

Lecture 15

Recall: $T: V \rightarrow V$, $F = \mathbb{C}$.

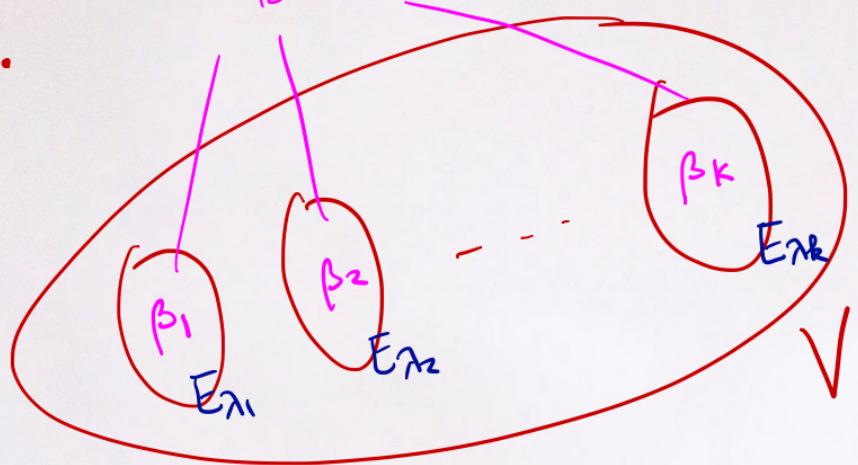
Char poly of T : $f_T(t) = (-1)^n (t - \lambda_1)^{n_1} (t - \lambda_2)^{n_2} \cdots (t - \lambda_k)^{n_k}$

n_j = algebraic multiplicity of λ_j = $\mu_T(\lambda_j)$

$\dim(\text{Eigenspace of } \lambda_j) = \dim(N(T - \lambda_j I_V)) = \dim(E_{\lambda_j})$

Geometric multiplicity = $\gamma_T(\lambda_j)$

- T is diagonalizable iff $M_T(\lambda_j) = \gamma_T(\lambda_j)$
for $j=1, 2, \dots, k$
- Bases of E_{λ_j} 's



Then: $\beta = \beta_1 \cup \beta_2 \cup \dots \cup \beta_k$ is a basis of eigenvectors
for V .

Theorem: Let T be a linear operator on a finite dimensional vector space V such that the characteristic polynomial splits. Let $\lambda_1, \lambda_2, \dots, \lambda_k$ be distinct eigenvalues of T .

Then: (a) T is diagonalizable iff: $M_T(\lambda_i) = g_T(\lambda_i)$
for $i=1, 2, \dots, k$

(b) If T is diagonalizable and β_i is an ordered basis for E_{λ_i} for each i , then $\beta := \beta_1 \cup \beta_2 \cup \dots \cup \beta_k$ is an ordered basis for V consisting of eigenvectors.

(so that $[T]_{\beta}$ is a diagonal matrix)

Proof: Write $n = \dim(V)$, and $m_i = M_T(\lambda_i)$ and $d_i = \dim(E_{\lambda_i})$ for all i . $\dim(E_{\lambda_i})$

Suppose T is diagonalizable and β is a basis for V consisting of eigenvectors of T .

(e.g. $\beta = \{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4, \vec{v}_5, \dots, \vec{v}_n\}$)

The diagram illustrates the decomposition of the basis β into eigenspaces. The vectors \vec{v}_1 and \vec{v}_3 are highlighted in yellow, while \vec{v}_2 , \vec{v}_4 , and \vec{v}_5 are highlighted in pink. Green arrows connect the first three vectors to a blue oval labeled E_{λ_1} , indicating they are eigenvectors corresponding to the eigenvalue λ_1 . Similarly, the last three vectors connect to a green oval labeled E_{λ_j} , indicating they are eigenvectors corresponding to the eigenvalue λ_j .

