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# **Stability and Uniqueness for Inverse Problems for Partial Differential Equations by Carleman Estimates**

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# Foreword

- Theoretical studies for inverse problems
- Numerical methods for inverse problems

IP numerics without theory  $\Rightarrow$  No quality assurance

IP theory without numerics  $\Rightarrow$  Mathematical toys

Hopefully my theoretical achievements may be useful also for numerical approaches.

Main technics: Carleman estimate

Formulation: Inverse problems for PDE with single measurement

What is Carleman estimate?

How to use Carleman estimate for IP?

## Contents:

- Part I. Main methodology
- Part II. Recent results by me with Prof. Imanuvilov
  - inverse problems for parabolic equations
  - inverse problems for hyperbolic equations
  - unique continuation for Schödinger equation

# Part I. Description of main methodology: case of first-order equations

Part I is from a joint work with

Professor Piermarco Cannarsa  
(Università degli Studi di Roma "Tor Vergata")

Professor Giuseppe Floridia  
(Sapienza Università di Roma)

# §1. Introduction

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Main target: Transport equation:

$$\partial_t u(x, t) + (H(x) \cdot \nabla u) + p(x, t)u = 0 \quad \text{in } Q := \Omega \times (0, T)$$

$\Omega \subset \mathbb{R}^d$ : bounded smooth domain,

$|H| \neq 0$  on  $\overline{\Omega}$ ,  $H \in C^1(\overline{\Omega})$ ,  $p \in L^\infty$

Let  $\Gamma \subset \partial\Omega$  be given subboundary.

Observability: Determine  $u(\cdot, 0)$  in  $\Omega$  by  $u|_{\Gamma \times (0, T)}$ .

Inverse coefficient problem:

$u|_{\Gamma \times (0, T)}$  and  $u(\cdot, 0)|_\Omega \implies p(x)$  for  $x \in \Omega$

in  $\partial_t u(x, t) + H(x) \cdot \nabla u + p(x)u = 0$ .

## References:

- [1] P. Cannarsa, G. Floridia, F. Gölgeleyen, M. Yamamoto, Inverse coefficient problems for a transport equation by local Carleman estimate, *Inverse Problems* 35 (2019).
- [2] O. Imanuvilov and M. Yamamoto, Inverse problems for a compressible fluid system (2020).
- [3] F. Gölgeleyen and M. Yamamoto, Stability for some inverse problems for transport equations, *SIAM J. Math. Anal.* 48 (2016).
- [4] P. Gaitan and H. Ouzzane, Inverse problem for a free transport equation using Carleman estimates, *Appl. Anal.* 93 (2014).

# Basic setting

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Main equation

$$\partial_t u(x, t) + (H(x) \cdot \nabla u) + p(x, t)u = 0 \quad \text{in } Q := \Omega \times (0, T)$$

Standing notations

- $\Omega \subset \mathbb{R}^d$ : smooth bounded domain
- $Q := \Omega \times (0, T)$ .
- $S^{d-1} := \{x \in \mathbb{R}^d; |x| = 1\}$
- $\nu = \nu(x)$ : unit outward normal vector to  $\partial\Omega$  at  $x$ .

## §2. Carleman estimate: Non-rotating case

**Assumption:**  $\exists v \in S^{d-1} := \{x \in R^d; |x| = 1\}$  such that  $(H(x) \cdot v) > \exists \delta_0 > 0$  in  $Q$

$$\Rightarrow \left\{ \frac{H(x)}{|H(x)|}; x \in \Omega \right\} \subset \frac{S^{d-1}}{2}.$$

Set  $\varphi(x, t) := |x + rv|^2 - \beta t$ ,  $r >> 1$ ,  $\beta \ll 1$ ,  $\Sigma_+ := \{(x, t) \in \partial\Omega \times (0, T); (H(x) \cdot \nu(x)) > 0\}$ .

**Theorem 1 (Carleman estimate)**  $\exists s_0 > 0$  and  $\exists C > 0$  such that

$$\begin{aligned} & s \int_{\Omega} |u(x, 0)|^2 e^{2s\varphi(x, 0)} dx + s^2 \int_Q |u|^2 e^{2s\varphi(x, t)} dx dt \\ & \leq C \int_Q |(\partial_t + (H \cdot \nabla))u|^2 e^{2s\varphi(x, t)} dx dt + Cs \int_{\Sigma_+} |u|^2 e^{2s\varphi(x, t)} dS dt \\ & \quad + Cs \int_{\Omega} |u(x, T)|^2 e^{2s\varphi(x, T)} dx \quad \text{for all } s \geq s_0. \end{aligned}$$

**Important characters of Carleman estimates**

- Uniform  $L^2$ -weighted estimates in large parameter  $s > 0$ .
- Lower-order terms of PDE do not affect.

