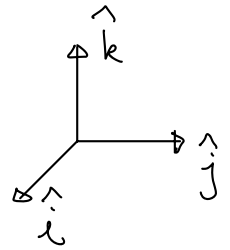


Vector Analysis

Notation: Usually in textbooks, vectors are denoted by boldface **i**, but hard to do it on screen, so my notation of vectors are:

general vectors: $\vec{v}, \vec{F}, \vec{r}, \vec{\nabla}, \dots$ (differential operators)

unit vectors: $\hat{i}, \hat{j}, \hat{k}, \hat{n}, \hat{T}, \dots$



and use $\|\vec{v}\|$ to denote the length of \vec{v} to avoid confusion with absolute value $|x|$

Line integrals in \mathbb{R}^3 (\mathbb{R}^n) (path integrals)

Def 9: The line integral of a function f on a curve (path, line) C with parametrization

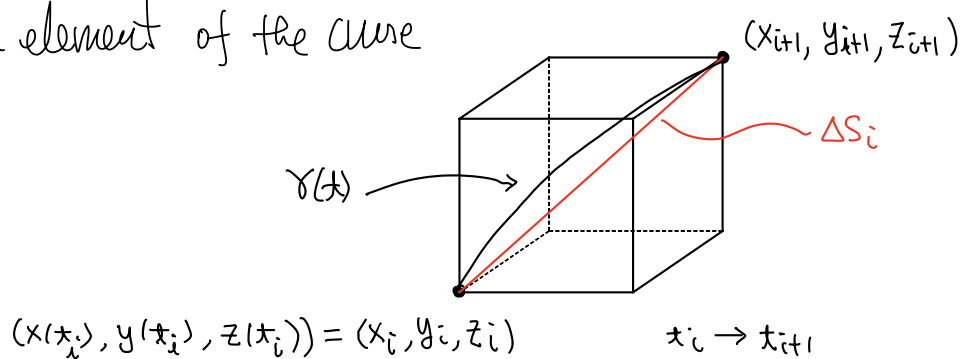
$$\begin{array}{ccc} \vec{r} : [a, b] & \longrightarrow & \mathbb{R}^3 \\ \text{(position vector)} & \psi & \psi \\ t & \longmapsto & (x(t), y(t), z(t)) \end{array}$$

is $\int_C f(\vec{r}) ds = \lim_{\|P\| \rightarrow 0} \sum_{i=1}^n f(\vec{r}(t_i)) \Delta S_i$

where P is a partition of $[a, b]$, and

$$\Delta S_i = \sqrt{(\Delta x_i)^2 + (\Delta y_i)^2 + (\Delta z_i)^2}$$

i.e. $ds =$ length element of the curve



Remarks:

(1) If $f \equiv 1$,

$$\int_C ds = \text{arc-length of } C$$

(2) The definition is well-defined, i.e. the RHS in the definition is independent of the parametrization $\vec{r}(t)$.

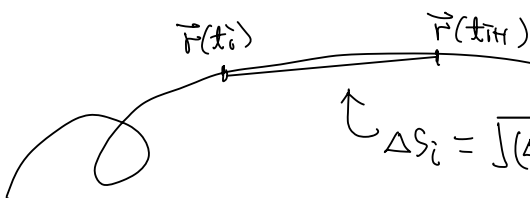
Def 9' (Formula for line integral)

Notations as in Def 9, then

$$\int_C f(\vec{r}) ds = \int_a^b f(\vec{r}(t)) \|\vec{r}'(t)\| dt$$

where $\vec{r}'(t) = (x'(t), y'(t), z'(t))$

Since



$$\Delta S_i = \sqrt{(\Delta x_i)^2 + (\Delta y_i)^2 + (\Delta z_i)^2}$$

$$= \sqrt{\left(\frac{\Delta x_i}{\Delta t_i}\right)^2 + \left(\frac{\Delta y_i}{\Delta t_i}\right)^2 + \left(\frac{\Delta z_i}{\Delta t_i}\right)^2} \Delta t_i$$

$$\cong \sqrt{x'(t_i)^2 + y'(t_i)^2 + z'(t_i)^2} \Delta t_i$$

$$= \|\vec{r}'(t_i)\| \Delta t_i$$

Remarks (1) " $ds = \|\vec{r}'(t)\| dt$ " is usually referred as the arc-length element,

where $\vec{r}(t) = (x'(t), y'(t), z'(t))$ and $\|\vec{r}'(t)\| = \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2}$.