For each i , let $\beta_i = \beta \cap E_{\lambda_i}$ and $n_i \stackrel{\text{def}}{=} \#\beta_i$

Then: $n_i \leq d_i = \dim(E_{\lambda_i})$ ($\because \beta_i$ is lin. independent)

Also, $d_i \leq m_i$ (last lecture)

So, we have $n_i \leq d_i \leq m_i$ for all i .

$$\therefore n = \sum_{i=1}^k n_i \leq \sum_{i=1}^k d_i \leq \sum_{i=1}^k m_i = n = \dim(V)$$

$$\therefore \sum_{i=1}^k d_i - \sum_{i=1}^k n_i = 0 \Leftrightarrow \sum_{i=1}^k (d_i - n_i) = 0$$
$$\Rightarrow d_i = n_i \text{ for all } i.$$

$$\therefore \sum_{i=1}^k m_i - \sum_{i=1}^k d_i = 0 \Leftrightarrow \sum_{i=1}^k (m_i - d_i) = 0$$
$$\Rightarrow d_i = m_i \text{ for all } i.$$

$$\therefore n_i = d_i = m_i \text{ for all } i$$

(So, β_i is a basis of E_{n_i})

Conversely, suppose $m_i = d_i \forall i$.

For each i , let β_i be the ordered basis of E_{λ_i} and let $\beta = \beta_1 \cup \beta_2 \cup \dots \cup \beta_k$.

Then: from previous proposition, we know β is linearly independent.

$$\text{But } \# \beta = \sum_{i=1}^k d_i = \sum_{i=1}^k m_i = n = \dim(V)$$

$$\begin{matrix} |\beta_1| + |\beta_2| + \dots + |\beta_k| \\ \text{dim}(E_{\lambda_1}) \quad \text{dim}(E_{\lambda_2}) \quad \text{dim}(E_{\lambda_k}) \\ d_1 \end{matrix}$$

$\therefore \beta$ is a basis for V of eigenvectors

$\therefore T$ is diagonalizable.

Example: Let $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ be defined by:

$$T(f(x)) = f(x) + (x+1)f'(x)$$

Then: $A := [T]_{\beta} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}$

where $\beta = \{1, x, x^2\}$ = standard ordered basis for $P_2(\mathbb{R})$.

∴ the char. poly :

$$\det(A - t I_3) = \det \begin{pmatrix} 1-t & 1 & 0 \\ 0 & 2-t & 2 \\ 0 & 0 & 3-t \end{pmatrix} = (1-t)^1(2-t)^1(3-t)^1$$

$$\left. \begin{array}{l} 1 \leq \gamma_T(1) \leq M_T(1) = 1 \\ 1 \leq \gamma_T(2) \leq M_T(2) = 1 \\ 1 \leq \gamma_T(3) \leq M_T(3) = 1 \end{array} \right\}$$

$$\left. \begin{array}{l} \gamma_T(1) = M_T(1) \\ \gamma_T(2) = M_T(2) \\ \gamma_T(3) = M_T(3) \end{array} \right\}$$

⇒ Diagonalizable

~~E_1~~ $N(A - 1I_3) = N\left(\begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{pmatrix}\right) = \left\{ a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} : a \in \mathbb{R} \right\} \subseteq \mathbb{R}^3$

$[T - 1 I_V]_{\beta}$

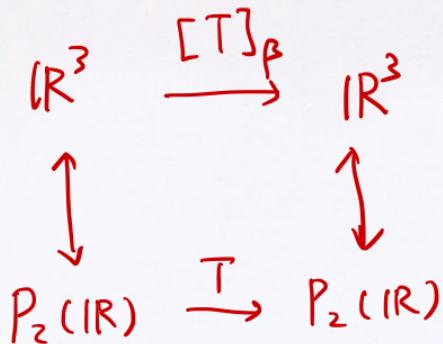
$\Rightarrow E_1 = N(T - 1 I_V) = \left\{ a1 : a \in \mathbb{R} \right\} \subseteq P_2(\mathbb{R})$

Similarly, $N(A - 2I_3) = N\left(\begin{pmatrix} -1 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{pmatrix}\right) = \left\{ a \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} : a \in \mathbb{R} \right\}$

$E_2 = \left\{ a(1+x) : a \in \mathbb{R} \right\} \subset P_2(\mathbb{R})$

$E_3 = \left\{ a \underbrace{(1+2x+x^2)}_{(1+x)^2} : a \in \mathbb{R} \right\}$

$\beta = \{1, 1+x, (1+x)^2\}$ is a basis
of eigenvectors for V .