**Proof.**  $(H \cdot v) > 0$  on  $\bar{\Omega} \implies$

$$B(x, t) := (\nabla \varphi \cdot H) - \beta = 2(x + rv \cdot H) - \beta \geq O(r) - \beta > 0 \text{ on } \bar{\Omega}$$

for  $r \gg 1$  and  $\beta \ll 1$ . Set  $w := ue^{s\varphi} \implies$

$$Pw := e^{s\varphi}(\partial_t + (H \cdot \nabla))(e^{-s\varphi}w) = (\partial_t w + (H \cdot \nabla w)) - sBw.$$

Then, neglecting  $|\partial_t w + (H \cdot \nabla w)|^2$ , we have

$$\begin{aligned} \int_Q |\partial_t u + (H \cdot \nabla u)|^2 e^{2s\varphi} dx dt &= \int_Q |Pw|^2 dx dt \\ &\geq s^2 \int_Q B^2 w^2 dx dt - 2s \int_Q Bw(x, t)(\partial_t w + (H \cdot \nabla w)) dx dt \end{aligned}$$

Use integration by parts and  $B > 0$  on  $\bar{\Omega}$  ■

### §3. Methodology from Carleman estimate to inverse problems

Method: originally by Bukhgeim-Klibanov (1981). We rely on  
Simplification by Huang, Imanuvilov and Yamamoto (2020)

Assume that  $\exists v \in S^{d-1}$  such that  $(H \cdot v) \geq \exists \delta_0 > 0$  on  $\bar{\Omega}$  for  
 $\partial_t u(x, t) + (H(x) \cdot \nabla u) + p(x)u(x, t) = 0$ .

Theorem 2 (observability). Let  $T > \frac{1}{\delta} \sup_{x \in \Omega} |x + rv|^2$ . Then

$$\|u(\cdot, 0)\|_{L^2(\Omega)} \leq C \|u\|_{L^2(\partial\Omega \times (0, T))}.$$

Here  $\delta > 0$  depends on  $\delta_0$  and  $\Omega$ .

Remark. Hölder stability: Let  $\|u(\cdot, T)\|_{L^2(\Omega)} \leq M_0$ . Then  $\exists C > 0$  and  $\exists \kappa \in (0, 1)$  such that

$$\|u(\cdot, 0)\|_{L^2(\Omega)} \leq C(\|u\|_{L^2(\Sigma_+)}^\kappa + \|u\|_{L^2(\Sigma_+)}).$$

$\Sigma_+$ : outgoing subboundary of  $\partial\Omega \times (0, T)$ .

## Inverse coefficient problem

Let  $u = u(p) \in H^1(Q)$  satisfy

$$\begin{cases} \partial_t u + (H(x) \cdot \nabla u(x, t)) + p(x)u = 0, \\ u(x, 0) = u_0(x), \quad x \in \Omega, 0 < t < T. \end{cases}$$

We assume  $\|p\|_{L^\infty(\Omega)}, \|q\|_{L^\infty(\Omega)} \leq M$ : arbitrarily fixed constant.

**Theorem 3.**

Let

$$T > \frac{1}{\delta} \sup_{x \in \Omega} |x + rv|^2, \quad |u_0| > 0 \quad \text{on } \overline{\Omega}.$$

Then

$$\|p - q\|_{L^2(\Omega)} \leq C \|\partial_t u(p) - \partial_t u(q)\|_{L^2(\partial\Omega \times (0, T))}$$

under a priori boundness on  $u(p), u(q)$  with suitable norms.

