

eg of higher order derivatives (order ≥ 3)

Previous eg: $f(x,y) = x \sin y + y^2 e^{2x}$

$$\Rightarrow f_{xy} = \cos y + 4y e^{2x} = f_{yx}$$

$$\Rightarrow (3^{\text{rd}} \text{ order}) f_{xyx} = (f_{xy})_x = 8y e^{2x} = (f_{yx})_x = f_{yxx}$$

$$f_{xyy} = (f_{xy})_y = -\sin y + 4e^{2x} = (f_{yx})_y = f_{yxy}$$

\vdots (E_x : other 3rd order partial derivatives)

One can calculate similarly up to any order

Question Is it always true that $f_{xy} = f_{yx}$?

Answer: No.

Counterexample:

$$f(x,y) = \begin{cases} \frac{xy(x^2-y^2)}{x^2+y^2} & \text{if } (x,y) \neq (0,0) \\ 0 & \text{if } (x,y) = (0,0) \end{cases}$$

By definition,

$$f_{xy}(0,0) = (f_x)_y(0,0) = \lim_{h \rightarrow 0} \frac{f_x(0,h) - f_x(0,0)}{h}$$

\therefore we need to calculate the 1st order partial derivative

$f_x(0,h)$ and $f_x(0,0)$.

$$\text{For } (0,h), \quad f_x(x,y) = \frac{\partial}{\partial x} \left(\frac{xy(x^2-y^2)}{x^2+y^2} \right)$$

$$= \frac{(x^2+y^2)(3x^2y-y^3) - xy(x^2-y^2)(2x)}{(x^2+y^2)^2}$$

$$\Rightarrow f_x(0,h) = \frac{-h^5}{h^4} = -h$$

$$\text{For } (0,0), \quad f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{0 - 0}{h} = 0$$

$$\therefore f_{xy}(0,0) = \lim_{h \rightarrow 0} \frac{f_x(0,h) - f_x(0,0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{-h - 0}{h} = -1.$$

Similarly, $f_{yx}(0,0) = 1$ (Ex!)

(An easy way to see this make sense: $f(x,y) = -f(y,x)$)

Hence $f_{xy}(0,0) \neq f_{yx}(0,0)$!

Question: When do we have $f_{xy} = f_{yx}$?

Thm (Clairaut's Thm / Mixed Derivatives Thm)

Let $f: \Omega \rightarrow \mathbb{R}$ ($\Omega \subset \mathbb{R}^n$, open)

If f_{xy} & f_{yx} exist and are continuous on Ω , then

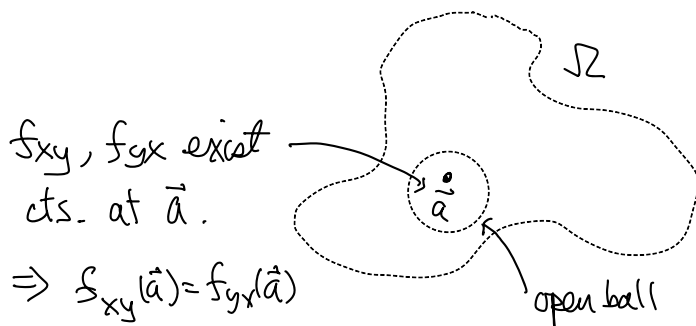
$$f_{xy} = f_{yx} \text{ on } \Omega.$$

Actually, one can prove a stronger version:

Thm Let $\begin{cases} \bullet f: \Omega \rightarrow \mathbb{R} \quad (\Omega \subset \mathbb{R}^n, \text{open}) \\ \bullet \vec{a} \in \Omega \end{cases}$

If $\begin{cases} \bullet f_{xy} \text{ \& } f_{yx} \text{ exist in an open ball containing } \vec{a}, \text{ and} \\ \bullet f_{xy} \text{ \& } f_{yx} \text{ are continuous at } \vec{a}, \end{cases}$

then $f_{xy}(\vec{a}) = f_{yx}(\vec{a})$.



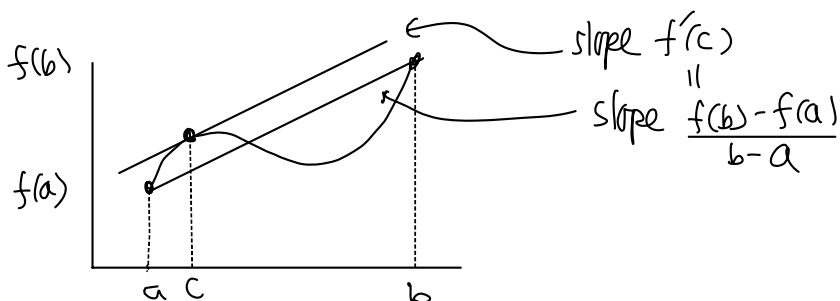
Recall

Mean Value Theorem for 1-variable Function

Let $f: [a, b] \rightarrow \mathbb{R}$, $\begin{cases} \bullet \text{continuous on } [a, b] \text{ \& } \\ \bullet \text{differentiable on } (a, b) \end{cases}$