(2) Suppose the curve C is parametrized by a new parameter \tilde{t}

$$\begin{array}{ccc} t & \longleftrightarrow & \tilde{t} \\ \uparrow & & \uparrow \\ [a, b] & & [\tilde{a}, \tilde{b}] \end{array} \quad \left(t \leftrightarrow \tilde{t} \text{ is increasing} \right.$$

$$\left. \frac{d\tilde{t}}{dt} > 0, \frac{dt}{d\tilde{t}} > 0 \right)$$

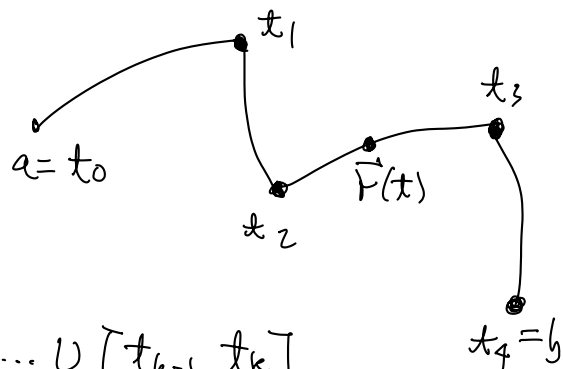
$$\begin{aligned} \text{then } ds &= \|\vec{r}'(t)\| dt = \left\| \frac{d\vec{r}}{dt}(t) \right\| dt \\ &= \left\| \frac{d\vec{r}}{d\tilde{t}} \cdot \frac{d\tilde{t}}{dt} \right\| dt = \left\| \frac{d\vec{r}}{d\tilde{t}} \right\| \left| \frac{d\tilde{t}}{dt} \right| dt = \left\| \frac{d\vec{r}}{d\tilde{t}} \right\| d\tilde{t} \end{aligned}$$

$\therefore ds$ and hence $\int_C f(\vec{r}) ds$ is independent of the parametrization of C .

(3) If $\vec{r}(t)$ is only piecewise differentiable,

then the RHS of Def 9'

becomes a sum :



$$\text{If } [a, b] = \underbrace{[t_0, t_1]}_a \cup \dots \cup [t_{i-1}, t_i] \cup \dots \cup [t_{k-1}, t_k] \underbrace{=}_b$$

non-differentiable point for $\vec{r}(t)$

such that $\vec{r} |_{[t_{i-1}, t_i]}$ is differentiable, then

$$\int_C f(\vec{r}) ds = \sum_{i=1}^k \int_{t_{i-1}}^{t_i} f(\vec{r}(t)) \|\vec{r}'(t)\| dt$$

eg 32: $f(x, y, z) = x - 3y^2 + z$

C = (straight) line segment joining the origin and $(1, 1, 1)$

Find $\int_C f(x, y, z) ds$

Soln: Parametrize C by

$$\begin{aligned}\vec{r}(t) &= (0, 0, 0) + t[(1, 1, 1) - (0, 0, 0)], \quad 0 \leq t \leq 1 \\ &= (t, t, t)\end{aligned}$$

