mathcal{P}}$ satisfying $\|\dot{\mathcal{P}}\| < \delta$,

$$z(1-\delta) + 3(z-\delta) \leq S(g; \vec{\theta}) \leq z(1+\delta) + 3(z+\delta)$$

i.e. $8 - 5\delta \leq S(g; \vec{\theta}) \leq 8 + 5\delta$

$$\therefore |S(g; \vec{\theta}) - 8| \leq 5\delta.$$

Therefore $\forall \varepsilon > 0$, we can take $\delta_\varepsilon = \frac{\varepsilon}{10} > 0$ to have

$\forall \vec{\theta}$ with $\|\vec{\theta}\| < \delta_\varepsilon$,

$$|S(g; \vec{\theta}) - 8| \leq 5 \cdot \frac{\varepsilon}{10} < \varepsilon. \quad \times$$