Then $\exists c \in (a, b)$ such that

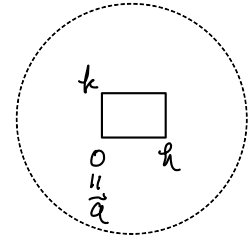
$$\frac{f(b) - f(a)}{b - a} = f'(c)$$



Pf of Clairaut's Thm

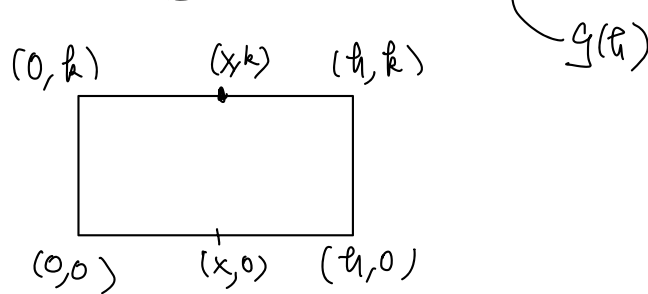
We may assume $\vec{a} = (0,0) \in \Omega$

and need to show $f_{xy}(0,0) = f_{yx}(0,0)$.



Let $h, k > 0$ and $[0, h] \times [0, k] \subset \Omega$

Define $\alpha = f(h, k) - f(0, k) - f(h, 0) + f(0, 0)$



Let $g(x) = f(x, k) - f(x, 0)$, $0 \leq x \leq h$

Then $\alpha = g(h) - g(0)$

$$g'(x) = f_x(x, k) - f_x(x, 0)$$

Mean Value Thm $\Rightarrow \exists h_1 \in (0, h)$ such that

$$\frac{g(h) - g(0)}{h} = g'(h_1)$$

i.e. $\frac{\alpha}{h} = f_x(h_1, k) - f_x(h_1, 0)$

$$\alpha = h [f_x(h_1, k) - f_x(h_1, 0)]$$

Mean Value Thm again $\Rightarrow \exists k_1 \in (0, k)$ such that

$$\frac{f_x(h_1, k) - f_x(h_1, 0)}{k} = (f_{xy})_{(h_1, k_1)}$$

$$\therefore \alpha = h k f_{xy}(h_1, k_1)$$

Similarly, $\exists (h_2, k_2) \in (0, h) \times (0, k)$ such that (Ex!)

$$\alpha = h k f_{yx}(h_2, k_2) \quad (\text{By interchanging the role of } x \text{ \& } y)$$

$$\therefore f_{xy}(h_1, k_1) = f_{yx}(h_2, k_2)$$

Letting $h, k \rightarrow 0^+ \Rightarrow h_1, k_1 \rightarrow 0$ & $h_2, k_2 \rightarrow 0$

$$\therefore f_{xy}(0,0) = f_{yx}(0,0) \quad \text{since } f_{xy} \text{ \& } f_{yx} \text{ are continuous at } \vec{a} = (0,0).$$

✘

Def Let $f: \Omega \rightarrow \mathbb{R}$ ($\Omega \subseteq \mathbb{R}^n$, open)

Then • f is called a C^k function if
all partial derivatives of f up to
order k exist and are continuous on Ω

• f is called a C^∞ function if
 f is C^k for all $k \geq 0$.

egs: (1) If f is continuous (0-order partial derivative)
then f is C^0 .

(2) If f is C^2 , then $f, f_x, f_y, f_{xx}, f_{xy} = f_{yx}, f_{yy}$ exist &
are all continuous. (by Clairaut's)

(3) Polynomials, Rational functions,
 exponential, logarithm, trigonometric functions
 are C^∞ function on their domains of definition.
 & hence their sum/difference/product/
 quotient/compositions
 are C^∞ function on their domains of definition.

explicit eg = $e^{x^2-y} \sin\left(\frac{x}{y}\right)$ (except $y=0$)
 on domain of definition = $\mathbb{R}^2 \setminus \{x\text{-axis}\}$

Generalization of Clairaut's Thm

If f is C^k on an open set $\Omega \subseteq \mathbb{R}^n$, then the order
 of (taking) differentiation does not matter for all
 partial derivatives up to order k .

eg If $f(x, y, z)$ is C^3 , then

$$\begin{aligned} f_{xz} &= f_{zx}, & f_{xyz} &= f_{xzy} = f_{zxy} = f_{zyx} \\ &\vdots & &= f_{yzx} = f_{yxz} \\ \text{etc.} & & & \end{aligned}$$

$$f_{xxy} = f_{xyx} = f_{yxx} \text{ and etc.}$$

(Mid term up to here, generalization of Clairaut's Thm)