(i.e. $x(t) = t, y(t) = t, z(t) = t$)

$$\Rightarrow \vec{r}'(t) = (1, 1, 1), \quad \forall t \in [0, 1]$$

$$\begin{aligned}\Rightarrow \int_C f(\vec{r}) ds &= \int_0^1 [x(t) - 3y(t)^2 + z(t)] \|\vec{r}'(t)\| dt \\ &= \int_0^1 (t - 3t^2 + t) \sqrt{3} dt = 0 \quad (\text{check!}) \neq\end{aligned}$$

eg33: let C be a curve in \mathbb{R}^2 (plane curve) (i.e. $z(t) \equiv 0$)
and it has 2 parametrizations

$$\vec{r}_1(t) = (\cos t, \sin t), \quad t \in [-\frac{\pi}{2}, \frac{\pi}{2}]$$

$$\vec{r}_2(t) = (\sqrt{1-t^2}, -t), \quad t \in [-1, 1]$$

Suppose $f(x,y) = x$. Find $\int_C f(x,y) ds$.

(We simply omit the z -variable, as C is a plane curve and f is indep. of z)

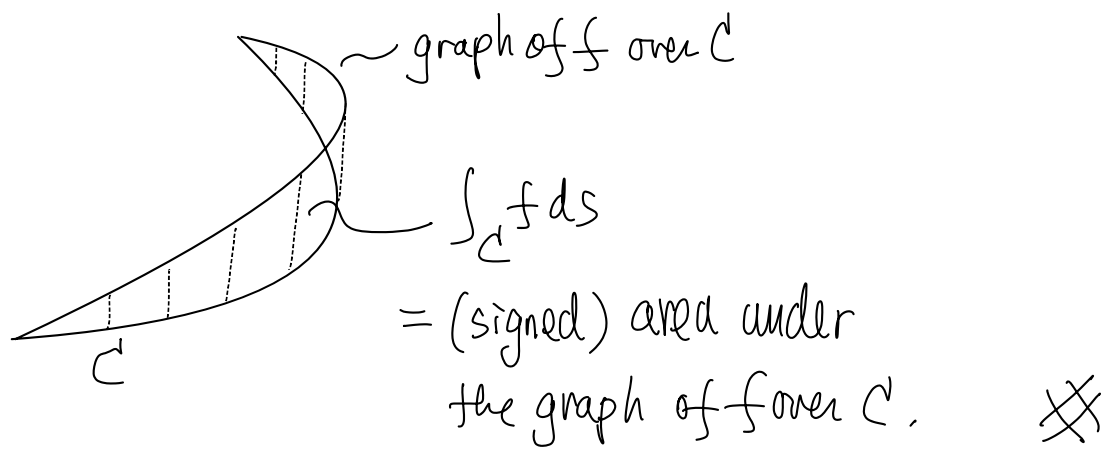
Soln: (1) $\vec{r}_1(t) = (\cos t, \sin t), \quad -\frac{\pi}{2} \leq t \leq \frac{\pi}{2}$

$$\begin{aligned} \int_C f(x,y) ds &= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos t \cdot \|(\cos t, \sin t)'\| dt \\ &= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos t dt = 2 \quad (\text{check!}) \end{aligned}$$

(2) $\vec{r}_2(t) = (\sqrt{1-t^2}, -t), \quad -1 \leq t \leq 1$

$$\begin{aligned} \int_C f(x,y) ds &= \int_{-1}^1 \sqrt{1-t^2} \sqrt{\left(\frac{d}{dt}\sqrt{1-t^2}\right)^2 + \left(\frac{d}{dt}(-t)\right)^2} dt \\ &= \dots = \int_{-1}^1 dt = 2 \quad (\text{check!}) \end{aligned}$$

This verifies the fact that the line integral is indep. of the parametrization. (Note: $\vec{r}_1(t)$ & $\vec{r}_2(t)$ are in opposite directions, see later discussion.)



