

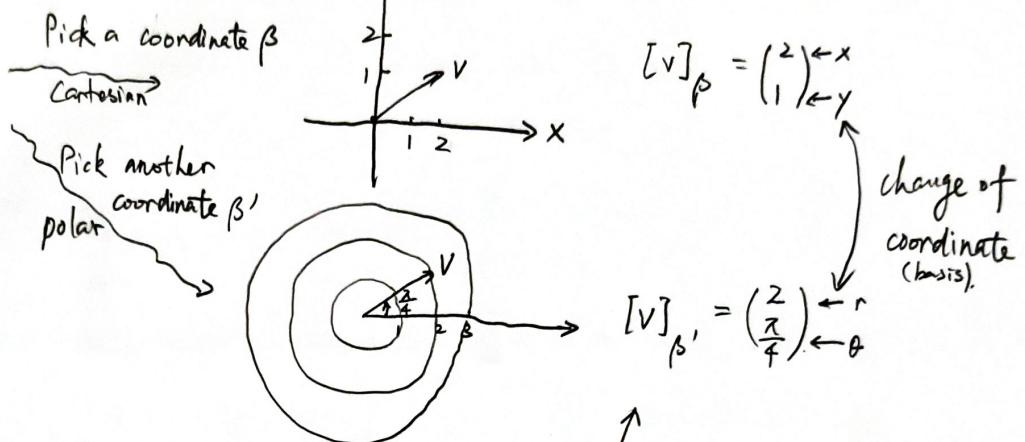
§4 Matrix Representation of Linear Maps. Change of Basis

This section reduces 2040 to 1030 by a process called "choosing a basis"

Coordinate free

(i) Vector spaces

$$\begin{array}{c} v \\ \nearrow \\ o \\ \searrow \\ v \in V \end{array}$$



independent of coordinate
 \uparrow essential information of an object
 2040

one representation of an object.
 1030

(ii) Linear maps

$$V \xrightarrow{T} W = V$$

$$\begin{array}{c} v \\ \nearrow \\ y \\ \searrow \\ T_v \end{array}$$

Reflection by dotted line.

Independent of coordinate

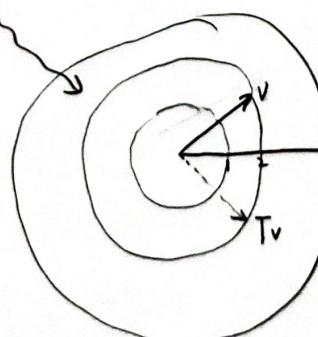
\uparrow
 essential information of a linear map

2040

Pick a basis α for V , β for W

$$\begin{array}{c} v \\ \nearrow \\ y \\ \searrow \\ T_v \end{array}$$

Pick another basis α' for V and β' for W



$$\text{Choose } \alpha = \beta = \{x, y\}.$$

$$[v]_{\alpha} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, [T_v]_{\beta} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\begin{aligned} T \text{ maps } & \begin{pmatrix} 1 \\ 1 \end{pmatrix}_{\alpha} \text{ to } \begin{pmatrix} 1 \\ -1 \end{pmatrix}_{\beta} \\ \Rightarrow [T]_{\alpha}^{\beta} &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \end{aligned}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}_{\alpha} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}_{\beta}$$

change of coordinate (basis)

one representation of an object.
 1030

Choose polar coordinate $\alpha' = \beta' = \{r, \theta\}$.

$$[v]_{\alpha'} = \left(\sqrt{2}, \frac{\pi}{4} \right)$$

$$[T_v]_{\beta'} = \left(\sqrt{2}, -\frac{\pi}{4} \right)$$

$$T \text{ maps } \left(\frac{\sqrt{2}}{4} \right)_{\alpha'} \text{ to } \left(-\frac{\sqrt{2}}{4} \right)_{\beta'}$$

$$\Rightarrow [T]_{\alpha'}^{\beta'} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \sqrt{2} \\ \frac{\pi}{4} \end{pmatrix}_{\alpha'} = \begin{pmatrix} \sqrt{2} \\ -\frac{\pi}{4} \end{pmatrix}_{\beta'}$$

$$[T]_{\alpha'}^{\beta'} [v]_{\alpha'} = [T_v]_{\beta'}$$

$$\begin{matrix} (1,0) & (0,1) \\ \uparrow & \uparrow \\ \theta \in \mathbb{R}/2\pi\mathbb{Z} & \frac{\pi}{4} - \frac{\pi}{4} \end{matrix}$$

Throughout this tutorial, we denote

V, W are finite dimension vector space over \mathbb{F} .
 we don't have $\infty \times \infty$ matrices.