Differentiability

Recall: 1-variable: f is differentiable at a

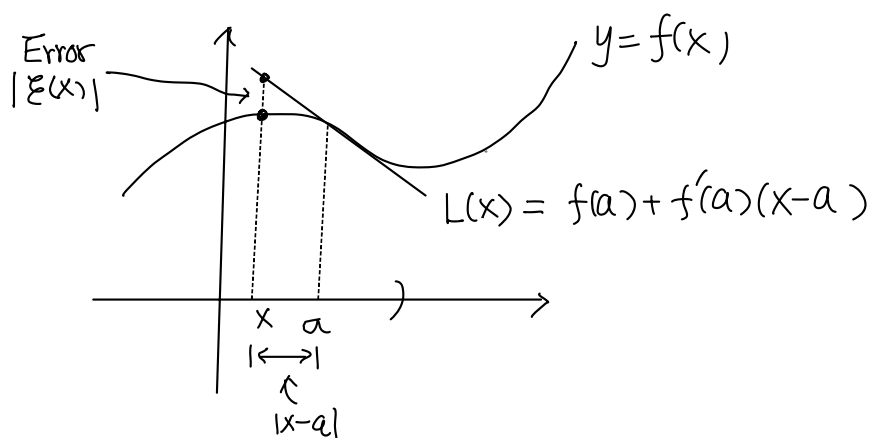
$$\text{if } f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} \text{ exists}$$

which is equivalent to

Linear Approximation of f at the point a :

$$f(x) \approx f(a) + f'(a)(x - a)$$

$L(x)$ is the "best" linear function
(deg ≤ 1 , poly)
to approximate $f(x)$ near a



What does it mean by "best"?

$$\lim_{x \rightarrow a} \left| \frac{f(x) - f(a)}{x - a} - f'(a) \right|$$

Answer: $\lim_{x \rightarrow a} \frac{|f(x) - L(x)|}{|x - a|} = 0$ $\left(\lim_{x \rightarrow a} \frac{|E(x)|}{|x - a|} = 0 \right)$

where $f(x) - L(x)$ is usually referred as the "error" term $E(x) = f(x) - L(x)$.

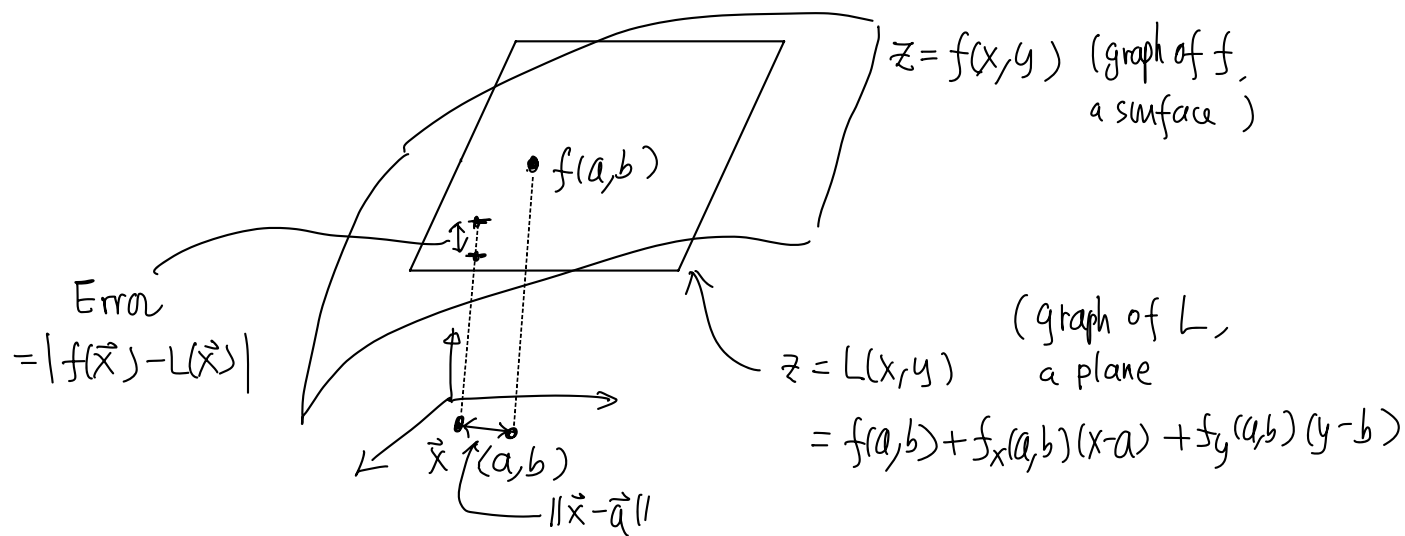
Higher dimensions analogy:

linear function (deg ≤ 1 , poly)

$$L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

and want

$$f(x,y) \approx L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$



Def: Let $f: \Omega \rightarrow \mathbb{R}$, $\Omega \subseteq \mathbb{R}^n$, open
 $\vec{a} = (a_1, \dots, a_n) \in \Omega$