Prop 7: If C is a piecewise smooth curve made by joining C_1, C_2, \dots, C_n end-to-end, then

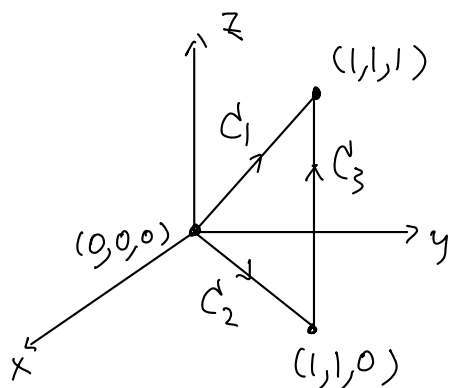
$$\int_C f ds = \sum_{i=1}^n \int_{C_i} f ds$$

(Pf: Clear from the remark (3) of Def 9', but C_i can be piecewise differentiable in this Prop.)

Remark: "end-to-end" means "end point of C_{k-1} = initial point of C_k ".

eg34: Let $f(x,y,z) = x - 3y^2 + z$ (again)

C_1, C_2, C_3 are (straight) line segments as in the figure



We already did $\int_{C_1} f ds = 0$ (eg32)

One can similarly calculate

$$\begin{aligned} \int_{C_2 \cup C_3} f ds &= \int_{C_2} f ds + \int_{C_3} f ds \\ &= -\frac{\sqrt{2}}{2} - \frac{3}{2} \quad (\text{Ex!}) \end{aligned}$$

(For instance, $\int_{C_3} f ds = \int_0^1 (1 - 3(1)^2 + t) dt$ (what parametrization?))

The observation is $\int_{C_1} f ds = 0 \neq \int_{C_2 \cup C_3} f ds$

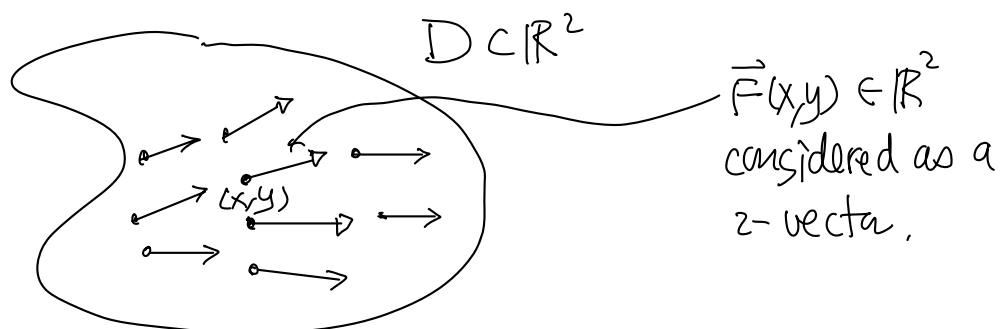
even C_1 & $C_2 \cup C_3$ have the same beginning and end points!

(Remark: different from 1-variable calculus)

Conclusion: Line integral of a function depends, not only on the end points, but also the path.

Vector Fields

Def 10 = Let $D \subset \mathbb{R}^2$ or \mathbb{R}^3 be a region, then a vector field on D is a mapping $\vec{F}: D \rightarrow \mathbb{R}^2$ or \mathbb{R}^3 respectively



In component form:

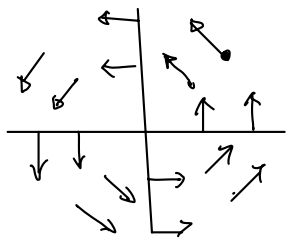
$$\mathbb{R}^2: \vec{F}(x, y) = M(x, y)\hat{i} + N(x, y)\hat{j}$$

$$\mathbb{R}^3: \vec{F}(x, y, z) = M(x, y, z)\hat{i} + N(x, y, z)\hat{j} + L(x, y, z)\hat{k}$$

where M, N, L are functions on D called the components of \vec{F} .

eg 35 $\vec{F}(x, y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2 + y^2}}$ on $\mathbb{R}^2 \setminus \{(0, 0)\}$

$$= -\sin\theta\hat{i} + \cos\theta\hat{j} \quad (\text{in polar coordinates})$$



Properties of \vec{F} : (i) $\|\vec{F}(x, y)\| = 1$

(ii) $\vec{F} \perp \vec{r}(x, y) = x\hat{i} + y\hat{j} = r(\cos\theta\hat{i} + \sin\theta\hat{j})$

eg36 (Gradient vector field of a function)

(i) $f(x,y) = \frac{1}{2}(x^2 + y^2)$

$$\vec{\nabla} f(x,y) \stackrel{\text{def}}{=} \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) = (x,y) = x\hat{i} + y\hat{j} = \vec{r}(x,y)$$

position vector field.

