

# Suggested solutions to HW3 for MATH3270a

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1. (**4points=1point**  $\times$  4) **Find** the general solution to the following differential equations:

- (a)  $y^{(4)} + 2y^{(3)} + y'' = 0$ ;
- (b)  $y^{(4)} + 8y^{(2)} + 16y = 0$ ;
- (c)  $y^{(3)} + y'' + y' + y = 2e^{-t} + 4t$ ;
- (d)  $y^{(4)} + 2y'' + y = 4 + \cos 2t$ ;

**Solution:**

(a) The corresponding characteristic equation is

$$r^4 + 2r^3 + r^2 = 0,$$

then  $r_1 = r_2 = 0, r_3 = r_4 = -1$ , so the general solution is

$$y = C_1 + C_2t + C_3e^{-t} + C_4te^{-t}$$

where  $C_1, C_2, C_3$  and  $C_4$  are arbitrary constants.

(b) The corresponding characteristic equation is

$$r^4 + 8r^2 + 16 = 0,$$

then  $r = \pm 2i$  with multiplicity 2, so the general solution is

$$y = C_1 \cos(2t) + C_2 \sin(2t) + C_3t \cos(2t) + C_4t \sin(2t)$$

where  $C_1, C_2, C_3$  and  $C_4$  are arbitrary constants.

(c) The corresponding characteristic equation is

$$r^3 + r^2 + r + 1 = 0,$$

then  $r_1 = -1, r_2 = i, r_3 = -i$ , so the general solution to the corresponding homogeneous equation is

$$y_c = C_1e^{-t} + C_2 \cos t + C_3 \sin t$$

where  $C_1, C_2$  and  $C_3$  are arbitrary constants. By observation, it's promising to find a particular solution of the form <sup>1</sup>

$$Y(t) = Ate^{-t} + Bt + C$$

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\*Any questions on solutions of HW3, please email me at rzhang@math.cuhk.edu.hk

<sup>1</sup>Here we use the method of undetermined coefficients to find a particular solution, you can also try the method of variation of parameters to solve problem 1(c)(d) by yourself.

where constants  $A, B, C$  are to be determined. Since

$$\begin{aligned}Y'(t) &= A(1-t)e^{-t} + B, \\Y''(t) &= A(t-2)e^{-t}, \\Y^{(3)} &= A(3-t)e^{-t},\end{aligned}$$

then by substituting  $Y(t)$  into the problem, we have

$$2e^{-t} + 4t = Y^{(3)} + Y'' + Y' + Y = 2Ae^{-t} + Bt + C + B$$

which implies that  $A = 1, B = 4, C = -4$ . Therefore, the general solution is given by

$$y = y_c + Y = C_1e^{-t} + C_2 \cos t + C_3 \sin t + te^{-t} + 4t - 4$$

with arbitrary constants  $C_1, C_2$  and  $C_3$ .

(d) The corresponding characteristic equation is

$$r^4 + 2r^2 + 1 = 0,$$

then  $r = \pm i$  with multiplicity 2, so the general solution to the corresponding homogeneous equation is

$$y_c = C_1 \cos t + C_2 \sin t + C_3 t \cos t + C_4 t \sin t$$

where  $C_1, C_2, C_3$  and  $C_4$  are arbitrary constants. By observation, it's promising to find a particular solution of the form

$$Y(t) = A + B \cos 2t + C \sin 2t$$

where  $A, B, C$  are constants to be determined. Since

$$\begin{aligned}Y'(t) &= -2B \sin 2t + 2C \cos 2t, \\Y''(t) &= -4B \cos 2t - 4C \sin 2t, \\Y^{(3)} &= 8B \sin 2t - 8C \cos 2t, \\Y^{(4)} &= 16B \cos 2t + 16C \sin 2t,\end{aligned}$$

then by substituting  $Y(t)$  into the problem, we have

$$4 + \cos 2t = Y^{(4)} + 2Y'' + Y = 9B \cos 2t + 9C \sin 2t + A$$

which implies that  $A = 4, B = \frac{1}{9}, C = 0$ . Therefore, the general solution is given by

$$y = y_c + Y = C_1 \cos t + C_2 \sin t + C_3 t \cos t + C_4 t \sin t + 4 + \frac{1}{9} \cos 2t$$

with arbitrary constants  $C_1, C_2$  and  $C_3$ .

