

Regular surfaces

Definition

A subset $M \subset \mathbb{R}^3$ is said to be a *regular surface* if for any $p \in M$, there is an open neighborhood U of p in M , an open set D in \mathbb{R}^2 and a map $\mathbf{X} : D \rightarrow M \cap U$ such that the following are true:

- (rs1) \mathbf{X} is *smooth*.
- (rs2) $d\mathbf{X}$ is *full rank*: $\mathbf{X}_u = \frac{\partial \mathbf{X}}{\partial u}$ and $\mathbf{X}_v = \frac{\partial \mathbf{X}}{\partial v}$ are linearly independent, for any $(u, v) \in D$.
- (rs3) \mathbf{X} is a *homeomorphism from D onto $M \cap U$* . (That is: \mathbf{X} is bijective, \mathbf{X} and \mathbf{X}^{-1} are continuous).

Regular surfaces, cont.

- Let M be a regular surface, a map $\mathbf{X} : D \rightarrow V$ where V is an open set of M , satisfying the above conditions.
- \mathbf{X} is called a *parametrization*, and V is called a *coordinate chart (patch, neighborhood)*.
- If $\mathbf{X}(u, v) = p$, then (u, v) are called *local coordinates* of p .
- So a regular surface is a set M in \mathbb{R}^3 which can be covered by a family of coordinate charts.

Example 1: graphs, $z = f(x, y)$

Graphs: Let $M = \{(x, y, z) \mid z = f(x, y), (x, y) \in D \subset \mathbb{R}^2\}$. Then M can be covered by a coordinate chart. We can take $U = D \times \mathbb{R}$. $\mathbf{X}(u, v) = (u, v, f(u, v))$ with $(u, v) \in D$. Check:

- (rs1) \mathbf{X} is smooth.
- (rs2) $d\mathbf{X}$ is full rank: $\mathbf{X}_u = (1, 0, f_u)$ and $\mathbf{X}_v = (0, 1, f_v)$ are linearly independent, for any $(u, v) \in U$.
- (rs3) \mathbf{X} is a homeomorphism from D onto $M \cap U = M$. (That is: \mathbf{X} is bijective, \mathbf{X} and \mathbf{X}^{-1} are continuous) (Why?).

Graphs are regular surfaces

So we have:

Proposition

Let $f : D \rightarrow \mathbb{R}$ be a smooth function on an open set $D \subset \mathbb{R}^2$.

Then the graph of f defined by the following is a regular surface:

$$\text{graph}(f) = \{(x, y, f(x, y)) \mid (x, y) \in D\}.$$

Example 2: Unit sphere, $\{x^2 + y^2 + z^2 = 1\}$

Unit sphere: $\mathbb{S}^2 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$. Take a point p in the northern (open) hemisphere. Let $U = \{z > 0\}$.
 $D = \{u^2 + v^2 < 1\}$. Let

$$\mathbf{X}(u, v) = (u, v, \sqrt{1 - u^2 - v^2}).$$

How many similar coordinate charts will cover \mathbb{S}^2 ?

Spherical coordinates

Consider another parametrization.

$$\mathbf{X}(\theta, \varphi) = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$$

with $\{(\theta, \varphi) \mid 0 < \theta < \pi, 0 < \varphi < 2\pi\}$. Then

$$\mathbf{X}_\theta = (\cos \theta \cos \varphi, \cos \theta \sin \varphi, -\sin \theta); \mathbf{X}_\varphi = (-\sin \theta \sin \varphi, \sin \theta \cos \varphi, 0).$$

How many similar coordinate charts will cover \mathbb{S}^2 ?