$T: V \rightarrow W$ is a linear map.

By a basis we mean an ordered basis, i.e., the order matters. (e.g. $\{e_1, e_2\} \neq \{e_2, e_1\}$ as basis).

Def. 4.1 (coordinate vector). $\dim V$

Choose a basis $\beta = \{e_1, \dots, e_n\}$ for V . Then for any $v \in V$.

$$v = \sum_{i=1}^n v_i e_i = (e_1, e_2, \dots, e_n) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

Write $[v]_\beta = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$ called coordinate vector of v with respect to (w.r.t) basis β .

Remark. (i) This is well-defined as the linear combination exist and unique (because of basis).

(ii). This defines a natural map $[]_\beta : V \rightarrow \mathbb{F}^n$

$$v \mapsto [v]_\beta = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}.$$

Every choice of basis gives rise to a map $V \rightarrow \mathbb{F}^n$.

Def. 4.2. (matrix representation).

For $T: V \rightarrow W$. Choose a basis $\alpha = \{e_1, \dots, e_n\}$ for V and
 a basis $\beta = \{e'_1, \dots, e'_m\}$ for W .
 $\dim V$ $\dim W$ (n may not be equal to m).

Then we can represent T by a matrix $[T]_\alpha^\beta \in A$ defined by.

$$A_{ij} = ([T e_j]_\beta)_i, \quad \text{or} \quad A = \left(\begin{array}{c|c|c|c} [Te_1]_\beta & [Te_2]_\beta & \cdots & [Te_n]_\beta \\ \hline 1 & 1 & \cdots & 1 \end{array} \right), \quad \text{or}$$

$$Te_j = A_{1j} e'_1 + A_{2j} e'_2 + \cdots + A_{mj} e'_m = (e'_1, e'_2, \dots, e'_m) \begin{pmatrix} A_{1j} \\ A_{2j} \\ \vdots \\ A_{mj} \end{pmatrix}$$

Eg. 4.3 $T: \mathbb{F}^2 \rightarrow \mathbb{F}^3$, $(x, y) \mapsto (x+3y, 2x+5y, 7x+9y)$.

(i) If we choose standard basis $\alpha = \{(1, 0), (0, 1)\}$ for \mathbb{F}^2 , $\beta = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ for \mathbb{F}^3 .

$$\text{then } T(1, 0) = 1 \cdot (1, 0, 0) + 2 \cdot (0, 1, 0) + 7 \cdot (0, 0, 1) \in \mathbb{F}^3, [T(1, 0)]_\beta = \begin{pmatrix} 1 \\ 2 \\ 7 \end{pmatrix}$$

$$T(0, 1) = 3 \cdot (1, 0, 0) + 5 \cdot (0, 1, 0) + 9 \cdot (0, 0, 1) \in \mathbb{F}^3, [T(0, 1)]_\beta = \begin{pmatrix} 3 \\ 5 \\ 9 \end{pmatrix}$$

$$\therefore [T]_\alpha^\beta = \begin{pmatrix} 1 & 3 \\ 2 & 5 \\ 7 & 9 \end{pmatrix}.$$

(ii). If we choose a basis $\alpha' = \{(1,2), (2,-1)\}$ of \mathbb{F}^2 and $\beta' = \beta = \{(1,0,0), (0,1,0), (0,0,1)\}$ for \mathbb{F}^3

Then

$$T(1,2) = T(1,0,0) + 12(0,1,0) + 25(0,0,1) \rightsquigarrow [T(1,2)]_{\beta'} = \begin{pmatrix} 7 \\ 12 \\ 25 \end{pmatrix}$$

$$T(2,-1) = (-1)(1,0,0) + (-1)(0,1,0) + 5(0,0,1) \rightsquigarrow [T(2,-1)]_{\beta'} = \begin{pmatrix} -1 \\ -1 \\ 5 \end{pmatrix}$$

$$\text{so } [T]_{\alpha'}^{\beta'} = \begin{pmatrix} 7 & -1 \\ 12 & -1 \\ 25 & 5 \end{pmatrix}$$

(iii) What if switch order?

