

Lecture 20

Jordan Canonical Form

Recall: Let $T: V \rightarrow V$ lin. operator on a fin-dim V (over F)

$T: V \rightarrow V$ is diagonalizable \Leftrightarrow

① Char poly splits.

② $\dim(E_{\lambda_i}) = m_i \leftarrow$ alg. multiplicity for all eigenvalues λ_i

(In general, $\dim(E_{\lambda_i}) \leq m_i$)

Remark: "Diagonalizable" \Leftrightarrow eigenspaces are BIG enough
(as a linear transf)

Theorem: Any $A \in M_{n \times n}(\mathbb{C})$ is similar to a matrix of the following form:

$$J = \begin{pmatrix} \boxed{\begin{matrix} \lambda_1 & 1 & 0 \\ & \lambda_1 & | \\ 0 & & \lambda_1 \end{matrix}} & & & \\ & \boxed{\begin{matrix} \lambda_2 & 1 & 0 \\ & \lambda_2 & | \\ 0 & & \lambda_2 \end{matrix}} & & \\ & & \dots & \\ & & & \boxed{\begin{matrix} \lambda_N & 1 & 0 \\ & \lambda_N & | \\ 0 & & \lambda_N \end{matrix}} \end{pmatrix}$$

(Jordan Canonical Form of A)

$\lambda_1, \lambda_2, \dots, \lambda_N$ are eigenvalues of A
(not necessarily distinct)

$$\left(\begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 3 & 3 \end{pmatrix} \right)$$

Given $T: V \rightarrow V$, V is fin-dim.

Find a basis β of $V \ni [T]_{\beta} = \begin{pmatrix} A_1 & & & \\ & A_2 & & \\ & & \ddots & \\ & & & A_k \end{pmatrix}$

$A_i = \begin{pmatrix} \lambda & & & 0 \\ & \lambda & & \\ & & \ddots & \\ 0 & & & \lambda \end{pmatrix}$ where λ is an eigenvalue of T .
($A_i =$ block square matrix)

- Remark:
- $[T]_{\beta}$ is called the Jordan Canonical form of T
 - A_i is called a Jordan block corresponding to λ
 - β is called the Jordan canonical basis.

Remark: Jordan canonical consists of blocks in this form:

$$A = \begin{pmatrix} \lambda & 1 & & 0 \\ & \lambda & \ddots & \\ & & \lambda & 1 \\ 0 & & & \lambda \end{pmatrix} \in M_{k \times k}(\mathbb{C})$$

It is called Jordan block of size k with eigenvalue λ .

Prop: (1) A has only 1 eigenvalue λ (multiplicity is k)
(2) $\dim(E_\lambda) = 1$ ($\Rightarrow A$ is not diagonalizable if $k \neq 1$)

(3) The smallest positive integer p s.t.

$(A - \lambda I)^p = 0$ is equal to the dimension k .

$$(\Rightarrow N((A - \lambda I)^p) = \mathbb{C}^k)$$

(4) If $\{\vec{e}_1, \dots, \vec{e}_k\}$ is the standard basis for \mathbb{C}^k ,

then $(A - \lambda I)^i \vec{e}_i = 0$ for each $i = 1, 2, \dots, k$.

$$K = \begin{pmatrix} \lambda & & & 0 \\ & \lambda & & \\ & & \ddots & \\ 0 & & & \lambda \end{pmatrix}$$

$$\Rightarrow \begin{cases} \textcircled{1} 1 \text{ eigenvalue} \\ \textcircled{2} \dim(E_\lambda) = 1 \end{cases}$$

$$N(K - \lambda I) = n - R(K - \lambda I) = 1$$

$$R \left(\begin{pmatrix} \lambda & & & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & & & \lambda \end{pmatrix} \right) = n-1$$

If JCF of A is

$$J = \left(\begin{array}{c} \begin{pmatrix} 2 & 1 \\ & 2 \end{pmatrix} \\ \begin{pmatrix} 2 & 1 & \\ & 2 & 1 \\ & & 2 \end{pmatrix} \\ \begin{pmatrix} 3 & 1 & \\ & 3 & 1 \\ & & 3 \end{pmatrix} \end{array} \right)$$

$$\text{Then: } E_2 = N(J - 2I)$$

$$= 2$$

\neq algebraic multiplicity

$$= 5$$

\therefore Not diagonalizable.

e.g. $A = \begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{pmatrix}$. Then: $(A - \lambda I) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$

$$(A - \lambda I)^2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(A - \lambda I)^3 = 0$$

Definition: Let λ be an eigenvalue of $A \in M_{n \times n}(\mathbb{C})$.