Then f is said to be differentiable at \vec{a}

if (1) $\frac{\partial f}{\partial x_i}(\vec{a})$ exists for all $i=1, \dots, n$

(2) In the linear approximation for $f(\vec{x})$ at \vec{a}

$$f(\vec{x}) = \underbrace{f(\vec{a}) + \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{a})(x_i - a_i)}_{L(\vec{x}) \text{ linear approx.}} + \underbrace{\varepsilon(\vec{x})}_{\substack{\uparrow \\ \text{error term}}}$$

the error term $\varepsilon(\vec{x})$ satisfies

$$\lim_{\vec{x} \rightarrow \vec{a}} \frac{|\varepsilon(\vec{x})|}{\|\vec{x} - \vec{a}\|} = 0$$

(A differentiable function is one which can be well approximated
by a linear function locally.)

Remark: $L(\vec{x}) = f(\vec{a}) + \sum_{i=1}^n \underbrace{\frac{\partial f}{\partial x_i}(\vec{a})}_{\substack{\uparrow \\ \text{slope of } f \text{ in} \\ x_i\text{-direction at } \vec{a}}} \underbrace{(x_i - a_i)}_{\Delta x_i}$

- $L(\vec{x})$ is a $\text{deg} \leq 1$ polynomial
- $L(\vec{a}) = f(\vec{a})$
- $\frac{\partial L}{\partial x_i}(\vec{a}) = \frac{\partial f}{\partial x_i}(\vec{a})$ (Easy Ex!)
- The graph of $y = L(\vec{x})$ is a tangent n -plane to the graph of $y = f(\vec{x})$ (which is a surface) at the point $\vec{x} = \vec{a}$.

eg 1: $f(x,y) = x^2 y$

(1) Show that f is differentiable at $(1,2)$

(2) Approximate $f(1.1, 1.9)$ using linearization, $f(1,2)$

(3) Find tangent plane of $z = f(x,y)$ at $(1,2,z)$.

Soln: (1) $\frac{\partial f}{\partial x} = 2xy$, $\frac{\partial f}{\partial y} = x^2$

$\frac{\partial f}{\partial x}(1,2) = 4$, $\frac{\partial f}{\partial y}(1,2) = 1$

∴ The linearization at $(1, 2)$ is

$$\begin{aligned}L(x, y) &= f(1, 2) + \frac{\partial f}{\partial x}(1, 2)(x-1) + \frac{\partial f}{\partial y}(1, 2)(y-2) \\ &= 2 + 4(x-1) + (y-2) \quad (= 4x + y - 2)\end{aligned}$$

with error term

$$\begin{aligned}\mathcal{E}(x, y) &= f(x, y) - L(x, y) \\ &= x^2y - [2 + 4(x-1) + (y-2)]\end{aligned}$$

$$\lim_{(x, y) \rightarrow (1, 2)} \frac{|\mathcal{E}(x, y)|}{\|(x, y) - (1, 2)\|}$$

$$= \lim_{(x, y) \rightarrow (1, 2)} \frac{|x^2y - 2 - 4(x-1) - (y-2)|}{\sqrt{(x-1)^2 + (y-2)^2}} \quad \left(\begin{array}{l} \text{let } h = x-1 \\ k = y-2 \end{array} \right)$$

$$= \lim_{(h, k) \rightarrow (0, 0)} \frac{|(1+h)^2(k+2) - 2 - 4h - k|}{\sqrt{h^2 + k^2}}$$

$$= \lim_{(h, k) \rightarrow (0, 0)} \frac{|h^2k + 2hk + 2h^2|}{\sqrt{h^2 + k^2}} \quad \left(\begin{array}{l} \text{let } h = r \cos \theta \\ k = r \sin \theta \end{array} \right)$$

$$= \lim_{r \rightarrow 0} \frac{|r^3 \cos^2 \theta \sin \theta + 2r^2 \cos \theta \sin \theta + 2r^2 \cos^2 \theta|}{r}$$

$$= \lim_{r \rightarrow 0} r |r \cos^2 \theta \sin \theta + 2 \cos \theta \sin \theta + 2 \cos^2 \theta|$$

$$= 0 \quad \text{by Squeeze Thm}$$

∴ f is differentiable at $(1, 2)$. (To be cont'd)