(ii) $f(x,y,z) = x$

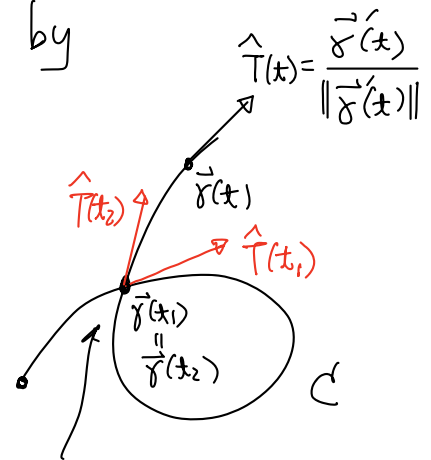
$$\vec{\nabla} f(x,y,z) \stackrel{\text{def}}{=} \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) = (1, 0, 0) = \hat{i}$$

(a constant vector field)

eg37 (Vector field along a curve)

Let C be a curve in \mathbb{R}^2 parametrized by

$$\begin{aligned} \vec{\gamma} &= [a,b] \rightarrow \mathbb{R}^2 \\ \downarrow & \quad \downarrow \\ t & \mapsto (x(t), y(t)) = \vec{\gamma}(t) \end{aligned}$$



Recall: $\hat{T} = \frac{\vec{\gamma}'(t)}{\|\vec{\gamma}'(t)\|}$

= unit tangent vector field along C (same point, but different vectors)

Note: this \hat{T} defined only on C (for a general curve), but not outside C .

(vector field along a curve may not come from a vector field) on a region.

Remark: for eg 37.

If we use $ds = \|\vec{r}'(t)\| dt$, then

$$\hat{T} = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{d\vec{r}}{ds} \quad \begin{array}{l} \text{(by Chain rule)} \\ \text{(if } s \text{ is a function of } t \text{)} \end{array}$$

where "arc-length s " is defined by

$$s(t) = \int_{t_0}^t \|\vec{r}'(t)\| dt, \quad \text{(up to an additive constant)}$$

A parametrization of a curve C by arc-length s is called arc-length parametrization:

$\vec{r}(s) =$ arc-length parametrization

$$\Rightarrow \left\| \frac{d\vec{r}}{ds}(s) \right\| = 1$$

Def 11 A vector field is defined to be continuous / differentiable / C^k if the component functions are.

eg 38:
 $\left\{ \begin{array}{l} \vec{F}(x,y) = \vec{r}(x,y) = x\hat{i} + y\hat{j} \text{ is } C^\infty \text{ (position vector)} \\ \vec{F}(x,y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2+y^2}} \text{ is not continuous in } \mathbb{R}^2 \\ \text{(but continuous in } \mathbb{R}^2 \setminus \{(0,0)\}) \end{array} \right.$

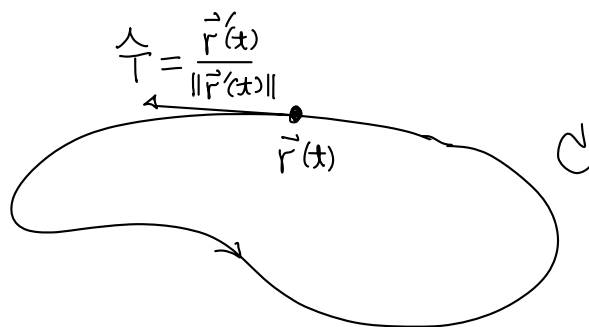
Line integral of vector field

Def 12: Let C be a curve with "orientation" given by a parametrization $\vec{r}(t)$ with $\vec{r}'(t) \neq 0, \forall t$. Define the line integral of a vector field \vec{F} along C to be

$$\int_C \vec{F} \cdot \hat{T} ds$$

where $\hat{T} = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$ is the unit tangent vector field along C .