Example: For $A = \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{pmatrix} \in M_{3 \times 3}(\mathbb{R})$

$f_A(t) = -(t-4)(t-3)^2$ splits over \mathbb{R} .

$$\gamma_T(4) = M_T(4) = 1$$

But $\text{rank}(A - 3I)$ $\xrightarrow{\text{B}}$ $= \text{rank}\left(\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{array}\right) = 2$

$$(\underbrace{\text{Rank}(B)}_2 + \underbrace{\text{Nullity}(B)}_1 = 3)$$

$$\gamma_A(3) = 1 \neq M_A(3) = 2$$

$\therefore T$ is not diagonalizable.

Example: Consider $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ defined by:

$$T(f(x)) = f(1) + f'(0)x + (f'(0) + f''(0))x^2$$

Let $\beta = \{1, x, x^2\}$.

$$[T]_{\beta} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \Rightarrow f_T(t) = -(t-1)^2(t-2)$$

splits over \mathbb{R} .

and the eigenvalues of T are 1 and 2.

$$\therefore \gamma_T(2) = \mu_T(2) = 1.$$

$$\text{Rank } ([T]_{\beta} - I) = \text{rank} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = 1 \Rightarrow \gamma_T(1) = 2 = \mu_T(1)$$

$\therefore T$ is diagonalizable.

For $[T]_P$, the eigenspaces:

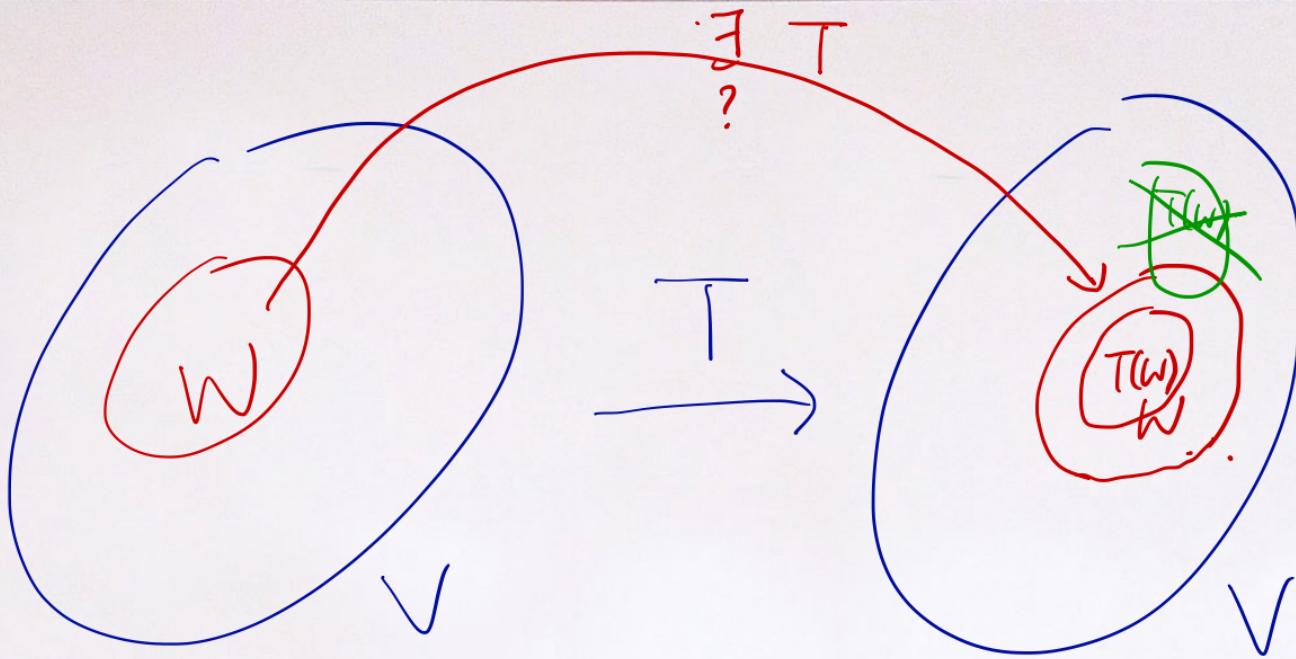
$$E_1 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_2 + x_3 = 0 \right\} = \text{span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}}_{\text{Basis}} \right\}$$

$$E_2 = \text{span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}}_{\text{Basis}} \right\}$$

