

eg 48 Verify both forms of Green's Thm for

$$\vec{F}(x,y) = (x-y)\hat{i} + x\hat{j} \quad \text{on } \Omega = \mathbb{R}^2, \quad \text{is } C^\infty.$$

$$C = \text{unit circle} = \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}, \quad t \in [0, 2\pi]$$

Then  $R =$  region enclosed by  $C = \{x^2 + y^2 < 1\}$  the unit disc.

(We also write  $C = \partial R$  boundary of  $R$ )

Soln  $M = x-y$  &  $N = x$

$$\frac{\partial M}{\partial x} = 1, \quad \frac{\partial M}{\partial y} = -1; \quad \frac{\partial N}{\partial x} = 1, \quad \frac{\partial N}{\partial y} = 0$$

$$\text{On } C, \quad x = \cos t, \quad y = \sin t, \quad t \in [0, 2\pi]$$

Normal form

$$\text{L.H.S.} = \oint_C M dy - N dx$$

$$= \int_0^{2\pi} (\cos t - \sin t) d(\sin t) - \cos t d(\cos t)$$

$$= \int_0^{2\pi} \cos^2 t dt = \pi \quad (\text{check!})$$

$$\text{R.H.S.} = \iint_R \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx dy = \iint_R (1+0) dx dy = \iint_R dx dy = \pi$$

Tangential form

$$\text{L.H.S.} = \oint_C M dx + N dy = \dots = 2\pi \quad (\text{check!})$$

$$\text{R.H.S.} = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy = \iint_R (1 - (-1)) dx dy = 2\pi$$

(Note: This example shows that even the 2 forms are equivalent, the values involved may differ.)

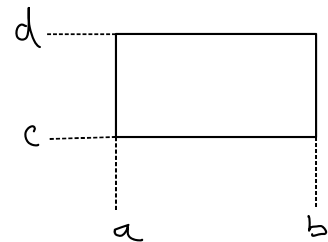
# Pf of Green's Thm (tangential form)

Recall: A region  $R$  is of special type:

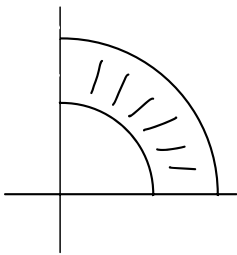
type (1): If  $R = \{(x,y) = a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$   
for some continuous functions  $g_1(x)$  &  $g_2(x)$ .

type (2): If  $R = \{(x,y) = h_1(y) \leq x \leq h_2(y), c \leq y \leq d\}$   
for some continuous functions  $h_1(x)$  &  $h_2(x)$ .

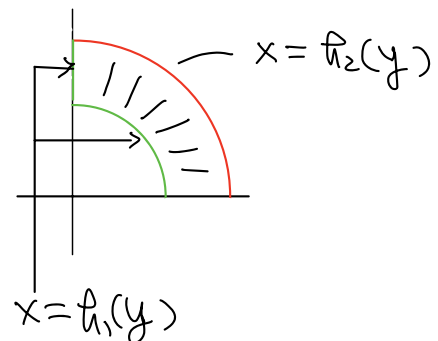
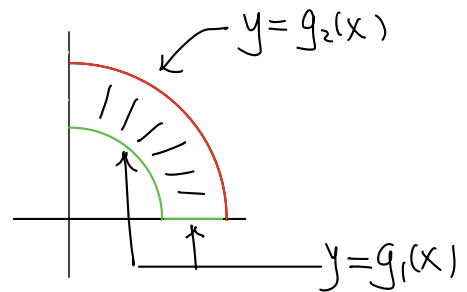
Now: If  $R$  is both type (1) and type (2), it said to be simple.

eg 4: (i)  rectangle is simple

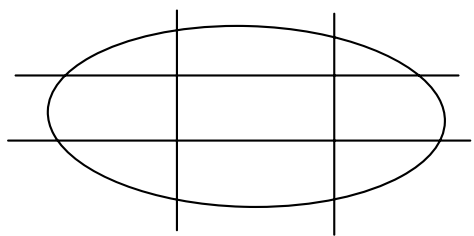
(ii)



simple  
 / type (1)  
 \ type (2)



(iii)