2. (1points=0.5points  $\times$  2) **Determine** a suitable form of  $Y(t)$  for using the method of undetermined coefficients to the following equations:

- (a)  $y^{(3)} - 2y'' + y' = 3t^3 + 2e^t$ ;
- (b)  $y^{(4)} - y^{(3)} - y'' + y' = t^2 + 8 + t \sin t$ .

**Solution:**

(a) The corresponding characteristic equation is

$$r^3 - 2r^2 + r = 0,$$

then  $r_1 = 0, r_2 = r_3 = 1$ , so one particular solution is of the form

$$Y(t) = (At^3 + Bt^2 + Ct + D)t + Et^2e^t$$

where  $A, B, C, D$  and  $E$  are constants to be determined.

(b) The corresponding characteristic equation is

$$r^4 - r^3 - r^2 + r = 0,$$

then  $r_1 = 0, r_2 = r_3 = 1, r_4 = -1$ , so one particular solution is of the form

$$Y(t) = (At^2 + Bt + C)t + (Dt + E) \cos t + (Ft + G) \sin t$$

where  $A, B, C, D, E, F$  and  $G$  are constants to be determined.

3. **(2point) Write** down a formula involving integrals for a particular solution  $Y(t)$  of the differential equation

$$y^{(3)} - 3y'' + 3y' - y = r(t),$$

and use it to **solve** for  $Y(t)$  when  $r(t) = t^{-2}e^t$ .

**Solution:** The corresponding characteristic equation is

$$r^3 - 3r^2 + 3r - 1 = 0,$$

so  $r_1 = r_2 = r_3 = 1$  and a fundamental set of solution to homogeneous equation is

$$\{y_1 = e^t, y_2 = te^t, y_3 = t^2e^t\},$$

and

$$W[y_1, y_2, y_3](t) = \begin{vmatrix} e^t & te^t & t^2e^t \\ e^t & (t+1)e^t & (t^2+2t)e^t \\ e^t & (t+2)e^t & (t^2+4t+2)e^t \end{vmatrix} = 2e^{3t}.$$

Then we intend to find a particular solution to the non-homogeneous equation of the following form

$$Y(t) = C_1(t)e^t + C_2(t)te^t + C_3(t)t^2e^t,$$

with functions  $C_1(t), C_2(t)$  and  $C_3(t)$  to be determined. Since

$$\begin{aligned} Y'(t) &= (C_1'(t)y_1 + C_2'(t)y_2 + C_3'(t)y_3) + C_1(t)y_1' + C_2(t)y_2' + C_3(t)y_3', \\ Y''(t) &= \frac{d}{dt} (C_1'(t)y_1 + C_2'(t)y_2 + C_3'(t)y_3) + C_1'(t)y_1' + C_2'(t)y_2' + C_3'(t)y_3' \\ &\quad + C_1(t)y_1'' + C_2(t)y_2'' + C_3(t)y_3'', \\ Y^{(3)} &= \frac{d^2}{dt^2} (C_1'(t)y_1 + C_2'(t)y_2 + C_3'(t)y_3) + \frac{d}{dt} (C_1'(t)y_1' + C_2'(t)y_2' + C_3'(t)y_3') \\ &\quad + C_1'(t)y_1'' + C_2'(t)y_2'' + C_3'(t)y_3'' \\ &\quad + C_1(t)y_1''' + C_2(t)y_2''' + C_3(t)y_3''', \end{aligned}$$

so if  $C_1'(t)$  and  $C_2'(t)$  satisfy the following algebraic system

$$\begin{aligned} C_1'(t)y_1 + C_2'(t)y_2 + C_3'(t)y_3 &= 0, \\ C_1'(t)y_1' + C_2'(t)y_2' + C_3'(t)y_3' &= 0, \\ C_1'(t)y_1'' + C_2'(t)y_2'' + C_3'(t)y_3'' &= r(t), \end{aligned}$$

then  $Y(t)$  is a solution to  $y^{(3)} - 3y'' + 3y' - y = r(t)$ . By solving the above system, we have

$$\begin{aligned} C_1'(t) &= r(t) \frac{W_1}{W[y_1, y_2, y_3]}, \\ C_2'(t) &= r(t) \frac{W_2}{W[y_1, y_2, y_3]}, \\ C_3'(t) &= r(t) \frac{W_3}{W[y_1, y_2, y_3]}, \end{aligned}$$

