

## Lecture 5:

### Zorn's Lemma

Let  $S$  be a partially ordered set. If every chain of  $S$  has an upper bound in  $S$ , then  $S$  contains a maximal elements.

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Definition 1: (Partially ordered) A partially ordered on a (non-empty) set  $S$  is a binary relation on  $S$ , denoted  $\leq$ , which satisfies:

- for  $\forall s \in S$ ,  $s \leq s$
  - if  $s \leq s'$  and  $s' \leq s$ , then  $s = s'$
  - if  $s \leq s'$  and  $s' \leq s''$ , then  $s \leq s''$ .
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Definition 2: If every elements in a partially ordered set  $S$  is comparable under  $\leq$ , then  $S$  is called a totally ordered set.

Definition 3: A chain is a collection of elements in  $S$  satisfying:  
if  $s_1 \in S$  and  $s_2 \in S$ , then either  $s_1 \leq s_2$  or  $s_2 \leq s_1$ .

For simplicity, we may consider countable chain  $s_1 \leq s_2 \leq \dots$  in our discussion  
(not necessarily countable) for the ease of explanation

Definition 4: A maximal element  $m$  of a partially ordered set  $S$  is defined  
as follows: for  $\forall s \in S$  to which  $m$  is comparable,  $s \leq m$ .

Definition 5 An upper bound  $\tilde{C}$  of a chain  $\{C_i\}_{i \in I}$  is that for all  $i \in I$ ,  
 $C_i \leq \tilde{C}$ .

## Zorn's lemma (adapted to 2048)

Let  $V$  be a vector space. Let  $S$  be the collection of linearly independent subsets of  $V$ . Then  $S$  is partially ordered under  $\subseteq$ .

Assume every chain  $\{L_\alpha\}_{\alpha \in I}$  of  $S$  has an upper bound.

(Obviously,  $\bigcup_{\alpha} L_{\alpha}$  is an upper bound of the chain. We need to show that

$\bigcup_{\alpha} L_{\alpha}$  is linearly independent)

Then:  $S$  has a maximal element.

Theorem: Every vector space has a basis.

Proof: Let  $\mathcal{L}$  be the collection of all linearly independent subsets of  $V$ .

For any chain  $\{S_i\}_{i \in I}$  (we may consider a countable chain  $S_1 \subset S_2 \subset \dots$  for easier interpretation.)

$\bigcup_{i \in I} S_i$  is also linearly independent.  $\therefore \bigcup_i S_i \in \mathcal{L}$ .

By Zorn's lemma,  $\exists$  maximal linearly independent set  $M$ .

We claim that  $\text{span}(M) = V$ .

If not,  $\exists \vec{v} \in V \ni \vec{v} \notin \text{span}(M)$ .

Then:  $M \cup \{\vec{v}\}$  is linearly independent.

But  $M \subset M \cup \{\vec{v}\}$ . Contradiction to Zorn's lemma.

$\therefore$  ①  $\text{span}(M) = V$

②  $M$  is L.I.

$\Rightarrow M$  is a basis.



Theorem: Every spanning set of a non-zero vector space  $V$  contains a basis of  $V$ .

Proof: Let  $S$  be a spanning set of  $V$ .

Let  $\mathcal{E}$  be the collection of linearly independent subsets of  $S$ .

Then  $\mathcal{E} \neq \emptyset$  (as  $\{\vec{v}\} \in \mathcal{E}$  for any  $\vec{v} \neq \vec{0} \in S$ )

Then,  $\mathcal{E}$  under  $\subseteq$  is partially ordered.

Let  $\{L_i\}_{i \in I}$  be a chain in  $\mathcal{E}$ .

Then  $\bigcup_i L_i \in \mathcal{E}$  and  $\bigcup_i L_i$  is an upper bound.

By Zorn's lemma, there is a maximal element  $\mathcal{B}$  in  $\mathcal{E}$ .

(i.e. a linearly independent subset of  $S$  which is maximal)

We'll show that  $\text{Span}(\mathcal{B}) = \text{Span}(\mathcal{S}) = V$

It suffices to show that for any  $\vec{v} \in \mathcal{S}$ ,  $\vec{v} \in \text{Span}(\mathcal{B})$ .

If not, suppose  $\vec{v} \notin \text{Span}(\mathcal{B})$ .

Then:  $\mathcal{B} \cup \{\vec{v}\}$  is linearly independent subset of  $\mathcal{S}$ .

Hence,  $\mathcal{B} \cup \{\vec{v}\} \in \mathcal{L}$ . But  $\mathcal{B} \cup \{\vec{v}\} \supsetneq \mathcal{B}$ .