Stereographic projection

There is still another important parametrization, the **Stereographic projection**. The unit sphere M is considered as the set $x^2 + y^2 + (z - 1)^2 = 1$.

$$\pi : M \setminus \{(0, 0, 2)\} = N \rightarrow \mathbb{R}^2$$

so that $N, p, \pi(p)$ are on a straight line. Then $\mathbf{X} : \mathbb{R}^2 \rightarrow M \setminus \{N\}$ is a coordinate chart.

$$\mathbf{X}(u, v) = \left(\frac{4u}{u^2 + v^2 + 4}, \frac{4v}{u^2 + v^2 + 4}, \frac{2(u^2 + v^2)}{u^2 + v^2 + 4} \right).$$

Regular surfaces are graphs locally

Proposition

Let M be regular surface and let $\mathbf{X} : U \rightarrow M$ be a coordinate parametrization. Then for any $p = (u_0, v_0) \in U$ there is a open set $V \subset U$ with $p \in V$ such that $\mathbf{X}(V)$ is a graph over an open set in one of the coordinate plane.

Review on inverse function theorem

Let $F : U \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a smooth map from an open set U to \mathbb{R}^m , $F(\mathbf{x}) = \mathbf{y}(\mathbf{x}) = (y^1, \dots, y^m)$ where $\mathbf{x} = (x^1, \dots, x^n)$, $\mathbf{y} = (y^1, \dots, y^m)$. Let $\mathbf{x}_0 = (x_0^1, \dots, x_0^n) \in U$. The Jacobian matrix of F at \mathbf{x}_0 is the $m \times n$ matrix

$$dF_{\mathbf{x}_0} = \left(\frac{\partial y^i}{\partial x^j}(\mathbf{x}_0) \right).$$

Theorem

(Inverse Function Theorem) Let $F : U \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a smooth map. Suppose $F(\mathbf{x}_0) = \mathbf{y}_0$ and $dF_{\mathbf{x}_0}$ is nonsingular. Then there exist open sets $U \supset V \ni \mathbf{x}_0$ and $W \ni \mathbf{y}_0$, such that F is a diffeomorphism from V to W . That is to say, $F : V \rightarrow W$ is bijective and F^{-1} is also smooth on W .

Proof of the inverse function theorem

Proof:

- May assume that $\mathbf{x}_0 = \mathbf{0} = \mathbf{y}_0$. Let $A = dF_{\mathbf{x}_0}$.
- Then

$$F(\mathbf{x}) = A\mathbf{x} + G(\mathbf{x}),$$

$$G(\mathbf{x}_1) - G(\mathbf{x}_2) = o(|\mathbf{x}_1 - \mathbf{x}_2|) \text{ as } \mathbf{x}_1, \mathbf{x}_2 \rightarrow \mathbf{0}.$$

- Hence for any $\epsilon > 0$, we can find $\delta > 0$ such that if $\mathbf{x}_1, \mathbf{x}_2 \in B(\mathbf{0}, \delta) = \{|\mathbf{x}| < \delta\}$, we have ,

$$|F(\mathbf{x}_1) - F(\mathbf{x}_2)| \geq |A(\mathbf{x}_1 - \mathbf{x}_2)| - \epsilon|\mathbf{x}_1 - \mathbf{x}_2|$$

- From this we conclude that F is one-one in $B(\mathbf{0}, \delta)$ if $\epsilon > 0$ is small enough.

Proof (cont.)

- Let $\mathbf{y}_1 \in \mathbb{R}^n$. Want to find \mathbf{x} so that $F(\mathbf{x}) = A\mathbf{x} + G(\mathbf{x}) = \mathbf{y}_1$.
- $\exists \mathbf{x}_1, A\mathbf{x}_1 = \mathbf{y}_1$. (?) Inductively, $\exists \mathbf{x}_{n+1}$ with $A\mathbf{x}_{n+1} = \mathbf{y}_1 - G(\mathbf{x}_n)$.
- There is $\rho > 0$ such that if $|\mathbf{y}_1| < \rho$, then $\mathbf{x}_n \in B(\mathbf{0}, \frac{1}{4}\delta)$ and $\mathbf{x}_n \rightarrow \mathbf{x} \in \overline{B(\mathbf{0}, \frac{1}{2}\delta)} \subset B(\mathbf{0}, \delta)$. (Why?)