i.e. C is oriented in the direction of $\vec{r}'(t)$ or \hat{T} at every point



Note: If $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ ($n=2$ or 3) then

$$\begin{aligned} \int_C \vec{F} \cdot \hat{T} ds &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \|\vec{r}'(t)\| dt \\ &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt \end{aligned}$$

$\xrightarrow{d\vec{r}}$

Abuse of notations:
 $\vec{r}(t) = \vec{r}(x(t), y(t)) = x(t)\hat{i} + y(t)\hat{j}$
because of the position vector field
 $\vec{F} = x\hat{i} + y\hat{j}$

\therefore naturally, we denote

$$d\vec{r} = \hat{T} ds$$

and

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r}$$

eg 38 : $\vec{F}(x,y,z) = z\hat{i} + xy\hat{j} - y^2\hat{k}$

$$C: \vec{r}(t) = t^2\hat{i} + t\hat{j} + \sqrt{t}\hat{k}, \quad 0 \leq t \leq 1$$

Soln $d\vec{r} = (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt$

$$\begin{aligned} \int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} \\ &= \int_0^1 (\sqrt{t}\hat{i} + t^2 \cdot t\hat{j} - t^2\hat{k}) \cdot (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt \\ &= \int_0^1 (2t\sqrt{t} + t^3 - \frac{t^2}{2\sqrt{t}}) dt = \frac{17}{20} \quad (\text{check!}) \\ &\quad \times \end{aligned}$$

In components form:

Line integral of $\vec{F} = M\hat{i} + N\hat{j}$ along

$$C: \vec{r}(t) = g(t)\hat{i} + h(t)\hat{j}$$

can be expressed as

$$\begin{aligned} \int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} = \int_a^b (\vec{F} \cdot \frac{d\vec{r}}{dt}) dt \\ &= \int_a^b (Mg' + Nh') dt \end{aligned}$$

$$\left(\text{more explicitly: } \int_a^b [M(g(t), h(t))g'(t) + N(g(t), h(t))h'(t)] dt \right)$$

$$\text{Note that, } \begin{cases} x = g(t) \\ y = h(t) \end{cases}$$

$$\Rightarrow \begin{cases} dx = g'(t) dt \\ dy = h'(t) dt \end{cases}$$

$$\therefore \int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_a^b M dx + N dy$$

Similarly, for 3-dim

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_a^b M dx + N dy + L dz$$

$$\left(\text{for } \vec{F} = M\hat{i} + N\hat{j} + L\hat{k} \right)$$

Another way to justify the notation:

$\vec{r} = (x, y, z)$ the position vector

$$\Rightarrow \boxed{d\vec{r} = (dx, dy, dz)} \quad (\text{natural notation})$$

$$\begin{aligned} \text{Then } \int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} = \int_C (M, N, L) \cdot (dx, dy, dz) \\ &= \int_C M dx + N dy + L dz. \end{aligned}$$

eg 39: Evaluate $I = \int_C -y dx + z dy + 2x dz$

where $C: \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j} + t \hat{k} \quad (0 \leq t \leq 2\pi)$
 $= (\cos t, \sin t, t)$

Soln

$$I = \int_0^{2\pi} (-\sin t d \cos t + t d \sin t + 2 \cos t dt)$$
$$= \int_0^{2\pi} (-\sin t \cdot (-\sin t) + t \cdot \cos t + 2 \cos t) dt$$
$$= \dots = \pi \quad (\text{check!}) \quad \times$$

$$(d\vec{r} = (-\sin t, \cos t, 1) dt \quad \& \quad \vec{r}'(t) = (-\sin t, \cos t, 1))$$