

## Lecture 13:

Recall:  $T: V \rightarrow V$ ,  $F = \mathbb{C}$ .

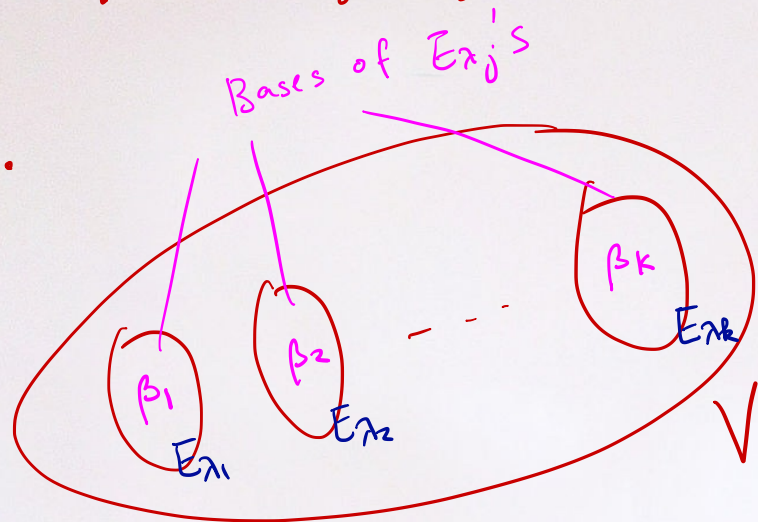
Char poly of  $T$ :  $f_T(t) = (-1)^n (t - \lambda_1)^{n_1} (t - \lambda_2)^{n_2} \dots (t - \lambda_k)^{n_k}$

$n_j =$  algebraic multiplicity of  $\lambda_j = \mu_T(\lambda_j)$

$$\dim(\text{Eigenspace of } \lambda_j) = \dim(N(T - \lambda_j I_V)) = \dim(E_{\lambda_j})$$

$$\text{Geometric multiplicity} = \gamma_T(\lambda_j)$$

- $T$  is diagonalizable iff  $\mu_T(\lambda_j) = \nu_T(\lambda_j)$   
for  $j=1, 2, \dots, k$



Then:  $\beta = \beta_1 \cup \beta_2 \cup \dots \cup \beta_k$  is a basis of eigenvectors  
for  $V$ .

Example: Let  $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$  be defined by:

$$T(f(x)) = f(x) + (x+1)f'(x)$$

Then:  $A := [T]_{\beta} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}$

where  $\beta = \{1, x, x^2\}$  = standard ordered basis for  $P_2(\mathbb{R})$ .

$\therefore$  the char. poly:

$$\det(A - tI_3) = \det \begin{pmatrix} 1-t & 1 & 0 \\ 0 & 2-t & 2 \\ 0 & 0 & 3-t \end{pmatrix} = (1-t)^1(2-t)^1(3-t)^1$$

$$\left. \begin{aligned} 1 &\leq \gamma_T(1) \leq \mu_T(1) = 1 \\ 1 &\leq \gamma_T(2) \leq \mu_T(2) = 1 \\ 1 &\leq \gamma_T(3) \leq \mu_T(3) = 1 \end{aligned} \right\}$$

$$\gamma_T(1) = \mu_T(1)$$

$$\gamma_T(2) = \mu_T(2)$$

$$\gamma_T(3) = \mu_T(3)$$

$\Rightarrow$  Diagonalizable

$$\cancel{E_1} N(A - 1I_3) = N \left( \begin{array}{ccc} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \end{array} \right) = \left\{ a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} : a \in \mathbb{R} \right\} \subseteq \mathbb{R}^3$$

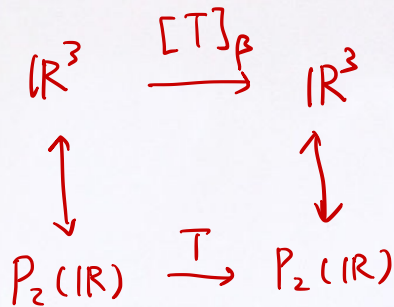
$$\Rightarrow \bar{E}_1 = N(T - 1I_V) = \{ a \cdot 1 : a \in \mathbb{R} \} \subseteq P_2(\mathbb{R})$$

$$\text{Similarly, } N(A - 2I_3) = N \left( \begin{array}{ccc} -1 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{array} \right) = \left\{ a \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} : a \in \mathbb{R} \right\}$$

$$E_2 = \{ a(1+x) : a \in \mathbb{R} \} \subseteq P_2(\mathbb{R})$$

$$E_3 = \{ a(1+2x+x^2) : a \in \mathbb{R} \}$$

$\beta = \{1, 1+x, (1+x)^2\}$  is a basis of eigenvectors for  $V$ .



