

Remark: To prove Thm 10 in \mathbb{R}^2 , we need the Green's Thm
 (in \mathbb{R}^3 , we need the Stokes' Thm)

Thm 11 (Green's Theorem)

Let $\Omega \subseteq \mathbb{R}^2$ be open, $\vec{F} = M\hat{i} + N\hat{j}$ be C^1 vector field on Ω ;
 C be a piecewise "smooth" simple closed anti-clockwise oriented
 curve enclosing a region R which lies entirely in Ω .

Then • Normal Form

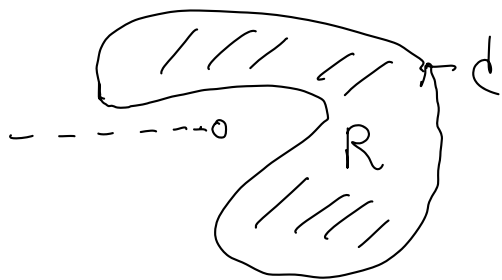
$$\oint_C \vec{F} \cdot \hat{n} ds = \oint_C M dy - N dx = \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx dy$$

• Tangential Form

$$\oint_C \vec{F} \cdot \hat{T} ds = \oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

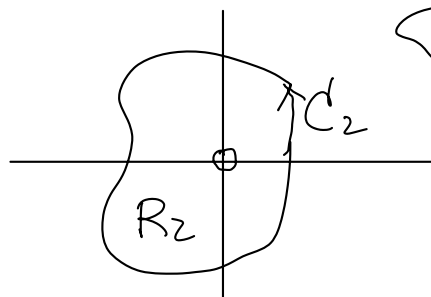
(Remark: The two forms are equivalent.)

Note: $\Omega_1 = \mathbb{R}^2 \setminus \{x \leq 0\}$



Green's Thm applies,
 since $R \subset \Omega_1$

$\Omega_2 = \mathbb{R}^2 \setminus \{(0,0)\}$



C_1
 Green's Thm
 applies,
 since $R_1 \subset \Omega_2$

$(0,0) \in R_2$, but $(0,0) \notin \Omega_2$

$\Rightarrow R_2 \not\subset \Omega_2$,

Green's Thm doesn't apply.

eg 48 Verify both forms of Green's Thm for

$$\vec{F}(x,y) = (x-y)\hat{i} + x\hat{j} \quad \text{on } \Omega = \mathbb{R}^2, \quad \text{is } C^\infty.$$

$$C = \text{unit circle} = \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}, \quad t \in [0, 2\pi]$$

Then $R =$ region enclosed by $C = \{x^2 + y^2 < 1\}$ the unit disc.

(We also write $C = \partial R$ boundary of R)

Soln $M = x - y, \quad N = x$

$$\frac{\partial M}{\partial x} = 1, \quad \frac{\partial M}{\partial y} = -1; \quad \frac{\partial N}{\partial x} = 1, \quad \frac{\partial N}{\partial y} = 0$$

On C , $x = \cos t, \quad y = \sin t, \quad t \in [0, 2\pi]$

Normal form $\text{L.H.S.} = \oint_C M dy - N dx$

$$= \int_0^{2\pi} (\cos t - \sin t) d(\sin t) - \cos t d(\cos t)$$

$$= \int_0^{2\pi} \cos^2 t dt = \pi \quad (\text{check!})$$

$$\text{RHS} = \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx dy = \iint_R (1 + 0) dx dy = \pi$$

Tangential form $\text{L.H.S.} = \oint_C M dx + N dy = 2\pi \quad (\text{check!})$

$$\text{R.H.S.} = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy = \iint_R (1 - (-1)) dx dy = 2\pi$$

(Note: This example shows that even the 2 forms are equivalent, the values involved may differ.)

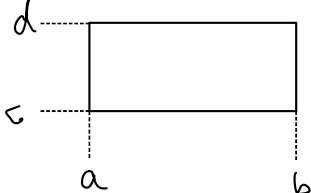
Pf of Green's Thm (tangential form)

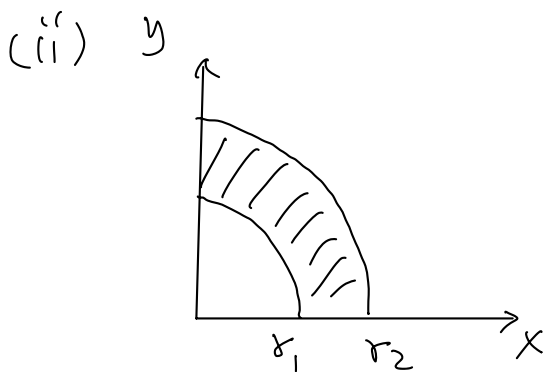
Recall: A region R is of special type:

type (1) = If $R = \{(x,y) = a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$
for some continuous functions $g_1(x)$ & $g_2(x)$.