Contradicting to the fact that  $\mathcal{B}$  is maximal.

$\therefore \vec{v} \in \text{Span}(\mathcal{B})$ .

$\therefore \text{Span}(\mathcal{B}) = \text{Span}(\mathcal{S}) = V$ .

$\therefore \mathcal{B}$  is a basis.

Remark: To find a basis inside a spanning set  $\mathcal{S}$ , it's natural to find a minimal spanning set of  $V$  inside  $\mathcal{S}$ .

If  $M \subset \mathcal{S}$  is minimal, then  $M$  is linearly independent.

If not, we can find  $v \in M \ni \text{Span}(M \setminus \{v\}) = \text{Span}(M)$ , contradicting the minimality of  $M$ .

One might consider Zorn's lemma as follows:

Let  $\mathcal{C}$  be the set of all spanning subsets of  $\mathcal{S}$ , partially order  $\mathcal{C}$  by reverse inclusion. That is:  $S_1 \in \mathcal{C}$  and  $S_2 \in \mathcal{C}$ ,  $S_1 \leq S_2$  iff  $S_1 \supseteq S_2$ .

For any chain  $\{S_i\}_{i \in I}$  in  $\mathcal{C}$ ,  $\bigcap_{i \in I} S_i$  is the upper bound.

If  $\bigcap_{i \in I} S_i \in \mathcal{C}$ , then Zorn's lemma tells us  $\mathcal{C}$  has a maximal element (i.e. minimal spanning set)

BUT:  $\bigcap_{i \in I} S_i$  MAY NOT always be in  $\mathcal{C}$ !!

## Linear Transformation

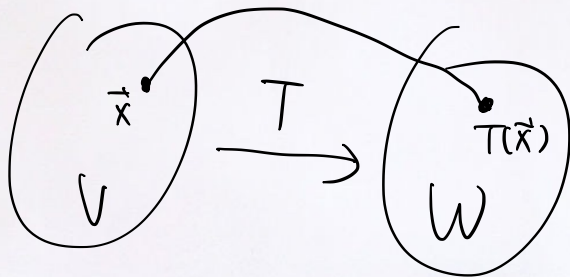
Definition: Let  $V$  and  $W$  be vector spaces over  $F$ .

A linear transformation from  $V$  to  $W$  is a map  $T: V \rightarrow W$

such that: (a)  $T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$

(b)  $T(a\vec{x}) = aT(\vec{x})$

for all  $\vec{x}, \vec{y} \in V$ ,  $a \in F$ .





Proposition: Let  $T: V \rightarrow W$  be a linear transformation. Then:

$$(i) \quad T(\vec{0}_V) = \vec{0}_W$$

$$(ii) \quad T\left(\sum_{i=1}^n a_i \vec{x}_i\right) = \sum_{i=1}^n a_i T(\vec{x}_i) \quad \forall \vec{x}_1, \vec{x}_2, \dots, \vec{x}_n \in V$$

*(T preserves linear combination)*  $a_1, a_2, \dots, a_n \in F.$

$$(i) \quad T(\vec{0}_V) = T(\vec{0}_V + \vec{0}_V) = T(\vec{0}_V) + T(\vec{0}_V)$$

$$\Rightarrow T(\vec{0}_V) = \vec{0}_W. \quad (\text{Cancellation law})$$

(ii) Use math. induction (exercise)

Examples: • For any vector spaces  $V$  and  $W$ , we have:

(a) The **zero transformation**  $T_0: V \rightarrow W$  defined by  $T_0(\vec{x}) := \vec{0}_W$   
for  $\forall \vec{x} \in V$

(b) The **identity transformation**  $I_V: V \rightarrow V$  defined by  $I_V(\vec{x}) = \vec{x}$   
for  $\forall \vec{x} \in V$ .

• Let  $A \in M_{m \times n}(F)$  be a  $m \times n$  matrix.  $F$ .

Define:  $L_A: F^n \rightarrow F^m$  as: ( $F^n =$  space of col vectors of size  $n$ )

$$L_A(\vec{x}) \stackrel{\text{def}}{=} A\vec{x}$$

$L_A$  is called the left multiplication by  $A$ .