2 intersections at most

2 intersections at most

} ⇒ simple

$$\forall a \in \mathbb{R}: \# \{ \partial R \cap \{x=a\} \} \leq 2$$

$$\# \{ \partial R \cap \{y=a\} \} \leq 2$$

} ⇒ simple

(provided  $\partial R$  is piecewise smooth)

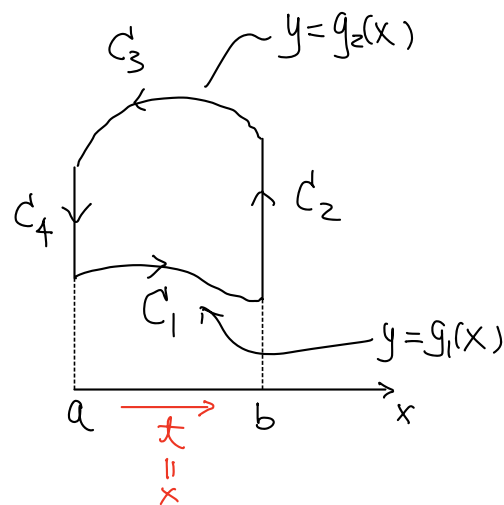
(Proof: Omitted)

### Pf of Green's Thm for Simple Region

By definition,  $R$  is of type (1) and

can be written as

$$R = \{ (x,y) : a \leq x \leq b, g_1(x) \leq y \leq g_2(x) \}$$

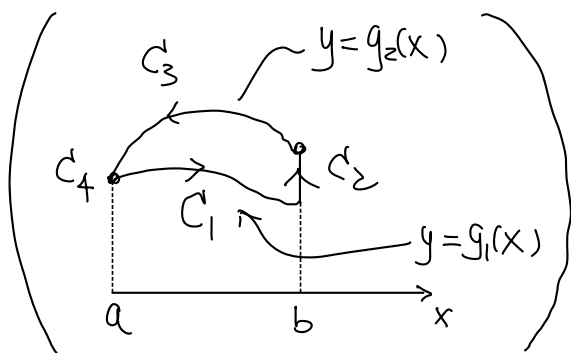


Let denote the components of the boundary

of  $R$  by  $C_1, C_2, C_3$  and  $C_4$  as

in the figure (Note:  $C_2$  and/or  $C_4$

could just be a point)



Then  $\partial R = C_1 + C_2 + C_3 + C_4$  as oriented curve

(using "+" instead of "U" to denote the orientation)

Now  $C_1 = \{y = g_1(x)\}$  can be parametrized by

$$(x, y) = \vec{r}(t) = (t, g_1(t)), \quad a \leq t \leq b \quad (\text{with correct orientation})$$

$$\therefore \int_{C_1} M dx = \int_a^b M(t, g_1(t)) dt$$

Similarly " $-C_3$ " can be parametrized by

$$\vec{r}(t) = (t, g_2(t)), \quad a \leq t \leq b \quad (\text{with correct orientation})$$

$$\therefore \int_{-C_3} M dx = \int_a^b M(t, g_2(t)) dt$$

For  $C_2 = \{x = b, g_1(b) \leq y \leq g_2(b)\}$ , it can be parametrized by

$$\vec{r}(t) = (b, t), \quad g_1(b) \leq t \leq g_2(b) \quad (\text{with correct orientation})$$

$$\therefore \int_{C_2} M dx = 0 \quad (\text{since } \frac{dx}{dt} = 0)$$

$$\text{Similarly } \int_{C_4} M dx = - \int_{-C_4} M dx = 0.$$

$$\text{Hence } \oint_{\partial R} M dx = \sum_{i=1}^4 \oint_{C_i} M dx$$

$$= \int_a^b [M(t, g_1(t)) - M(t, g_2(t))] dt$$

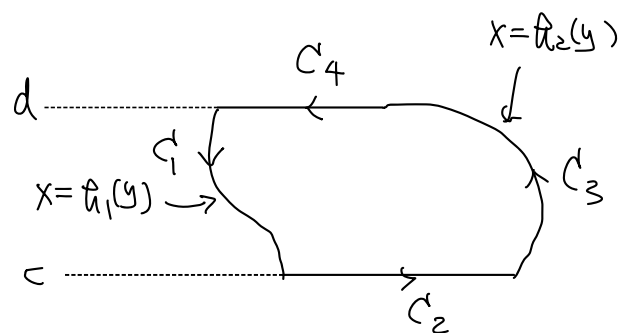
$$\left( = \int_a^b [M(x, g_1(x)) - M(x, g_2(x))] dx \right)$$