If we choose $\alpha'' = \alpha' = \{(1,2), (2,-1)\}$ for \mathbb{F}^2 , and $\beta'' = \{(0,0,1), (0,1,0), (1,0,0)\}$ for \mathbb{F}^3 .

Then

$$T(1,2) = 25(0,0,1) + 12(0,1,0) + T(1,0,0) \rightsquigarrow [T(1,2)]_{\beta''} = \begin{pmatrix} 25 \\ 12 \\ 1 \end{pmatrix}$$

$$T(2,-1) = 5(0,0,1) + (-1)(0,1,0) + (-1)(1,0,0) \rightsquigarrow [T(2,-1)]_{\beta''} = \begin{pmatrix} 5 \\ -1 \\ -1 \end{pmatrix}$$

$$\text{so } [T]_{\alpha''}^{\beta''} = \begin{pmatrix} 25 & 5 \\ 12 & -1 \end{pmatrix}. \quad \text{Note that } [T]_{\alpha''}^{\beta''} \neq [T]_{\alpha'}^{\beta'}$$

Ex: (i) $[T_1 \cdot T_2]_{\alpha}^{\beta} = [T_1]_{\alpha}^{\beta} [T_2]_{\alpha}^{\beta}$ (ii) $[T^{-1}]_{\beta}^{\alpha} = ([T]_{\alpha}^{\beta})^{-1}$ if T is invertible. (iii) $[T]_{\alpha}^{\beta} [v]_{\alpha}^{\beta} \xrightarrow{\text{written vertically}} [Tv]_{\beta}$.

Change of basis

Q: Is there a systematic way to choose a basis so that $[T]_{\alpha}^{\beta}$ is $\begin{pmatrix} I & 0 \\ 0 & 0 \end{pmatrix}$?

In particular, if $\dim V = \dim W$, is there a way to make $[T]_{\alpha}^{\beta}$ diagonal?

Ans: Consider the commutative diagram

$$\begin{array}{ccccccc}
 V & \xrightarrow[\cong]{I_V} & V & \xrightarrow{T} & W & \xrightarrow[\cong]{I_W} & W \\
 \downarrow [I_V]_{\alpha_0} & & \downarrow [T]_{\alpha} & & \downarrow [T]_{\beta} & & \downarrow [I_W]_{\beta_0} \\
 \mathbb{F}^n & \xrightarrow{[I_V]_{\alpha_0}^{\alpha}} & \mathbb{F}^n & \xrightarrow{[T]_{\alpha}^{\beta}} & \mathbb{F}^m & \xrightarrow{[I_W]_{\beta_0}^{\beta}} & \mathbb{F}^m
 \end{array}$$

Eg 4.3. (Cont'd). $T(x, y) = (x+3y, 2x+5y, 7x+9y)$. $\alpha = \{(1, 0), (0, 1)\}$. $\beta = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$.

$$\begin{array}{ccccccc}
 & & \text{canonical embedding in first 2 coordinates.} & & & & \\
 V & \xrightarrow{\text{id}} & V & \xrightarrow{T} & W & \xrightarrow{\text{id}} & W \\
 \downarrow []_{\alpha_0} & & \downarrow []_{\alpha} & & \downarrow []_{\beta} & & \downarrow []_{\beta_0} \\
 \mathbb{F}^n & \xrightarrow{[Id]_{\alpha_0}^{\alpha}} & \mathbb{F}^n & \xrightarrow{[T]_{\alpha}^{\beta}} & \mathbb{F}^m & \xrightarrow{[Id]_{\beta_0}^{\beta}} & \mathbb{F}^m \\
 \left(\begin{matrix} -5 & 3 \\ 2 & -1 \end{matrix} \right) & & \left(\begin{matrix} 1 & 3 \\ 2 & 5 \\ 7 & 9 \end{matrix} \right) & & \left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right) & &
 \end{array}$$

$[T]_{\alpha_0}^{\beta_0} = \left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right)$

column operations.