Proof of the observability inequality (Theorem 2)

$$\partial_t u + ((H(x) \cdot \nabla u) + p(x, t)u = 0 \text{ in } Q.$$

Lemma 1 (energy estimate).  $\|u(\cdot, T)\|_{L^2(\Omega)} \leq C(\|u(\cdot, 0)\|_{L^2(\Omega)} + \|u\|_{L^2(\partial\Omega \times (0, T))}).$

Carleman estimate  $\Rightarrow$

$$\int_{\Omega} |u(x, 0)|^2 e^{2s\varphi(x, 0)} dx \leq C \int_{\partial\Omega \times (0, T)} |u|^2 e^{2s\varphi} dx dt + C \int_{\Omega} |u(\cdot, T)|^2 e^{2s\varphi(x, T)} dx$$

Then  $T > \frac{1}{\delta} \sup_{x \in \Omega} |x + rv|^2 \Rightarrow$

- $-\mu_0 := \sup_{x \in \Omega} \varphi(x, T) = \sup_{x \in \Omega} |x + rv|^2 - \beta T < 0$  if we choose small  $\beta \sim \delta$ .
- $\varphi(x, 0) \geq 0$

$\Rightarrow$

$$\int_{\Omega} |u(x, 0)|^2 dx \leq Ce^{Cs} \|u\|_{L^2(\partial\Omega \times (0, T))}^2 + Ce^{-2s\mu_0} \int_{\Omega} |u(x, T)|^2 dx$$

Lemma 1  $\Rightarrow$

$$\begin{aligned} \|u(x, 0)\|_{L^2(\Omega)}^2 &\leq Ce^{Cs} \|u\|_{L^2(\partial\Omega \times (0, T))}^2 \\ + Ce^{-2s\mu_0} \|u(\cdot, 0)\|_{L^2(\Omega)}^2 &+ Ce^{-2s\mu_0} \|u\|_{L^2(\partial\Omega \times (0, T))}^2 \end{aligned}$$

Take  $s > 0$  large  $\Rightarrow$  Absorb the second term on right side into left side ■

# Part II. Recent works on inverse problems by Carleman estimates

With Professor Oleg Imanuvilov  
(Colorado State University)

## §1. Inverse parabolic problems

Let  $\Omega \subset \mathbb{R}^d$ : bounded domain,  $\nu$ : unit outward normal vector to  $\partial\Omega$

$$\begin{cases} \partial_t u = \operatorname{div}(a(x)\nabla u) + c(x)u(x, t), & (x, t) \in \Omega \times (0, T), \\ \partial_\nu u|_{\partial\Omega} = 0, \\ u(\cdot, t_0) = u_0 & \text{in } \Omega \end{cases}$$

Here  $a > 0$  on  $\overline{\Omega}$ ,  $\in C^3(\overline{\Omega})$ . Let  $\Gamma \subset \partial\Omega$  be a subboundary.

Inverse problem:  $u|_{\Gamma \times (0, T)} \implies c(x)$

References (not comprehensive)

Case I:  $0 < t_0 < T$ .

Bukhgeim-Klibanov (1981): uniqueness

Imanuvilov-Yamamoto (1998): Lipschitz stability in  $\Omega$  (global)

My life has been with inverse parabolic problems!

Yamamoto-Zou (2001): stability and numerical methods

Case II:  $t_0 = T$ . no data after  $T$ .

Imanuvilov and Yamamoto (2023): global Lipschitz stability

### Case III: $t_0 = 0$ (IP for initial boundary value problem)

- Klibanov (1992): uniqueness if  $\Gamma \not\supseteq$  "half of  $\partial\Omega$ " and  $\left| \frac{(\nabla a \cdot (x - x_0))}{a(x)} \right| < 2$  with some  $x_0 \notin \overline{\Omega}$ .
- Suzuki-Murayama (1980): uniqueness if any eigenmode of  $u_0 > 0$  is not zero for **one dimensional case** by Gel'fand-Levitan theory (inverse eigenvalue problem)
- Imanuvilov and Yamamoto (2023): uniqueness if  $u_0 \neq 0$  is "very smooth".

Case II:  $t_0 = T$ .

$$\begin{cases} \partial_t u = \operatorname{div}(a \nabla u) + c(x)u, & x \in \Omega, 0 < t < T, \\ \partial_\nu u|_{\partial\Omega} = 0, & u(\cdot, T) = u_0. \end{cases}$$

Let  $u(c, b)(x, t)$  be solution to

$$\begin{cases} \partial_t u = \operatorname{div}(a \nabla u) + c(x)u, \\ \partial_\nu u|_{\partial\Omega} = 0, & u(\cdot, 0) = b. \end{cases}$$

Let  $H^\gamma(\Omega)$  be Sobolev-Slobodecki space,  $\mathcal{P} := \{c \in C^\gamma(\bar{\Omega}); \|c\|_{C^\gamma(\bar{\Omega})} \leq M\}$ ,

$\mathcal{B} := \{b \in C^{2+\gamma}(\bar{\Omega}); \partial_\nu b|_{\partial\Omega} = 0, \|b\|_{C^{2+\gamma}(\bar{\Omega})} \leq M, b \geq \delta_0\}$  with arbitrarily chosen

$M > 0$ ,  $\delta_0 > 0$  and  $0 < \gamma < 1$ .