$\vec{x} \in \mathbb{C}^n$ is a generalized eigenvector of A corresponding to the eigenvalue λ if (i) $\vec{x} \neq \vec{0}$

and (ii) $(A - \lambda I)^p \vec{x} = \vec{0}$ for some positive integer p .

We denote the generalized eigenspace by:

$$K_\lambda = \{ \vec{x} \in \mathbb{C}^n = (A - \lambda I)^p \vec{x} = \vec{0} \text{ for some } p \geq 1 \}$$

Main Theorem: (Jordan Decomposition Theorem)

Let $A \in M_{n \times n}(\mathbb{C})$ with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$ (distinct) with corresponding multiplicities m_1, m_2, \dots, m_k . Then:

(1) $\dim(K_{\lambda_i}) = m_i$

(2) $\mathbb{C}^n = K_{\lambda_1} \oplus K_{\lambda_2} \oplus \dots \oplus K_{\lambda_k}$

(3) Each K_{λ_i} has a basis $\beta_i = \gamma_{1,i} \cup \dots \cup \gamma_{\ell,i}$ where every $\gamma_{m,i}$ is a **cycle** =

$$\gamma_{m,i} = \left\{ (A - \lambda_i I)^{m-1} \vec{x}, (A - \lambda_i I)^{m-2} \vec{x}, \dots, (A - \lambda_i I) \vec{x}, \vec{x} \right\}$$

Consider $\gamma = \{ (A - \lambda_i I)^{p-1} \vec{x}, (A - \lambda_i I)^{p-2} \vec{x}, \dots, \vec{x} \}$

$$\vec{w}_1 = (A - \lambda_i I) \vec{w}_2 \Rightarrow A \vec{w}_2 = \vec{w}_1 + \lambda_i \vec{w}_2$$

$[L_A]_\gamma =$

$$= \begin{pmatrix} [A \vec{w}_1]_\gamma & [A \vec{w}_2]_\gamma \\ \vdots & \vdots \\ \lambda_i & 1 & 0 \\ 0 & \lambda_i & 1 \\ \vdots & \vdots & \vdots \\ 0 & \vdots & \vdots \end{pmatrix}$$

\Downarrow Jordan block.

Example: $A = \begin{pmatrix} 2 & 2 & 3 \\ 1 & 3 & 3 \\ -1 & -2 & -2 \end{pmatrix}$

Step 1: Compute eigenvalues.

$f(t) = -(t-1)^3 \Rightarrow$ ONLY 1 eigenvalue $\lambda = 1$, ^{alg.} mult = 3.

Step 2: Find eigenspace

$E_1 = N(A - 1I) = N \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ -1 & -2 & -3 \end{pmatrix} = \text{span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} \right\}$

$\dim(E_1) = 2 < 3$ ($\Rightarrow A$ is NOT diagonalizable)

Step 3: Decide the Jordan Canonical Form

~~$J = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$~~

or

~~$J = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix}$~~

or $J = \begin{pmatrix} 1 & & \\ & 1 & 1 \\ & & 1 \end{pmatrix}$

Step 4: Find basis K_λ consisting of cycles.

$$\beta = \gamma_1 \cup \gamma_2 = \{\vec{v}_1\} \cup \{(A - \lambda I)\vec{v}_2, \vec{v}_2\}$$

Need $\vec{v}_2 \in N(A - \lambda I)^2$ but $\vec{v}_2 \notin N(A - \lambda I) = E_1$
eigenvectors

$$(A - 1I)^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Choose $\vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

Then $\gamma_2 = \{(A - \lambda I)\vec{v}_2, \vec{v}_2\} = \left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$

Take $\vec{v}_1 \in E_1 \Rightarrow \vec{v}_1$ is not parallel to $\begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$

Choose $\vec{v}_1 = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$

$$\Rightarrow Q^{-1}AQ = \begin{pmatrix} \boxed{1} & & \\ & \boxed{\begin{matrix} 1 & 1 \\ & 1 \end{matrix}} & \\ & & \end{pmatrix} \quad \text{where } Q = \begin{pmatrix} -2 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$$

Example: $A = \begin{pmatrix} -1 & 1 & 0 \\ 0 & -1 & -2 \\ 0 & 0 & -1 \end{pmatrix}$ alg.