First: $\left(\begin{matrix} 1 & 3 \\ 2 & 5 \\ 7 & 9 \end{matrix} \right) \left(\begin{matrix} 1 & 3 \\ 2 & 5 \end{matrix} \right)^{-1} = \left(\begin{matrix} 1 & 0 \\ 0 & 1 \end{matrix} \right)$

row operations $\left(\begin{matrix} -5 & 3 \\ 2 & -1 \end{matrix} \right)$

Second: $\left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right) \left(\begin{matrix} 1 & 0 \\ 0 & 1 \end{matrix} \right) = \left(\begin{matrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{matrix} \right)$

so $\left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right) \left(\begin{matrix} 1 & 3 \\ 2 & 5 \\ 7 & 9 \end{matrix} \right) \left(\begin{matrix} -5 & 3 \\ 2 & -1 \end{matrix} \right) = \left(\begin{matrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{matrix} \right)$.

We try to find α_0 so that $[I_V]_{\alpha_0}^{\alpha} = \left(\begin{matrix} -5 & 3 \\ 2 & -1 \end{matrix} \right)$ let $\alpha_0 = \{e_1, e_2\}$.

$$\begin{array}{l}
 [Id]_{\alpha_0}^{\alpha} ([e_1]_{\alpha_0}, [e_2]_{\alpha_0}) = ([Id(e_1)]_{\alpha}, [Id(e_2)]_{\alpha}) = \left(\begin{matrix} 1 \\ 1 \end{matrix} \right) = \left(\begin{matrix} 1 \\ e_1 \\ e_2 \end{matrix} \right) \text{ as } \alpha \text{ is the standard basis.} \\
 \text{Id!!!}
 \end{array}$$

Hence $e_1 = (-5, 2)$, $e_2 = (3, -1)$.

We try to find β_0 so that $[Id]_{\beta}^{\beta_0} = \left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right) \Rightarrow [Id]^{\beta} \beta_0 = \left(\begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \right) = ([Id]_{\beta}^{\beta_0})^{-1}$. Let $\beta_0 = \{e'_1, e'_2, e'_3\}$.

$$\begin{array}{l}
 [Id]^{\beta} \beta_0 \left([e'_1]_{\beta_0}, [e'_2]_{\beta_0}, [e'_3]_{\beta_0} \right) = \left([Id(e'_1)]_{\beta}, [Id(e'_2)]_{\beta}, [Id(e'_3)]_{\beta} \right) = \left(\begin{matrix} 1 \\ 1 \\ 1 \end{matrix} \right) \\
 \text{Id!!!}
 \end{array}$$

as β is standard basis
and $Id^{\beta}(e_i) = e'_i$

Hence $e'_1 = (1, 0, -1)$, $e'_2 = (0, 1, 12)$, $e'_3 = (0, 0, 1)$

You may check $[T]_{\alpha_0}^{\beta_0} = \left(\begin{matrix} 1 & 0 \\ 0 & 1 \end{matrix} \right)$ under these basis, our calculation is right.

Remark: Actually in definition of T , (x, y) means $x \cdot (1, 0) + y \cdot (0, 1)$ so we can view it to be coordinates w.r.t. standard basis..

Q. Why do we define

$$[T]_{\alpha}^{\beta} = \left(\begin{array}{c|c} [Te_1]_{\beta} & [Te_n]_{\beta} \\ \hline | & | \end{array} \right) ? \quad \alpha = \{e_1, \dots, e_n\}, \beta = \{e'_1, \dots, e'_m\}$$

Ans. We want

$$[Tv]_{\beta} = [T]_{\alpha}^{\beta} [v]_{\alpha}.$$

$$\text{Indeed, } v = \sum_{i=1}^n v_i e_i = (e_1, \dots, e_n) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

$$\begin{aligned} Tv &= \sum_{i=1}^n v_i Te_i = (Te_1, \dots, Te_n) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \\ &= (e'_1, \dots, e'_m) \underbrace{\left(\begin{array}{c|c} [Te_1]_{\beta} & [Te_n]_{\beta} \\ \hline | & | \end{array} \right)}_{\text{not yet defined}} \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \end{aligned}$$

Hence we define $\left(\begin{array}{c|c} [Te_1]_{\beta} & [Te_n]_{\beta} \\ \hline | & | \end{array} \right)$ to be $[T]_{\alpha}^{\beta}$.

Note that here we write basis element horizontally, and coordinate vertically.