Theorem 1.1 (Imanuvilov-Y. 2023). Let  $\Gamma \subset \partial\Omega$  be arbitrarily chosen and  $0 < \theta < \gamma$ . Then

$$\|c_1 - c_2\|_{H^\theta(\Omega)} \leq C(\|u(c_1, b_1) - u(c_2, b_2)\|_{H^1(\Gamma \times (0, T))} + \|(u(c_1, b_1) - u(c_2, b_2))(\cdot, T)\|_{H^{2+\theta}(\Omega)})$$

for all  $c_1, c_2 \in \mathcal{P}$  and  $b_1, b_2 \in \mathcal{B}$ .

## Key for Proof.

Imanuvilov-Yamamoto (2023): ArXiv 2211.11930

- Global Carleman estimate with the weight:

$$\frac{e^{\lambda d(x)} - e^{2\lambda \|d\|_{C(\bar{\Omega})}}}{t(T-t)}.$$

- compactness-uniqueness argument

Case III:  $t_0 = 0$ . Not completely solved.

$$u(c) : \begin{cases} \partial_t u = \operatorname{div}(a \nabla u) + c(x)u, \\ \partial_\nu u|_{\partial\Omega} = 0, \quad u(\cdot, 0) = u_0. \end{cases}$$

with fixed  $u_0$

Inverse problem. Determine  $c(x)$ ,  $x \in \Omega$  by  $u|_{\Gamma \times (0, T)}$ .

We have no adequate Carleman estimates in this case.

Let  $-Av := \operatorname{div}(a(x)\nabla v) + c(x)v$  with domain  $\{v \in H^2(\Omega); \partial_\nu v|_{\partial\Omega} = 0\}$ .

Theorem 1.2 (Imanuvilov-Y. 2023). Let

$$u_0 \in \mathcal{R}(\exp(-A^{\frac{2}{3}+\varepsilon}\tau)), \quad u_0(x) \neq 0 \quad \text{for all } x \in \overline{\Omega}$$

with some  $\varepsilon > 0, \tau > 0$  and let  $\Gamma \subset \partial\Omega$  be arbitrarily chosen subboundary. Then  $u(c_1) = u(c_2)$  on  $\Gamma \times (0, T)$  implies  $c_1 = c_2$  in  $\Omega$ .

Remarks.

$$(1) u_0 \in \mathcal{R}(\exp(-A^{\frac{2}{3}+\varepsilon}\tau)) \iff \sum_{k=1}^{\infty} (u_0, \varphi_k)^2 \exp(2\lambda_k^{\frac{2}{3}+\varepsilon}\tau) < \infty$$

$\Rightarrow$  very strong regularity.

Here  $A\varphi_k = \lambda_k \varphi_k$  and  $\|\varphi_k\|_{L^2(\Omega)} = 1$  for  $k \in \mathbb{N}$

(2) If  $u_0 \in \mathcal{R}(e^{-A\tau})$ , the uniqueness is trivial:  $u(\cdot, t)$  can be analytically extended to  $(-\tau, 0)$ , and is reduced to Case I:  $0 < t_0 < T$ .

### Technical remarks.

1. Bukhgeim-Klibanov method by Carleman estimate does not work for  $t_0 = 0$ .

2, Transfer to other type of equation:

(A) Reznitskaya transform (similar to Laplace transform)

$\Rightarrow$  reduction of inverse parabolic problem to inverse hyperbolic problem

However, inverse hyperbolic problem by Carleman estimate requires

- geometric constraints on observation subboundary  $\Gamma$
- extra conditions on principal term  $a(x)$ .

$\Rightarrow$  not natural condition for inverse parabolic problem.

(B) Some integral transform reducing inverse parabolic problem to inverse elliptic problem is known (e.g., Romanov: "Inverse Problems of Mathematical Physics" (1987)). However not applicable to our case.