Idea of proof: Regular surfaces are graphs

Proof:

(Sketch) Let $\mathbf{X}(u, v) = (x(u, v), y(u, v), z(u, v))$. May assume that at (u_0, v_0)

$$\det \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \neq 0.$$

Let $(x_0, y_0) = (x(u_0, v_0), y(u_0, v_0))$. By the inverse function theorem, there is a nbh of U_1 of (u_0, v_0) and W of (x_0, y_0) so that $(u, v) \rightarrow (x, y)$ has a smooth inverse. Then the image of U_1 under \mathbf{X} is of the form

$$\begin{aligned} (x, y) &\rightarrow (u(x, y), v(x, y)) \\ &\rightarrow (x(u(x, y)), y(u(x, y)), z(u(x, y), v(x, y))) \\ &= (x, y, f(x, y)). \end{aligned}$$

Regular value of a function

Proposition

Let U be an open set in \mathbb{R}^3 and let $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ be a smooth function. Suppose a is a regular value of f . (That is: if $f(x, y, z) = a$, then $\nabla f(x) \neq \mathbf{0}$.) Then

$$M = \{(x, y, z) \in U \mid f(x) = a\}$$

is a regular surface.

Examples: Quadratic surfaces

The unit sphere is given by $\{f = 1\}$ with $f(x, y, z) = x^2 + y^2 + z^2$.
 $\nabla f = (2x, 2y, 2z)$ which is not zero if $f = 1$. So 1 is a regular value.

In general: Quadric surfaces.

Proof of level sets of regular values are regular surfaces

Proof:

(Sketch) Let $(x_0, y_0, z_0) \in M$. May assume that $f_z \neq 0$ at this point. Consider the map: $F : U \rightarrow \mathbb{R}^3$ defined by $F(x, y, z) = (x, y, f(x, y, z))$. Then the Jacobian matrix is invertible at $p = (x_0, y_0, z_0)$. Let $F(x_0, y_0, z_0) = (u_0, v_0, t_0) = q$, with $t_0 = a$. Then there exist nbh V of p and W of q so that F has a smooth inverse F^{-1} . Now $F^{-1}(u, v, t) = (u, v, g(u, v, t))$. Let $W_1 = \{(u, v) | (u, v, a) \in W\}$. Then for $(x, y, z) \in V \cap M$, $F(x, y, z) = (x, y, a) = (u, v, g(u, v, a))$ and so this set is the graph of over (u, v) .

Surfaces of revolution

Let $\alpha(t)$ be a regular curve in the yz -plane given by

$$\alpha(u) = (0, y(u), z(u))$$

so that $x(t) > 0$. Consider the surface given by

$$\mathbf{X}(u, v) = (y(u) \cos v, y(u) \sin v, z(u)).$$

Then

$$\mathbf{X}_u = (y' \cos v, y' \sin v, z'); \mathbf{X}_v = (-y \sin v, y \cos v, 0).$$

Torus

Rotating a circle $(y - a)^2 + z^2 = r^2$ about the z -axis, $a > r > 0$.

$$\mathbf{X}(u, v) = ((r \cos u + a) \cos v, (r \cos u + a) \sin v, r \sin u).$$

$$0 < u < 2\pi, 0 < v < 2\pi$$

$$z^2 + (\sqrt{x^2 + y^2} - a)^2 = r^2.$$

Let $f = z^2 + (\sqrt{x^2 + y^2} - a)^2$, then

$$\nabla f = 2\left(\frac{x(\sqrt{x^2 + y^2} - a)}{\sqrt{x^2 + y^2}}, \frac{y(\sqrt{x^2 + y^2} - a)}{\sqrt{x^2 + y^2}}, z\right)$$

Then ∇f is smooth (why?) and r^2 is a regular value of f (why?).