

The simplest examples of Riemannian manifolds are those whose sectional curvature is constant. The complete ones are called space forms. For each K all simply connected space forms with sectional curvature K are isometric.

$x_1, \dots, x_n$: standard coordinates of $\mathbb{R}^n$, $g_{ij} = \frac{\delta_{ij}}{(1 + \frac{K}{4} \sum x_i^2)^2}$

$(\mathbb{R}^n, g_{ij}) = S_{\frac{1}{\sqrt{K}}}^n$: constant curvature $K > 0$, not complete.

$(\|x\|^2 < -\frac{4}{K}, g_{ij})$: $K < 0$.

Define $\langle R(u, v)w, x \rangle = -K \begin{vmatrix} \langle u, w \rangle & \langle v, w \rangle \\ \langle u, x \rangle & \langle v, x \rangle \end{vmatrix}$: well-defined, i.e. (**).

Moreover, R has constant sectional curvature K .

$$R(u, v)w = K(\langle w, v \rangle u - \langle w, u \rangle v).$$

$x_1, \dots, x_n$: normal coordinates in a neighborhood of $p \in M$.

$$g_{ij} = \delta_{ij} - \frac{1}{3} R_{ikjl} x_k x_l + O(|x|^3). \quad \therefore \Gamma_{ij}^k = \frac{1}{2} \sum_m \left(\frac{\partial}{\partial x_i} g_{jm} + \frac{\partial}{\partial x_j} g_{mi} - \frac{\partial}{\partial x_m} g_{ij} \right) g^{mk}$$

$$\Gamma_{ij}^k(p) = 0, \quad \frac{\partial}{\partial x_k} g_{ij}(p) = 0.$$

Definition M^n is said to have isotropic curvature at p if $K(\sigma)$ is independent of the choice of $\sigma \subset T_p M$. M is isotropic if it is isotropic at every point. $n \geq 3$.

Lemma $\Rightarrow R(u, v, w, x) = f(\langle u, w \rangle \langle v, x \rangle - \langle u, x \rangle \langle v, w \rangle)$, $f \in C^\infty(M)$.

Theorem (Schur) An isotropic Riemannian manifold M^n , $n \geq 3$, has constant curvature.

Ricci curvature and Scalar curvature

Def The Ricci curvature is a symmetric bilinear form on $T_p M$ for each $p \in M$ defined to be the trace of the linear transformation $z \mapsto R(z, x)y$.

Hence $\text{Ric}(x, y) = \sum_i \langle R(e_i, x)y, e_i \rangle$, where $\{e_i\}$ is an orthonormal basis of $T_p M$.

symmetric $\because \text{Ric}(x, y) = \sum \langle R(e_i, x)y, e_i \rangle = \sum \langle R(y, e_i)e_i, x \rangle = \text{Ric}(y, x)$

The Scalar curvature is the trace of the Ricci curvature.

$$S = \sum_{i,j} \langle R(e_i, e_j)e_j, e_i \rangle$$

Ric : symmetric $\Rightarrow$ Ricci curvature is completely determined by the quantity $\text{Ric}(v, v)$ for all vectors of unit length.

$\text{Ric}(v, v)$ is $(n-1)$ times the average value of the sectional curvature, taken over all the 2-planes containing v .

The scalar curvature is $n(n-1)$ times the average value of the sectional curvature at a given point.

$$R_{ij} = \text{Ric}\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right) = \sum_k R_{kij}^k = \sum_{kl} R_{kijl} g^{lk}$$

$$S = \sum R_{ij} g^{ij}$$

$$g_{ij} = \delta_{ij} - \frac{1}{3} R_{ikjl} x_k x_l + O(|x|^3)$$

$$d\mu_g = \left[1 - \frac{1}{6} R_{jk} x_j x_k + O(|x|^3)\right] d\mu_{\text{Euclidean}}, \quad d\mu_g = \sqrt{\det(g_{ij})} dx_1 \dots dx_n$$

$\text{Ric}(v, v)$ represents the amount by which the volume of a narrow conical piece in v direction deviates from that in $\mathbb{R}^n$.

$$\text{Vol}(B_r(p) \subset M) = \left[1 - \frac{S}{6(n+2)} r^2 + O(r^4)\right] \text{Vol}(B_r(0) \subset \mathbb{R}^n)$$

$$\text{ex) Vol}(B_r(p) \subset S^3) = 4\pi \int_0^r \sin^2 t \, dt = \frac{4\pi}{3} r^3 \left(1 - \frac{r^2}{5} + \frac{2}{105} r^4 - \dots\right), \quad S \equiv 6.$$

$$\text{Gauss-Bonnet Theorem} \quad \int_S K \, dA = 2\pi \chi(S).$$

$\therefore T^2$ cannot have positive Gaussian curvature.

1. T^n has no metric with positive scalar curvature. (Gromov-Lawson)
2. Hopf conjecture: $S^2 \times S^2$ cannot admit a metric with positive sectional curvature.
3. Every compact manifold admits a metric with negative constant scalar curvature. (Aubin)
4. Every compact M^3 has a metric of negative Ricci curvature. (Gau-Yau)
5. If compact M has positive Ricci curvature, then its first Betti number β_1 is zero. (Bochner) $\text{Rank } H_2(M) := \beta_2$.
6. A complete noncompact M^3 with positive Ricci curvature is diffeomorphic to $\mathbb{R}^3$.