where

$$\begin{aligned} W_1 &= \begin{vmatrix} 0 & te^t & t^2e^t \\ 0 & (t+1)e^t & (t^2+2t)e^t \\ 1 & (t+2)e^t & (t^2+4t+2)e^t \end{vmatrix} = t^2e^{2t}, \\ W_2 &= \begin{vmatrix} e^t & 0 & t^2e^t \\ e^t & 0 & (t^2+2t)e^t \\ e^t & 1 & (t^2+4t+2)e^t \end{vmatrix} = -2te^{2t}, \\ W_3 &= \begin{vmatrix} e^t & te^t & 0 \\ e^t & (t+1)e^t & 0 \\ e^t & (t+2)e^t & 1 \end{vmatrix} = e^{2t}. \end{aligned}$$

Thus a particular solution is of the following form

$$\begin{aligned} Y(t) &= C_1(t)e^t + C_2(t)te^t + C_3(t)t^2e^t \\ &= e^t \int \frac{1}{2}r(t)t^2e^{-t}dt + te^t \int -r(t)te^{-t}dt + t^2e^t \int \frac{1}{2}r(t)e^{-t}dt. \end{aligned}$$

If  $r(t) = t^{-2}e^t$ , then

$$\begin{aligned} Y(t) &= C_1(t)e^t + C_2(t)te^t + C_3(t)t^2e^t \\ &= e^t \int \frac{1}{2}dt + te^t \int -t^{-1}dt + t^2e^t \int \frac{1}{2}t^{-2}dt \\ &= -t \ln te^t. \end{aligned}$$

4. (3points) If  $y_1$  is a solution to the equation

$$y^{(3)} + p_2(t)y'' + p_1(t)y' + p_0(t)y = 0,$$

(a) (1point) use the substitution  $y = y_1(t)v(t)$  to **derive** a second order ODE for  $u = v'$ ;

(b) (2points) use it to **find** the general solution for

$$(2-t)y^{(3)} + (2t-3)y'' - ty' + y = 0,$$

for  $t < 2$  provided that  $y_1(t) = e^t$  is a solution.

**Solution:**

(a) Let

$$y = y_1(t)v(t),$$

then  $y' = y_1'v + y_1v'$ ,  $y'' = y_1''v + 2y_1'v' + y_1v''$  and  $y^{(3)} = y_1'''v + 3y_1''v' + 3y_1'v'' + y_1v'''$ . So the original ODE becomes

$$y_1v''' + (3y_1' + p_2y_1)v'' + (3y_1'' + 2p_2y_1' + p_1y_1)v' + (y_1''' + p_2y_1'' + p_1y_1' + p_0y_1)v = 0.$$

Since  $y_1$  is a solution, then  $u = v'$  satisfies

$$y_1u'' + (3y_1' + p_2y_1)u' + (3y_1'' + 2p_2y_1' + p_1y_1)u = 0,$$

which is a second order ODE for  $u$ .

(b) In this case,  $y_1 = e^t$  and

$$p_2 = \frac{2t-3}{2-t}, \quad p_1 = \frac{-t}{2-t}, \quad p_0 = \frac{1}{2-t}.$$

Let  $y = y_1 v$ , we have

$$v''' + \frac{3-t}{2-t}v'' = 0,$$

which is a first order linear ODE of  $v''$ , then

$$v'' = C_1 e^{-\int \frac{3-t}{2-t} dt} = C_1 (t-2)e^{-t}$$

and then

$$v' = C_1 \int (t-2)e^{-t} dt + C_2 = -C_1(t-1)e^{-t} + C_2$$

and thus

$$v = -C_1 \int (t-1)e^{-t} dt + C_2 t + C_3 = C_1 t e^{-t} + C_2 t + C_3$$

where  $C_1, C_2, C_3$  are arbitrary constants. Finally, the general solution is given by

$$y = C_1 t + C_2 t e^t + C_3 e^t.$$

5. (**5points=1point**  $\times$  **5**) [Method of Annihilators] Consider the following differential equation

$$\left(\frac{d}{dt} - 2\right)^3 \left(\frac{d}{dt} + 1\right) y = 3e^{2t} - te^{-t} \quad (1)$$

and try to solve a particular solution  $Y(t)$ .

(a) **Show** that the linear differential operators with constant coefficients obey the commutative law

$$\left(\frac{d}{dt} - a\right) \left(\frac{d}{dt} - b\right) f = \left(\frac{d}{dt} - b\right) \left(\frac{d}{dt} - a\right) f$$

for any twice-differentiable  $f$  and any constants  $a, b$ .