•  $T: M_{m \times n}(F) \rightarrow M_{n \times m}(F)$  defined by  $T(A) \stackrel{\text{def}}{=} A^t$  (transpose of  $A$ )

- $T: P_n(\mathbb{R}) \rightarrow P_{n-1}(\mathbb{R})$  defined by  $T(f(x)) = f'(x)$   
is a lin. transf. (derivative of  $f$ )

- Let  $a$  and  $b \in \mathbb{R}$ ,  $a < b$ . Then,

$T: C(\mathbb{R}) \rightarrow \mathbb{R}$  defined by =  
(Space of continuous functions)

$$T(f) \stackrel{\text{def}}{=} \int_a^b f(t) dt$$

## Null space or Range

Definition: Let  $V$  and  $W$  be vector spaces and  $T: V \rightarrow W$  be a linear transformation

Then, the null space (or kernel) of  $T$  is defined as:

$$N(T) := \text{def } \{ \vec{x} \in V : T(\vec{x}) = \vec{0}_W \} \subset V$$

the range (or image) of  $T$  is defined as:

$$R(T) := \{ T(\vec{x}) : \vec{x} \in V \} \subset W$$

e.g. For  $I_V: V \rightarrow V$ ,  $N(I_V) = \{ \vec{0}_V \}$ ,  $R(I_V) = V$   
(identity)

For  $T_0: V \rightarrow W$ ,  $N(T_0) = V$ ,  $R(T_0) = \{ \vec{0}_W \}$   
(zero transf)



•  $L_A: F^n \rightarrow F^m$  ( $A \in M_{m \times n}(F)$ )

$N(L_A) = N(A) =$  null space of  $A$

$R(L_A) = \mathcal{C}(A) =$  col space of  $A$

(space of linear combination of col vectors of  $A$ )

• For  $T: P_n(\mathbb{R}) \rightarrow P_{n-1}(\mathbb{R})$  defined by

$T(f(x)) = f'(x)$ , then:

$N(T) = \{ a_0 \in P_n(\mathbb{R}) : a_0 \in \mathbb{R} \}$

$R(T) = P_{n-1}(\mathbb{R})$

$A = \left( \begin{array}{c|c|c|c} | & | & \dots & | \end{array} \right)$

Proposition: Let  $T: V \rightarrow W$  be a linear transformation.

Then  $N(T)$  and  $R(T)$  are subspaces of  $V$  and  $W$  respectively.

Proof:  $\because T(\vec{0}_V) = \vec{0}_W$

$\therefore \vec{0}_V \in N(T)$  and  $\vec{0}_W \in R(T)$

Let  $\vec{x}$  and  $\vec{y} \in N(T)$  and  $a \in F$ . Then:

$$T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y}) = \vec{0}_W + \vec{0}_W = \vec{0}_W \quad \text{and}$$

$$T(a\vec{x}) = aT(\vec{x}) = a\vec{0}_W = \vec{0}_W$$

$\therefore \vec{x} + \vec{y} \in N(T)$  and  $a\vec{x} \in N(T)$

$\therefore N(T)$  is a subspace of  $V$ .

Now, let  $\vec{u}, \vec{v} \in R(T)$  and  $a \in F$ .

Then:  $\exists \vec{x}, \vec{y} \in V$  such that  $\vec{u} = T(\vec{x})$  and  $\vec{v} = T(\vec{y})$

$$\text{So, } T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y}) = \vec{u} + \vec{v} \Rightarrow \vec{u} + \vec{v} \in R(T)$$

$$T(a\vec{x}) = aT(\vec{x}) = a\vec{u} \Rightarrow a\vec{u} \in R(T)$$

$\therefore R(T)$  is a subspace of  $W$ .

Remark:  $T: V \rightarrow W$  is onto iff  $R(T) = W$   
(follows from the def)

Proposition: A linear transformation  $T: V \rightarrow W$  is one-to-one  
iff  $N(T) = \{\vec{0}\}$ .

Pf: (Recap: One-to-one  $\Leftrightarrow$  " $T(\vec{x}) = T(\vec{y}) \Rightarrow \vec{x} = \vec{y}$ ")

$(\Rightarrow)$  If  $T$  is one-to-one, then: for any  $\vec{x} \in N(T)$ ,

$$\text{we have } T(\vec{x}) = \vec{0}_W = T(\vec{0}_V)$$

$$\Rightarrow \vec{x} = \vec{0}_V$$

This implies  $N(T) = \{\vec{0}_V\}$ .



( $\Leftarrow$ ) Suppose  $N(T) = \{\vec{0}_V\}$

Let  $\vec{x}, \vec{y} \in V$  such that  $T(\vec{x}) = T(\vec{y})$ .

Then:  $T(\vec{x}) - T(\vec{y}) = T(\vec{x} - \vec{y}) = \vec{0}$

This implies  $\vec{x} - \vec{y} \in N(T) = \{\vec{0}_V\}$

$\therefore \vec{x} - \vec{y} = \vec{0}_V$  or  $\vec{x} = \vec{y}$ .

$\therefore T$  is 1-1.

