

## Change of Variables Formula : $(\mathbb{R}^2)$

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$$

$$\Rightarrow \begin{cases} dx = x_u du + x_v dv \\ dy = y_u du + y_v dv \end{cases}$$

$$\begin{aligned} \Rightarrow dx \wedge dy &= (x_u du + x_v dv) \wedge (y_u du + y_v dv) \\ &= (x_u y_v - x_v y_u) du \wedge dv \\ &= \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du \wedge dv \\ &= \frac{\partial(x, y)}{\partial(u, v)} du \wedge dv \end{aligned}$$

$$\boxed{dx \wedge dy = \frac{\partial(x, y)}{\partial(u, v)} du \wedge dv}$$

↑ Jacobian determinant.

Hence naturally

$$\boxed{\iint f(x, y) dx \wedge dy = \iint f(x(u, v), y(u, v)) \frac{\partial(x, y)}{\partial(u, v)} du \wedge dv}$$

Compare with

$$\boxed{\iint f(x, y) dx dy = \iint f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv}$$

Similarly for

$$\begin{cases} x = x(u, v, w) \\ y = y(u, v, w) \\ z = z(u, v, w) \end{cases}$$

Then

$$\boxed{dx \wedge dy \wedge dz = \frac{\partial(x, y, z)}{\partial(u, v, w)} du \wedge dv \wedge dw}$$

Pf:

$$\begin{aligned} dx \wedge dy \wedge dz &= (x_u du + x_v dv + x_w dw) \wedge (y_u du + y_v dv + y_w dw) \\ &\quad \wedge (z_u du + z_v dv + z_w dw) \\ &= (x_u y_v z_w - x_u y_w z_v) du \wedge dv \wedge dw \\ &\quad + (-x_v y_u z_w + x_v y_w z_u) du \wedge dv \wedge dw \\ &\quad + (x_w y_u z_v - x_w y_v z_u) du \wedge dv \wedge dw \quad (\text{Ex!}) \\ &= [x_u (y_v z_w - y_w z_v) - x_v (y_u z_w - y_w z_u) + x_w (y_u z_v - y_v z_u)] \\ &\quad du \wedge dv \wedge dw \\ &= \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix} du \wedge dv \wedge dw \quad \# \end{aligned}$$

- "Oriented" change of variables formula
- " $dx \wedge dy$ " oriented area element
- " $dx \wedge dy \wedge dz$ " oriented volume element.

(see later remark)

# Exterior differentiation "d" on a form "ω".

|   |   |                            |
|---|---|----------------------------|
| (0-form) $f$  | $df$  | (1-form)                   |
| (1-form) $\omega = \omega_1 dx + \omega_2 dy + \omega_3 dz$                           | $d\omega = d\omega_1 \wedge dx + d\omega_2 \wedge dy + d\omega_3 \wedge dz$                           | (2-form)                   |
| (2-form) $\zeta = \zeta_1 dy \wedge dz + \zeta_2 dz \wedge dx + \zeta_3 dx \wedge dy$ | $d\zeta = d\zeta_1 \wedge dy \wedge dz + d\zeta_2 \wedge dz \wedge dx + d\zeta_3 \wedge dx \wedge dy$ | (3-form)                   |
| (3-form) $f dx \wedge dy \wedge dz$   | $df \wedge dx \wedge dy \wedge dz = 0$  | (4-form) in $\mathbb{R}^3$ |

eg 0 :  $d(dx) = d(dy) = d(dz) = 0$

eg 1 (in  $\mathbb{R}^2$ )  $\omega = M dx + N dy$  ( $M = M(x,y), N = N(x,y)$ )

then  $d\omega = dM \wedge dx + dN \wedge dy$

$$= (M_x dx + M_y dy) \wedge dx + (N_x dx + N_y dy) \wedge dy$$

$$= (N_x - M_y) dx \wedge dy$$

↑ (+ve) oriented area element

In this notation, Green's Thm

$$\oint_{C=\partial R} M dx + N dy = \iint_R (N_x - M_y) dx dy$$

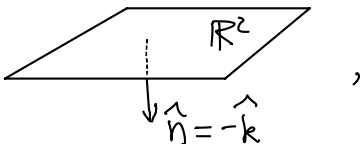
can be written as

$$\boxed{\oint_{\partial R} \omega = \iint_R d\omega}$$

Remark : If we let  $\vec{F} = M\hat{i} + N\hat{j} \iff \omega = Mdx + Ndy$

$$\text{then } (\vec{\nabla} \times \vec{F}) \cdot \hat{n} dA = (N_x - M_y) \underbrace{\hat{k} \cdot \hat{n}}_{dx \wedge dy} dA \iff d\omega$$

$\uparrow$   
 $(\hat{n} = \hat{k})$

and if we use 

then  $\hat{k} \cdot \hat{n} dA = -dx \wedge dy$

Hence  $\hat{k} \cdot \hat{n} dA = \begin{cases} dx \wedge dy & \text{if } \hat{n} = \hat{k} \\ dy \wedge dx & \text{if } \hat{n} = -\hat{k} \end{cases}$

$\uparrow$   
 (orientation of the "surface" domain)

eg 2 :  $\zeta = \zeta_1 dy \wedge dz + \zeta_2 dz \wedge dx + \zeta_3 dx \wedge dy$

Then  $d\zeta = d\zeta_1 \wedge dy \wedge dz + d\zeta_2 \wedge dz \wedge dx + d\zeta_3 \wedge dx \wedge dy$

$$= \left( \frac{\partial \zeta_1}{\partial x} dx + \dots \right) \wedge dy \wedge dz$$

$$+ \left( \dots + \frac{\partial \zeta_2}{\partial y} dy + \dots \right) \wedge dz \wedge dx$$

$$+ \left( \dots + \frac{\partial \zeta_3}{\partial z} dz \right) \wedge dx \wedge dy$$

$$= \left( \frac{\partial \zeta_1}{\partial x} + \frac{\partial \zeta_2}{\partial y} + \frac{\partial \zeta_3}{\partial z} \right) dx \wedge dy \wedge dz$$

$$= \text{div} \vec{F} dx \wedge dy \wedge dz$$

where  $\vec{F} = \zeta_1 \hat{i} + \zeta_2 \hat{j} + \zeta_3 \hat{k}$

Hence the divergence thm can be written as

$$\begin{aligned} \iiint_D d\vec{s} &= \iiint_D \left( \frac{\partial s_1}{\partial x} + \frac{\partial s_2}{\partial y} + \frac{\partial s_3}{\partial z} \right) \underbrace{dx dy dz}_{\text{+ve oriented volume element}} \\ &= \iiint_D \operatorname{div} \vec{F} dV = \iint_{\partial D} \vec{F} \cdot \vec{n} d\sigma \\ &\quad \uparrow \text{outward} \end{aligned}$$

(to be cont'd)