

Sec. 2.3: Q17

17. Let  $V$  be a vector space. Determine all linear transformations  $T: V \rightarrow V$  such that  $T = T^2$ . *Hint:* Note that  $x = T(x) + (x - T(x))$  for every  $x$  in  $V$ , and show that  $V = \{y: T(y) = y\} \oplus N(T)$  (see the exercises of Section 1.3).

**Definition.** Let  $V$  be a vector space and  $W_1$  and  $W_2$  be subspaces of  $V$  such that  $V = W_1 \oplus W_2$ . (Recall the definition of direct sum given in the exercises of Section 1.3.) A function  $T: V \rightarrow V$  is called the **projection on  $W_1$  along  $W_2$**  if, for  $x = x_1 + x_2$  with  $x_1 \in W_1$  and  $x_2 \in W_2$ , we have  $T(x) = x_1$ .

*Proof.* Claim:  $T = T^2 \iff T$  is a projection

( $\Rightarrow$ ) suppose  $T = T^2$ . Let  $W_T = \{y \in V : T(y) = y\}$

We will show that  $V = W_T \oplus N(T)$

①  $\forall x \in W_T \cap N(T)$ .

$$\begin{cases} x \in W_T, & \text{so } x = T(x) \\ x \in N_T, & \text{so } T(x) = 0 \end{cases} \Rightarrow x = 0$$

so  $W_T \cap N(T) = \{0\}$

②  $\forall x \in W_T$ ,  $x = T(x) \in R(T)$ , so  $W_T \subset R(T)$

$\forall x \in V$ ,  $T(T(x)) = T^2(x) = T(x)$  so  $T(x) \in W_T$  i.e.  $R(T) \subset W_T$

Therefore  $W_T = R(T)$

Besides,  $T(x - T(x)) = T(x) - T^2(x) = 0 \quad \forall x \in V$

so  $x - T(x) \in N(T) \quad \forall x \in V$ .

Since  $x = \underbrace{T(x)}_{\in W_T} + \underbrace{(x - T(x))}_{\in N(T)} \quad \forall x \in V$

then  $V = W_T + N(T)$

By ① and ②,  $V = W_T \oplus N(T) = R(T) \oplus N(T)$

$T$  is projection on  $W_T$  along  $N(T)$

( $\Leftarrow$ ) suppose  $T$  is a projection on  $W_1$  along  $W_2$ .  
then  $V = W_1 \oplus W_2$

For any  $v \in V$ ,  $\exists!$   $w_1 \in W_1$ ,  $w_2 \in W_2$   
s.t.  $v = w_1 + w_2$ , and  $T(v) = w_1$

Since  $w_1 = \underset{\substack{\uparrow \\ W_1}}{w_1} + \underset{\substack{\uparrow \\ W_2}}{0}$ , we have  $T(w_1) = w_1$

So  $T^2(v) = T(T(v)) = T(w_1) = w_1 = T(v)$

i.e.  $T^2 = T$

5. Sec. 2.4: Q16

16. Let  $B$  be an  $n \times n$  invertible matrix. Define  $\Phi: M_{n \times n}(F) \rightarrow M_{n \times n}(F)$  by  $\Phi(A) = B^{-1}AB$ . Prove that  $\Phi$  is an isomorphism.

Proof:

- $\Phi$  is linear.

$$\forall A_1, A_2 \in M_{n \times n}(F), \quad \forall \alpha \in F$$

$$\begin{aligned} \Phi(\alpha \cdot A_1 + A_2) &= B^{-1}(\alpha A_1 + A_2)B \\ &= B^{-1} \cdot (\alpha A_1 B + A_2 B) \\ &= \alpha \cdot B^{-1}A_1 B + B^{-1}A_2 B \\ &= \alpha \cdot \Phi(A_1) + \Phi(A_2) \end{aligned}$$

- $\Phi$  is injective

$$\forall A \in N(\Phi), \quad \Phi(A) = O_{n \times n} \text{ i.e. } B^{-1}AB = O_{n \times n}$$

Since  $B$  is invertible,  $B \cdot B^{-1} = B^{-1}B = I$

$$A = B \cdot (B^{-1}AB) \cdot B^{-1} = B \cdot O_{n \times n} \cdot B^{-1} = O_{n \times n}$$

$$\text{Thus } N(\Phi) = \{ O_{n \times n} \}$$

- $\Phi$  is surjective

$$\forall A \in M_{n \times n}(F), \quad \exists BAB^{-1} \in M_{n \times n}(F)$$

$$\text{s.t. } \Phi(BAB^{-1}) = B^{-1} \cdot (BAB^{-1}) \cdot B = A$$

$$\text{Thus } R(\Phi) = M_{n \times n}(F).$$

OR use  $\dim(M_{n \times n}(F)) = \dim(N(\Phi)) + \dim(R(\Phi))$

In all,  $\Phi$  is an isomorphism.

2. Consider a linear transformation  $T : V \rightarrow W$ . Prove or disprove the following.

- (a) If  $T$  has a right inverse, must it have a left inverse?
- (b) If  $T$  has a left inverse, must it have a right inverse?
- (c) If  $T$  has both a left and a right inverse, must it be invertible? (That is, must the left and right inverse be the same?)
- (d) If  $T$  has a unique right inverse  $S$ , is  $T$  necessarily invertible? (Hint. Consider  $ST + S - I$ .)