Step 1: Eigenvalues $\lambda = -1$, mult. = 3

Step 2: Eigenspace $E_{-1} = \text{span}\left\{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right\}$

$\Rightarrow \dim(E_{-1}) = 1 < 3$

Step 3: Jordan Canonical Form

$$J = \begin{pmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix}$$

Step 4: Find the basis for K_{-1}

$$\beta = \left\{ (A+I)^2 \vec{v}, (A+I) \vec{v}, \vec{v} \right\}$$

Find $\vec{v} \in N((A+I)^3)$ but $\vec{v} \notin N((A+I))$
 $\vec{v} \notin N((A+I)^2)$

$$N(A+I) = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$N((A+I)^2) = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$\text{Take } \vec{v} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{Then: } \beta = \left\{ \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\Rightarrow Q^{-1} A Q = \begin{pmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix} \text{ where } Q = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Theoretical proof: $T: V \rightarrow V$ (fin-dim), char poly splits.
($\lambda_1, \lambda_2, \dots, \lambda_k$ distinct eigenvalues)

Claim 1: $(T - \lambda_i I)|_{K_{\lambda_j}}: K_{\lambda_j} \rightarrow K_{\lambda_j}$ is 1-1 if $i \neq j$.

Pf: Let $\vec{x} \in K_{\lambda_j}$ and $(T - \lambda_i I)(\vec{x}) = \vec{0}$.

Let $p =$ smallest integer $\Rightarrow (T - \lambda_j I)^p(\vec{x}) = \vec{0}$.

Let $\vec{y} = (T - \lambda_j I)^{p-1}(\vec{x}) \neq \vec{0}$. Then: $(T - \lambda_j I)(\vec{y}) = \vec{0}$

$\therefore \vec{y} \in E_{\lambda_j}$

Also, $(T - \lambda_i I)(\vec{y}) = (T - \lambda_i I)(T - \lambda_j I)^{p-1}(\vec{x})$
 $= (T - \lambda_j I)^{p-1} \underbrace{(T - \lambda_i I)(\vec{x})}_{\vec{0}} = \vec{0}$

$\therefore \vec{y} \in E_{\lambda_i}$

$\Rightarrow \vec{y} \in E_{\lambda_i} \cap E_{\lambda_j} = \{\vec{0}\} \Rightarrow \vec{y} = \vec{0}$ (Contradiction)

$N((T - \lambda_j I)|_{K_{\lambda_j}}) = \{\vec{0}\} \Rightarrow (T - \lambda_j I)|_{K_{\lambda_j}}$ is 1-1.

Claim 2: $\dim(K_{\lambda_i}) \leq m_i = \text{multiplicity of } \lambda_i \text{ and}$
 $K_{\lambda_i} = N((T - \lambda_i I)^{m_i})$

Pf: ① Let $g(t) = \text{char poly of } T|_{K_{\lambda_i}}$

Then $g(t) \mid \text{char poly of } T$.

Now, $(T - \lambda_j I)|_{K_{\lambda_i}}(\vec{x}) \neq \vec{0}$ if $\lambda_i \neq \lambda_j$ and $\vec{x} \neq \vec{0}$

$\therefore \lambda_i$ is the ONLY eigenvalue of $T|_{K_{\lambda_i}}$

$\therefore g(t) = (\lambda_i - t)^d$, $d = \dim(K_{\lambda_i})$

$\therefore d \leq m_i$

$$\textcircled{2} \quad N((T - \lambda_i I)^{m_i}) \subseteq K_{\lambda_i} \quad (\text{by definition})$$

Now, by Cayley-Hamilton Thm,

$$\text{Char poly of } T|_{K_{\lambda_i}} \rightarrow g(T|_{K_{\lambda_i}}) = 0$$

$$\begin{aligned} \therefore (T|_{K_{\lambda_i}} - \lambda_i I)^d &= 0 \Rightarrow (T - \lambda_i I)^d (\vec{x}) = \vec{0} \text{ for } \forall \vec{x} \in K_{\lambda_i} \\ &\quad (d \leq m_i) \\ &\Rightarrow (T - \lambda_i I)^{m_i} (\vec{x}) = \vec{0} \text{ for } \forall \vec{x} \in K_{\lambda_i} \end{aligned}$$

$$\therefore K_{\lambda_i} \subseteq N((T - \lambda_i I)^{m_i})$$

Claim 3: $V = K\lambda_1 + K\lambda_2 + \dots + K\lambda_k$

Pf: By M.I. on $k = \#$ of distinct eigenvalues.

When $k=1$, let $m =$ multiplicity of λ_1 . Then, char poly of T
By Cayley-Hamilton Thm, $g(T) = (\lambda_1 I - T)^m = 0 \Leftarrow \begin{matrix} \text{"} \\ \text{zero transf.} \end{matrix} (\lambda_1 - t)^m$.

$$\therefore K_{\lambda_1} = N((T - \lambda_1 I)^m) = V$$

\therefore Thm is true for $k=1$.

Assume that the thm is true for any lin. op. w/ fewer than k distinct eigenvalues.

Consider $T: V \rightarrow V$ with k distinct eigenvalues:

$$\lambda_1, \lambda_2, \dots, \lambda_k$$