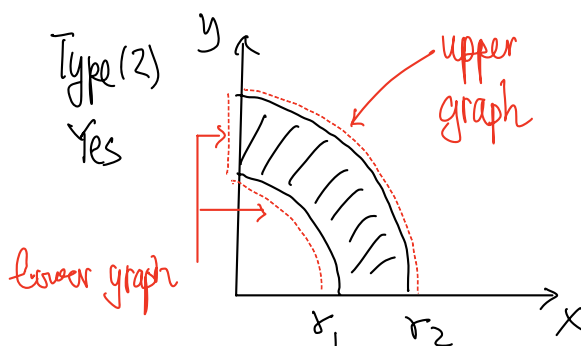
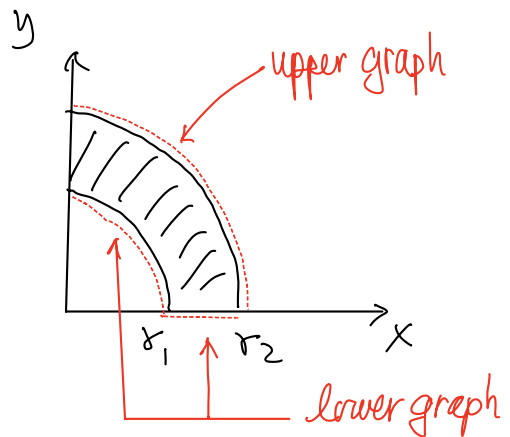
type (2) = If $R = \{(x,y) = h_1(y) \leq x \leq h_2(y), c \leq y \leq d\}$
for some continuous functions $h_1(x)$ & $h_2(x)$.

Now: If R is both type (1) and type (2), it said
to be simple.

eg 4.8: (i)  rectangle is simple

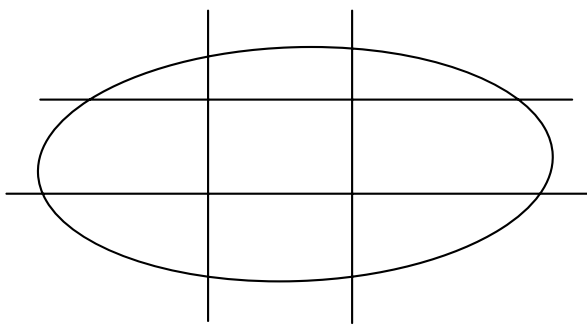


Type (1)
Yes



\Rightarrow simple region

(iii)



2 intersections at most

2 intersections at most

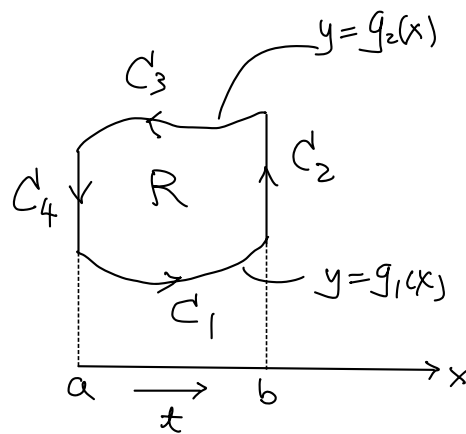
$$\left. \begin{aligned} \forall a \in \mathbb{R}: \# \{ \partial R \cap \{x=a\} \} &\leq 2 \\ \# \{ \partial R \cap \{y=a\} \} &\leq 2 \end{aligned} \right\} \Rightarrow \text{simple} \\ \left(\text{provided } \partial R \text{ is piecewise smooth} \right).$$

(Proof: omitted)

Pf of Green's Thm for Simple Region

By definition, R is of type (1) and can be written as

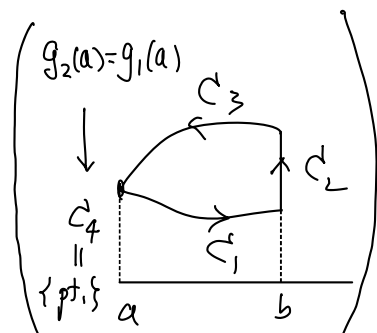
$$R = \{ (x,y) : a \leq x \leq b, g_1(x) \leq y \leq g_2(x) \}$$



Let denote the components of the boundary

of R by $C_1, C_2, C_3,$ and C_4 as in the figure

(Note: C_2 and/or C_4 could just be a point)



Then $\partial R = C_1 + C_2 + C_3 + C_4$ as oriented curve

(using "+" instead of "U" to denote the orientation)

Now $C_1 = \{y = g_1(x)\}$ can be parametrized by

$(x, y): \vec{r}(t) = (t, g_1(t)), a \leq t \leq b$ (with correct orientation)

$$\therefore \int_{C_1} M dx = \int_a^b M(t, g_1(t)) dt$$

Similarly " $-C_3$ " can be parametrized by

$\vec{r}(t) = (t, g_2(t)), a \leq t \leq b$ (with correct orientation)

$$\therefore \int_{-C_3} M dx = \int_a^b M(t, g_2(t)) dt$$

$$\Rightarrow \int_{C_3} M dx = - \int_{-C_3} M dx = - \int_a^b M(t, g_2(t)) dt$$

For $C_2 = \{x = b\}$, it can be parametrized by

$\vec{r}(t) = (b, t), g_1(b) \leq t \leq g_2(b)$ (with correct orientation)

$$\Rightarrow \int_{C_2} M dx = 0 \quad (\text{since } \frac{dx}{dt} = 0)$$

Similarly $\int_{C_4} M dx = - \int_{-C_4} M dx = 0$

Hence $\oint_{\partial R} M dx = \sum_{i=1}^4 \int_{C_i} M dx$

$$= \int_a^b [M(t, g_1(t)) - M(t, g_2(t))] dt$$

$$\left(= \int_a^b [M(x, g_1(x)) - M(x, g_2(x))] dx \right) \quad (\text{To be cont'd})$$