$\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \underbrace{\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}}_{\text{Basis}} \right\}$ is a basis of eigenvectors (of $[T]_P$)

for \mathbb{R}^3 .

i. $\{1, x-x^2, 1+x^2\}$ is a basis of eigenvectors (of T)
for $P_2(\mathbb{R})$.



$$T(W) = \{ T(\vec{x}) : \vec{x} \in W \}$$

Definition: Let T be a linear operator on a vector space V .

A subspace $W \subset V$ is called T -invariant if $T(W) \subseteq W$.

That is, $T(\vec{w}) \in W$ for $\forall \vec{w} \in W$.

Example: If T is a linear operator on V , then:

$\{\vec{0}\}$ is T -invariant

V is "

$R(T)$ "

$N(T)$ "

E_λ
↑
eigenvalue

($\vec{w} \in R(T)$, then: $T(T(\vec{v})) \in R(T)$)

($\vec{v} \in E_\lambda$, $T(\vec{v}) = \lambda \vec{v} \in E_\lambda$)

• For $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(a, b, c) = (a+b, b+c, 0)$

then x-y plane $\{(x, y, 0) : x, y \in \mathbb{R}\}$ is T-invariant

x-axis $\{(x, 0, 0) : x \in \mathbb{R}\}$ is T-invariant

z-axis $\{(0, 0, z) : z \in \mathbb{R}\}$ is NOT T-invariant.

$$T(0, 0, x) = (0, \cancel{x}, 0) \notin z\text{-axis}$$

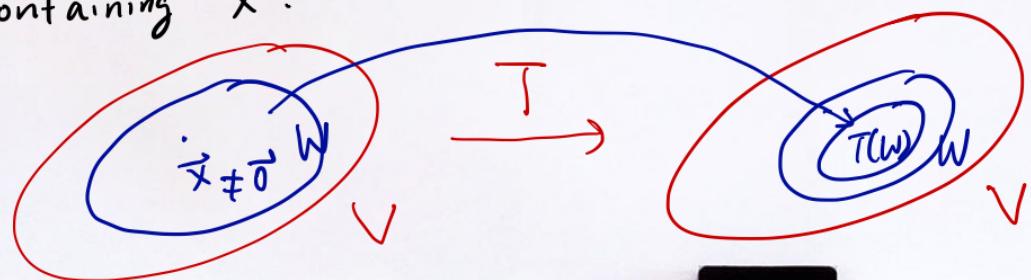
Def: Given a linear operator T on a vector space V , and a non-zero $\vec{x} \in V$, the subspace

$$W := \text{span}\left(\left\{ T^k(\vec{x}) : k \in \mathbb{N} \right\}\right) \stackrel{\text{def}}{=} \text{span}\left(\left\{ \vec{x}, T(\vec{x}), T^2(\vec{x}), \dots, T^k(\vec{x}), \dots \right\}\right)$$

$$(T^k \stackrel{\text{def}}{=} \underbrace{T \circ T \circ \dots \circ T}_{k \text{ times}})$$

is called T -cyclic subspace of V generated by \vec{x} .

Prop: W is the smallest T -invariant subspace of V containing \vec{x} .



Proof: For any $\vec{w} \in W$, $\exists a_0, \dots, a_k \in F$ s.t.

$$\vec{w} = \sum_{i=0}^k a_i T^i(\vec{x})$$

Then: $T(\vec{w}) = \sum_{i=0}^k a_i T^{i+1}(\vec{x}) \in W$.

i.e. W is T -invariant.

If $U \subset V$ is a T -invariant subspace containing \vec{x} .
then: it also contains $T(\vec{x}) \in U$ and $T^k(\vec{x}) \in U$ by induction.

$\therefore U \supset W$