Example: For  $A = \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{pmatrix} \in M_{3 \times 3}(\mathbb{R})$

$f_A(t) = -(t-4)(t-3)^2$  splits over  $\mathbb{R}$ .

$$\gamma_T(4) = \mu_T(4) = 1$$

But  $\text{rank}(A - 3I) = \text{rank}(\overset{B}{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}}) = 2$

$$\underbrace{(\text{Rank}(B))}_2 + \underbrace{(\text{Nullity}(B))}_1 = 3$$

$$\gamma_A(3) = 1 \neq \mu_A(3) = 2$$

$\therefore T$  is not diagonalizable.

Example: Consider  $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$  defined by:

$$T(f(x)) = f(1) + f'(0)x + (f'(0) + f''(0))x^2$$

Let  $\beta = \{1, x, x^2\}$ .

$$[T]_{\beta} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix} \Rightarrow f_T(t) = -(t-1)^2(t-2)$$

splits over  $\mathbb{R}$ .

and the eigenvalues of  $T$  are 1 and 2.

$$\therefore \gamma_T(2) = \mu_T(2) = 1.$$

$$\text{Rank}([T]_{\beta} - I) = \text{rank} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} = 1 \Rightarrow \gamma_T(1) = 2 = \mu_T(1)$$

$\therefore T$  is diagonalizable.

For  $[T]_{\beta}$ , the eigenspaces:

$$E_1 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_2 + x_3 = 0 \right\} = \text{span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}}_{\text{Basis}} \right\}$$

$$E_2 = \text{span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}}_{\text{Basis}} \right\}$$

$\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$  is a basis of eigenvectors (of  $[T]_{\beta}$ ) for  $\mathbb{R}^3$ .

$\therefore \{ 1, x-x^2, 1+x^2 \}$  is a basis of eigenvectors (of  $T$ ) for  $P_2(\mathbb{R})$ .

Definition: Let  $T$  be a linear operator on a vector space  $V$ .

A subspace  $W \subset V$  is called  $T$ -invariant if  $T(W) \subseteq W$ .

That is,  $T(\vec{w}) \in W$  for  $\forall \vec{w} \in W$ .

Example: If  $T$  is a linear operator on  $V$ , then:

$\{\vec{0}\}$  is  $T$ -invariant

$V$  is " "

$R(T)$  " "

$N(T)$  " "

$E_\lambda$  " "

↑  
eigenvalue

( $\vec{w} \in R(T)$ ), then:  $T(T(\vec{v})) \in R(T)$   
↑  
 $T(\vec{v})$

( $\vec{v} \in E_\lambda$ ),  $T(\vec{v}) = \lambda \vec{v} \in E_\lambda$



• For  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  defined by  $T(a, b, c) = (a+b, b+c, 0)$

then  $x$ - $y$  plane  $\{(x, y, 0) = x, y \in \mathbb{R}\}$  is  $T$ -invariant

$x$ -axis  $\{(x, 0, 0) = x \in \mathbb{R}\}$  is  $T$ -invariant

$z$ -axis  $\{(0, 0, x) = x \in \mathbb{R}\}$  is NOT  $T$ -invariant.

$$T\left(\underset{\circ}{\underset{\#}{0}}, 0, x\right) = \left(0, \underset{\circ}{\underset{\#}{x}}, 0\right) \notin z\text{-axis}$$

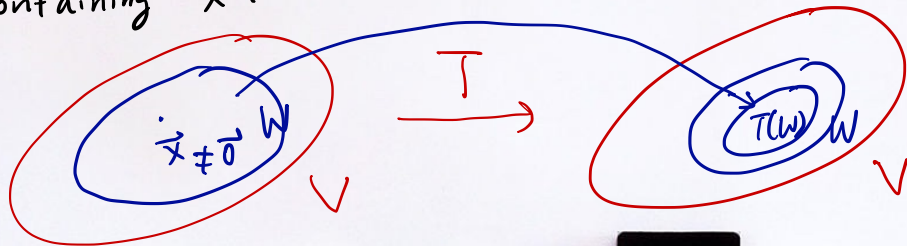
Def: Given a linear operator  $T$  on a vector space  $V$ , and a non-zero  $\vec{x} \in V$ , the subspace

$$W := \text{span}(\{T^k(\vec{x}) : k \in \mathbb{N}\}) \stackrel{\text{def}}{=} \text{span}(\{\vec{x}, T(\vec{x}), T^2(\vec{x}), \dots, T^k(\vec{x}), \dots\})$$

$$(T^k \stackrel{\text{def}}{=} \underbrace{T \circ T \circ \dots \circ T}_{k \text{ times}})$$

is called  $T$ -cyclic subspace of  $V$  generated by  $\vec{x}$ .