(b) **Show** that the operator  $\left(\frac{d}{dt} - 2\right) \left(\frac{d}{dt} + 1\right)^2$  annihilates the terms on the R.H.S. of equation (1).

(c) By applying  $\left(\frac{d}{dt} - 2\right) \left(\frac{d}{dt} + 1\right)^2$  to both side of equation (1), **show** that a particular solution  $Y(t)$  should satisfy

$$\left(\frac{d}{dt} - 2\right)^4 \left(\frac{d}{dt} + 1\right)^3 Y = 0$$

and hence **show** that

$$Y = c_1 e^{2t} + c_2 t e^{2t} + c_3 t^2 e^{2t} + c_4 t^3 e^{2t} + c_5 e^{-t} + c_6 t e^{-t} + c_7 t^2 e^{-t}$$

for some constants  $c_1, c_2, c_3, c_4, c_5, c_6, c_7$  to be determined.

(d) **Solve** a particular solution  $Y(t)$  for equation (1).

(e) For each of  $P_k(t), e^{\alpha t} P_k(t), e^{\alpha t} \sin(\mu t) P_k(t), e^{\alpha t} \cos(\mu t) P_k(t)$ , **write down** a polynomial  $f(r)$  such that  $f\left(\frac{d}{dt}\right)$  is an annihilator for it.

**Solution:**

(a) It follows from simple calculations that

$$\left(\frac{d}{dt} - a\right)\left(\frac{d}{dt} - b\right)f = \frac{d^2}{dt^2}f - (a+b)\frac{d}{dt}f + ab = \left(\frac{d}{dt} - b\right)\left(\frac{d}{dt} - a\right)f.$$

(b) Note that

$$\left(\frac{d}{dt} - 2\right)\left(\frac{d}{dt} + 1\right)^2(3e^{2t} - te^{-t}) = 0.$$

(c) It's obvious.

(d) Since  $e^{2t}$ ,  $te^{2t}$ ,  $t^2e^{2t}$  and  $e^{-t}$  are solutions to the corresponding homogeneous equation, then  $c_1 = c_2 = c_3 = c_5 = 0$ , and then

$$\begin{aligned} 3e^{2t} - te^{-t} &= \left(\frac{d}{dt} - 2\right)^3\left(\frac{d}{dt} + 1\right)Y = \left(\frac{d}{dt} - 2\right)^3\left(\frac{d}{dt} + 1\right)(c_4t^3e^{2t} + c_6te^{-t} + c_7t^2e^{-t}) \\ &= \left(\frac{d}{dt} - 2\right)^3(3c_4t^2e^{2t} + 3c_4t^3e^{2t} + c_6e^{-t} + 2c_7te^{-t}) \\ &= \left(\frac{d}{dt} - 2\right)^3(3c_4t^3e^{2t} + c_6e^{-t} + 2c_7te^{-t}) \\ &= 18c_4e^{2t} + \left(\frac{d}{dt} - 2\right)^3(c_6e^{-t} + 2c_7te^{-t}) \\ &= 18c_4e^{2t} + \left(\frac{d}{dt} - 2\right)^2((2c_7 - 3c_6)e^{-t} - 6c_7te^{-t}) \\ &= 18c_4e^{2t} + \left(\frac{d}{dt} - 2\right)((9c_6 - 12c_7)e^{-t} + 18c_7te^{-t}) \\ &= 18c_4e^{2t} + (54c_7 - 27c_6)e^{-t} - 54c_7te^{-t} \end{aligned}$$

which implies that  $c_4 = \frac{1}{6}$ ,  $c_6 = \frac{1}{27}$ ,  $c_7 = \frac{1}{54}$ , so

$$Y = \frac{1}{6}t^3e^{2t} + \frac{1}{27}te^{-t} + \frac{1}{54}t^2e^{-t}.$$

(e)

$$\begin{array}{ll} P_k(t) : & f(t) = t^{k+1}, \\ e^{\alpha t}P_k(t) : & f(t) = (t - \alpha)^{k+1}, \\ e^{\alpha t} \sin(\mu t)P_k(t) : & f(t) = (t^2 - 2\alpha t + \alpha^2 + \mu^2)^{k+1}, \\ e^{\alpha t} \cos(\mu t)P_k(t) : & f(t) = (t^2 - 2\alpha t + \alpha^2 + \mu^2)^{k+1}. \end{array}$$