Definition: Let  $T: V \rightarrow W$  be a linear transformation.

If  $N(T)$  and  $R(T)$  are finite-dimensional, we define:

- Nullity is denoted as Nullity  $(T)$  is the dimension of  $N(T)$ .
- Rank is denoted as Rank  $(T)$  is the dimension of  $R(T)$ .

Lemma: Let  $T: V \rightarrow W$  be a linear transformation. If

$\beta = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is a basis for  $V$ , then:

$$R(T) = \text{Span}(T(\beta)) \stackrel{\text{def}}{=} \text{Span}\{T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n)\}$$

Proof:  $\because T(\vec{v}_j) \in R(T)$  for  $j=1, 2, \dots, n$

and  $R(T)$  is subspace.

$$\therefore \text{Span} \left\{ \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_1)}, \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_2)}, \dots, \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_n)} \right\} \subset R(T)$$

Conversely, let  $\vec{w} \in R(T)$  where  $\vec{x} \in V$ .

$$\text{Then: } \exists a_1, a_2, \dots, a_n \in F \text{ s.t. } \vec{x} = \sum_{j=1}^n a_j \vec{v}_j.$$

$$\text{So, } \vec{w} = T(\vec{x}) = T\left(\sum_{j=1}^n a_j \vec{v}_j\right) = \sum_{j=1}^n a_j T(\vec{v}_j) \in \text{Span}\{T(\vec{v}_1), \dots, T(\vec{v}_n)\}$$

$$\therefore R(T) \subset \text{Span}(T(\beta)) \quad \therefore R(T) = \text{Span}(T(\beta))$$

Example:  $T: P_2(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$  defined by:

$$T(f) = \begin{pmatrix} f(0) & f(1) \\ 0 & f'(0) \end{pmatrix}$$

Take  $\beta = \{1, x, x^2\}$  as basis of  $P_2(\mathbb{R})$ .

We have:  $R(T) = \text{span} \{ T(1), T(x), T(x^2) \} = \text{Span}(T(\beta))$

$$= \text{span} \left\{ \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right\}$$

Lin. indep.

$$\Rightarrow \text{Rank}(T) = 3$$



Theorem: (Rank - Nullity Theorem)

Let  $V$  and  $W$  be vector spaces s.t.  $V$  is finite-dimensional.

Then for any linear transformation  $T: V \rightarrow W$ , we have:

$$\text{nullity}(T) + \text{Rank}(T) = \text{dim}(V)$$

Proof: Let  $n = \text{dim}(V)$  and  $k = \text{dim}(N(T)) \leq n$

Choose a basis  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  for  $N(T)$  and extend it to a basis  $\{\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$  for  $V$ .

Claim:  $S = \{T(\vec{v}_{k+1}), T(\vec{v}_{k+2}), \dots, T(\vec{v}_n)\}$  is a basis for  $R(T)$ .

$$\begin{aligned}
 \textcircled{1} \quad R(T) &= \text{span} \{ T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n) \} \\
 &= \text{span} \{ \underbrace{T(\vec{v}_{k+1}), \dots, T(\vec{v}_n)}_S \} = \text{span}(S)
 \end{aligned}$$

$\textcircled{2}$  Now suppose  $\exists b_{k+1}, b_{k+2}, \dots, b_n \in F$  s.t.

$$\sum_{i=k+1}^n b_i T(\vec{v}_i) = \vec{0}.$$

Then, by linearity, we have:  $T\left(\sum_{i=k+1}^n b_i \vec{v}_i\right) = \vec{0}$

$$\Rightarrow \sum_{i=k+1}^n b_i \vec{v}_i \in N(T)$$

$$\therefore \sum_{i=k+1}^n b_i \vec{v}_i = \sum_{i=1}^k c_i \vec{v}_i \quad \text{for some } c_1, \dots, c_k \in F.$$

But then: 
$$\sum_{i=1}^k (-c_i) \vec{v}_i + \sum_{i=k+1}^n b_i \vec{v}_i = \vec{0}$$

$\therefore \{\vec{v}_1, \dots, \vec{v}_n\}$  is a basis for  $V$  and so it is lin. ind.

$$\therefore (-c_i) = 0 \quad \text{for } i=1, 2, \dots, k$$

$$b_i = 0 \quad \text{for } i=k+1, k+2, \dots, n$$

$\therefore S$  is lin. ind.

$\therefore S$  is basis for  $R(T)$ .

$$\begin{aligned} \therefore & \text{Nullity}(T) + \text{Rank}(T) \\ &= \overset{\parallel}{k} + (n-k) \parallel \\ &= n = \dim(V) \parallel \end{aligned}$$