On the other hand, Fubini's Thm  $\Rightarrow$

$$\begin{aligned} \iint_R -\frac{\partial M}{\partial y} dA &= \int_a^b \left( \int_{g_1(x)}^{g_2(x)} -\frac{\partial M}{\partial y} dy \right) dx \\ &= \int_a^b [M(x, g_1(x)) - M(x, g_2(x))] dx \\ &= \oint_{\partial R} M dx \end{aligned}$$

Similar,  $R$  is also type (2),

$$R = \{(x, y) : h_1(y) \leq x \leq h_2(y), c \leq y \leq d\}$$



$$\begin{aligned} \oint_{\partial R} N dy &= - \int_c^d N(h_1(t), t) dt + 0 + \int_c^d N(h_2(t), t) dt + 0 \\ &= \int_c^d [N(h_2(t), t) - N(h_1(t), t)] dt \\ &= \int_c^d \left[ \int_{h_1(y)}^{h_2(y)} \frac{\partial N}{\partial x} dx \right] dy \\ &= \iint_R \frac{\partial N}{\partial x} dA \end{aligned}$$

All together

$$\oint_{\partial R} (M dx + N dy) = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \quad \neq$$

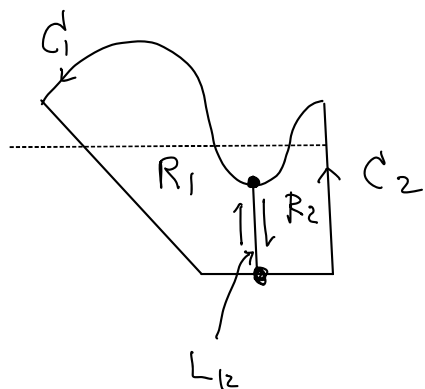
# Proof of Green's Thm for

$R =$  finite union of simple regions with intersections

only along some boundary line segments, and

those line segments touch only at the end points at most.

eg:



$R_1, R_2$  are simple

but  $R = R_1 \cup R_2 \neq$  simple

$$\partial R_1 = C_1 + L_{12}$$

$$\partial R_2 = C_2 - L_{12}$$



with anti-clockwise orientation

$$\text{and } \partial R = C_1 + C_2$$

By assumption  $R = \cup R_i$  finite union s.t.

- $R_i$  are simple, and

- $R_i \cap R_j =$  line segment of a common boundary portion denoted by

$$L_{ij} \quad (i \neq j)$$

$$\text{Then } \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA = \sum_i \iint_{R_i} \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

$$= \sum_i \oint_{\partial R_i} M dx + N dy \quad \left( \begin{array}{l} \text{by Green's Thm} \\ \text{for simple region} \end{array} \right)$$

Denote  $C_i =$  the part of  $\partial R_i$  with no intersection with any other  $R_j$  (except at the end points)

$$\text{Then } \partial R_i = C_i + \sum_{\substack{j \\ (j \neq i)}} L_{ij}$$

where  $L_{ij}$  is oriented according to the anti-clockwise orientation of  $\partial R_i$

Hence

$$\begin{aligned} \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA &= \sum_i \oint_{C_i + \sum_{\substack{j \\ (j \neq i)}} L_{ij}} M dx + N dy \\ &= \sum_i \int_{C_i} M dx + N dy + \sum_i \sum_{\substack{j \\ (j \neq i)}} \int_{L_{ij}} M dx + N dy \end{aligned}$$

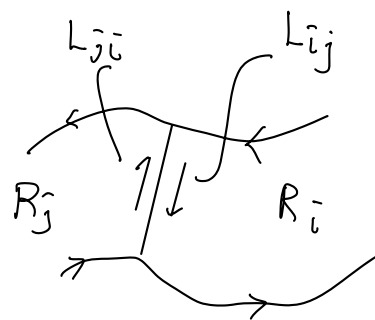
Note that, as  $C_i$  is not a common boundary of any other  $R_j$ ,

$$\sum_i C_i = \partial R$$

$$\therefore \sum_i \int_{C_i} M dx + N dy = \oint_{\partial R} M dx + N dy$$

Finally, we have  $L_{ji} = -L_{ij}$

as  $R_i$  &  $R_j$  are located on the two different sides of the



common boundary.