Prop:  $W$  is the smallest  $T$ -invariant subspace of  $V$  containing  $\vec{x}$ .



Proof: For any  $\vec{w} \in W$ ,  $\exists a_0, \dots, a_k \in F$  s.t.

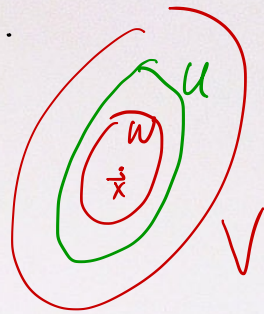
$$\vec{w} = \sum_{i=0}^k a_i T^i(\vec{x})$$

Then:  $T(\vec{w}) = \sum_{i=0}^k a_i T^{i+1}(\vec{x}) \in W$ .

$\therefore W$  is  $T$ -invariant.

If  $U \subset V$  is a  $T$ -invariant subspace containing  $\vec{x}$ .  
then: it also contains  $T(\vec{x}) \in U$  and  $T^k(\vec{x}) \in U$  by induction.

$\therefore U \supset W$



Example: • For  $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$  defined by  $T(f(x)) = f'(x)$   
 then  $T$ -cyclic subspace generated by  $x^n$  is:

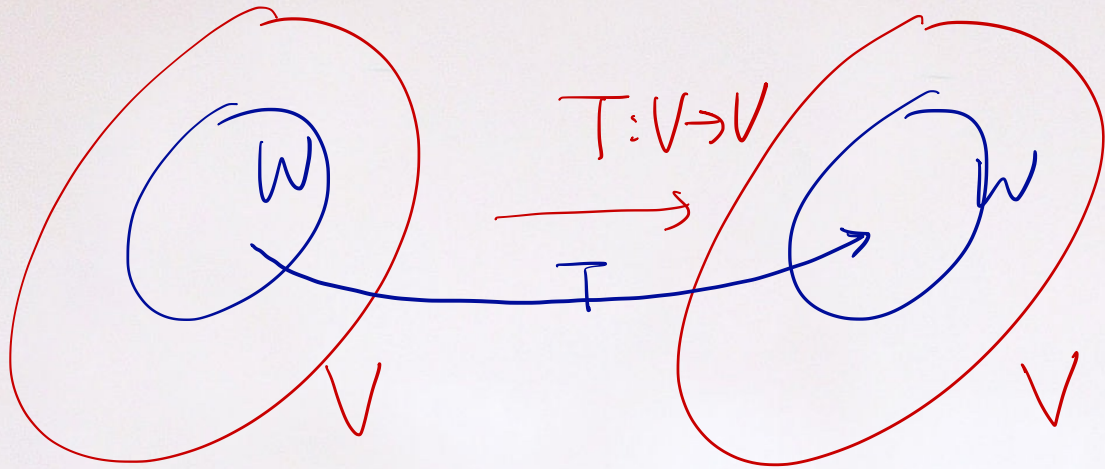
$$\text{span}\left\{x^n, n x^{n-1}, \dots, n! x, n!\right\} = P_n(\mathbb{R})$$

• Let  $T: V \rightarrow V$  be linear. Then, a 1-dimensional  
 $T$ -invariant subspace  $U \subset V$  is nothing but the span  
 of an eigenvector of  $T$ .

[If  $U = 1$ -dim  $T$ -invariant subspace.

Then,  $U = \text{span}\left\{\underset{\neq 0}{\vec{v}}\right\}$ . Then:  $T(\vec{v}) \in U \Rightarrow T(\vec{v}) = \lambda \vec{v} \therefore \vec{v} = \text{eigenvector of } T$ .

Also, if  $\vec{v} \in V$  is an eigenvector of  $T$ , then  $T$ -cyclic  
 subspace generated by  $\vec{v}$  is also  $\text{span}\{\vec{v}\} (= \{\vec{v}, \cancel{\frac{T(\vec{v})}{\lambda \vec{v}}}, \cancel{\frac{T^2(\vec{v})}{\lambda^2 \vec{v}}}, \dots\})$



Def:  $T|_W: W \rightarrow W$  defined by  $T|_W(\vec{w}) = T(\vec{w})$

$\mathcal{F}_{T|_W}(t)$  divides  $\mathcal{F}_T(t)$