(a) No.

$$T: F^\infty \rightarrow F^\infty$$

$$(a_1, a_2, \dots) \mapsto (a_2, a_3, \dots)$$

$$U: F^\infty \rightarrow F^\infty$$

$$(a_1, a_2, \dots) \mapsto (0, a_1, a_2, \dots)$$

Then  $T \circ U = I$ ,  $T$  has a right inverse.  
 Suppose  $T$  has left inverse  $F$  then  $F \circ T = I$ .

$$\begin{cases} F \circ (T \circ U)(a_1, a_2, \dots) = F \circ I(a_1, a_2, \dots) \\ \qquad \qquad \qquad = F(a_1, a_2, \dots) \\ (F \circ T) \circ U(a_1, a_2, \dots) = I \circ U(a_1, a_2, \dots) \\ \qquad \qquad \qquad = U(a_1, a_2, \dots) \end{cases}$$

Thus  $U = F$   
 but  $U \circ T(a_1, 0, 0, \dots) = U(0, 0, \dots) = (0, 0, \dots)$   
 i.e.  $U \circ T = I$   
 contradiction. so  $T$  has no left inverse.

(b) No.

Consider  $T: F^\infty \rightarrow F^\infty$

$$(a_1, a_2, \dots) \mapsto (0, a_1, a_2, \dots)$$

$$U: F^\infty \rightarrow F^\infty$$

$$(a_1, a_2, \dots) \mapsto (a_2, a_3, \dots)$$

Then  $U \circ T = I$  i.e.  $T$  has left inverse  $U$ .  
 By similar argument in (a), we know that  
 $T$  does not have a right inverse.

(c) if  $T$  has a left inverse  $U$  and a right inverse  $S$

$$\text{Then } U = U \circ I = U \circ (T \circ S) = (U \circ T) \circ S = I \circ S = S$$

(d)  $T$  has a unique  $S$ . Then  $T \circ S = I$ .

$$\begin{aligned} T \circ (S \circ T + S - I) &= T \circ S \circ T + T \circ S - T \\ &= I \circ T + T \circ S - T \\ &= I \end{aligned}$$

Hence  $S = S \circ T + S - I$

Then  $S \circ T = I$ ,  $S$  is also the left inverse of  $T$   
 $T$  is invertible.

2. Let  $g_0(x) = x + 1$ . Let  $T : P_2(\mathbb{R}) \rightarrow P_3(\mathbb{R})$  and  $U : P_3(\mathbb{R}) \rightarrow \mathbb{R}^3$  be defined by

$$T(f(x)) = f'(x)g_0(x) + \int_0^x f(t)dt \text{ and } U(h(x)) = (h(0), h(1), h'(1))^T$$

Let  $\alpha, \beta, \gamma$  be the standard ordered bases for  $P_2(\mathbb{R}), P_3(\mathbb{R}), \mathbb{R}^3$  respectively.

(a) Compute  $[T]_{\alpha}^{\beta}$ ,  $[U]_{\beta}^{\gamma}$ ,  $[U]_{\beta}^{\gamma}[T]_{\alpha}^{\beta}$  and  $[UT]_{\alpha}^{\gamma}$ .

(b) Let  $h_0(x) = 1 - 2x - x^2 + x^3$ , compute  $[h_0(x)]_{\beta}$ ,  $[U]_{\beta}^{\gamma}[h_0(x)]_{\beta}$  and  $[U(h_0(x))]_{\gamma}$ .

Solution.

$$\alpha = \{1, x, x^2\} \quad \beta = \{1, x, x^2, x^3\} \quad \gamma = \{e_1, e_2, e_3\}$$

$$(a) \quad T(1) = x, \quad T(x) = 1 + x + \frac{1}{2}x^2, \quad T(x^2) = 2x + 2x^2 + \frac{1}{3}x^3$$

$$U(1) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad U(x) = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \quad U(x^2) = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}, \quad U(x^3) = \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}$$

$$[T]_{\alpha}^{\beta} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 2 \\ 0 & \frac{1}{2} & \frac{2}{3} \\ 0 & 0 & \frac{1}{3} \end{pmatrix} \quad [U]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix}$$

$$[U]_{\beta}^{\gamma} \cdot [T]_{\alpha}^{\beta} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 2 \\ 0 & \frac{1}{2} & \frac{2}{3} \\ 0 & 0 & \frac{1}{3} \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & \frac{5}{2} & \frac{13}{3} \\ 1 & 2 & 7 \end{pmatrix}$$

$$[UT]_{\alpha}^{\gamma} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & \frac{5}{2} & \frac{13}{3} \\ 1 & 2 & 7 \end{pmatrix} ?$$

$$(b) \quad [h_0(x)]_{\beta} = \begin{pmatrix} 1 \\ -2 \\ -1 \\ 1 \end{pmatrix}$$

$$[U]_{\beta}^{\gamma} [h_0(x)]_{\beta} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$$

$$U(h_0) = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$$

$$[U(h_0)]_{\gamma} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$$