$$\sum_i \sum_{\substack{j \\ (j \neq i)}} \int_{L_{ij}} M dx + N dy = \sum_{\substack{i, j \\ (i \neq j)}} \int_{L_{ij}} M dx + N dy$$

$$= \sum_{i < j} \int_{L_{ij}} M dx + N dy + \sum_{\substack{j < i \\ i < j}} \int_{L_{ij}} M dx + N dy$$

$$= \sum_{i < j} \left( \int_{L_{ij}} M dx + N dy + \int_{L_{ji}} M dx + N dy \right)$$

$$= \sum_{i < j} \left( \int_{L_{ij}} M dx + N dy - \int_{L_{ij}} M dx + N dy \right)$$

$$= 0$$

This 2<sup>nd</sup> case basically include almost all situations in the level of Advanced Calculus.

The proof of general case needs "analysis" and will be omitted here.

✘



Def 12: The divergence of  $\vec{F} = M\hat{i} + N\hat{j}$  is defined to be

$$\operatorname{div} \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

Note:  $\operatorname{div} \vec{F} = \lim_{\epsilon \rightarrow 0} \frac{1}{\operatorname{Area}(\bar{D}_\epsilon(x,y))} \iint_{\bar{D}_\epsilon(x,y)} \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dA$

$$= \lim_{\epsilon \rightarrow 0} \frac{1}{\operatorname{Area}(\bar{D}_\epsilon(x,y))} \oint_{\partial \bar{D}_\epsilon(x,y)} \vec{F} \cdot \hat{n} \, ds$$

called  
= "flux density".

Notation: For  $f(x,y)$ ,  $\vec{\nabla} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j}$  (gradient)

$$= \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) f$$

It is convenient to denote

$$\vec{\nabla} = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right)$$

Then  $\vec{\nabla} \cdot \vec{F} = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot (M\hat{i} + N\hat{j})$

$$= \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} = \operatorname{div} \vec{F}$$

Hence we also write

$$\operatorname{div} \vec{F} = \vec{\nabla} \cdot \vec{F}$$

Def 13: Define  $\text{rot } \vec{F}$  to be

$$\text{rot } \vec{F} = \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \quad (\text{for } \vec{F} = M\hat{i} + N\hat{j})$$

Note: 
$$\text{rot } \vec{F} = \lim_{\epsilon \rightarrow 0} \frac{1}{\text{Area}(\bar{D}_\epsilon(xy))} \iint_{\bar{D}_\epsilon(xy)} \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

$$= \lim_{\epsilon \rightarrow 0} \frac{1}{\text{Area}(\bar{D}_\epsilon(xy))} \oint_{\partial \bar{D}_\epsilon(xy)} \vec{F} \cdot \hat{T} ds$$

called  
= circulation density

Using  $\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y}$ , we can write

$$\text{rot } \vec{F} = (\vec{\nabla} \times \vec{F}) \cdot \hat{k}$$

Since  $\vec{F} = M\hat{i} + N\hat{j} + \underbrace{0}_{\text{number zero}} \cdot \hat{k}$  (in  $\mathbb{R}^3$ ) ( $M=M(x,y)$  &  $N=N(x,y)$ )

$$\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \quad (\text{in } \mathbb{R}^3) \quad \left( \frac{\partial M}{\partial z} = \frac{\partial N}{\partial z} = 0 \right)$$

$$\Rightarrow \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ M & N \end{vmatrix} \hat{k} = \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \hat{k}$$

(check!)

$\Rightarrow \text{rot } \vec{F} = (\vec{\nabla} \times \vec{F}) \cdot \hat{k}$  i.e.  $\hat{k}$ -component of  $\vec{\nabla} \times \vec{F}$ .

A name for  $\vec{\nabla} \times \vec{F}$  is curl  $\vec{F}$ :  $\text{curl } \vec{F} \stackrel{\text{def}}{=} \vec{\nabla} \times \vec{F}$