## §2. Inverse hyperbolic problem (I)

$$u(c) : \begin{cases} \frac{\partial^2 u}{\partial t^2} = \operatorname{div}(a \nabla u) + c(x)u, \\ \partial_\nu u|_{\partial\Omega} = 0, \\ u(\cdot, 0) = u_0, \quad \partial_t u(\cdot, 0) = u_1. \end{cases}$$

Inverse hyperbolic problem (global version).

Let  $\omega \subset \Omega$ : subdomain. Determine  $c$  in  $\Omega$  by  $u|_{\omega \times (0, T)}$ .

Wave propagation  $\implies \omega \subset \Omega$  should be large,  $T > 0$  should be large.

Local uniqueness: Bukhgeim-Klibanov

Let  $\nu(x)$  be outward normal vector to  $\partial\Omega$  at  $x$ , set

$$\mathcal{U}_M := \{c \in W^{1,\infty}(\Omega); \|c\|_{W^{1,\infty}(\Omega)} \leq M\} \text{ with arbitrarily fixed } M > 0.$$

Theorem 2.1 (Imanuvilov-Y.:2001) Let

$$\partial\omega \supset \{x \in \partial\Omega; ((x - x_0) \cdot \nu(x)) \geq 0\}$$

$$T > \sup_{\Omega} |x - x_0|$$

for some  $x_0 \notin \overline{\Omega}$  and  $\partial\Omega \setminus \partial\omega$  is locally convex. Let  $|u_0(x)| > 0$  for  $x \in \overline{\Omega}$ ,  $\partial_\nu u(c_k)|_{\partial\Omega} = 0$ ,  $k = 1, 2$ . Then  $\|c_1 - c_2\|_{L^2(\Omega)} \sim \sum_{k=1}^2 \|\partial_t^k (u(c_1) - u(c_2))\|_{L^2(\omega \times (0, T))}$  for all  $c_1, c_2 \in \mathcal{U}_M$ .

**Key of Proof.** Energy estimate + Carleman estimate:

Set  $\varphi(x, t) = e^{\lambda(|x-x_0|^2 - \beta t^2)}$  with large  $\lambda > 0$ . Then  $\exists s_0 > 0$  and  $\exists C > 0$  such that

$$\begin{aligned} & \int_{-T}^T \int_{\Omega} (s|\nabla_{x,t} y|^2 + s^3|y|^2) e^{2s\varphi} dxdt \\ & \leq C \int_{-T}^T \int_{\Omega} |(\partial_t^2 - \Delta)y|^2 e^{2s\varphi} dxdt + C \int_{-T}^T \int_{\omega} (s|\partial_t y|^2 + s^3|y|^2) e^{2s\varphi} dSdt \end{aligned}$$

for all  $s > s_0$  and  $y \in H^2(\Omega \times (-T, T))$  satisfying  $\partial_\nu y|_{\partial\Omega \times (-T, T)} = 0$  and  $\partial_t^j y(\cdot, \pm T) = 0$  in  $\Omega$ ,  $j = 0, 1$ .

Proof is elementary by integration by parts.

Ref: Yamamoto (2023): Rome Lecture Note, Bellassoued and Yamamoto (2017)

### §3. Inverse hyperbolic problem (II):variable wave speeds

Consider  $r(x)\frac{\partial^2 u}{\partial t^2} = \Delta u$ :

Unique continuation: Let  $\Gamma \subset \partial\Omega$ .  $u, \nabla u$  on  $\Gamma \times (0, T)$ ,  $\Rightarrow u$  in a subdomain?

Variable  $r(x) \Rightarrow$  wave speed changes in  $x \Rightarrow$  refraction or cloaking (non-uniqueness)

We need conditions on  $r(x)$  and on  $\Gamma, T$ .

Remark.

Carleman estimate  $\Rightarrow$  uniqueness.

So non-uniqueness implies no Carleman estimate.

Carleman estimate for  $r(x)\partial_t^2 u - \Delta u = F$ . Same recipe of the proof as for the transport equation.

Let  $Q_{\pm} := \Omega \times (-T, T)$  and  $r > 0$  on  $\overline{Q_{\pm}} \in C^2(\overline{Q_{\pm}})$ .

Set  $\varphi(x, t) = d(x) - \beta t^2$  with  $d \in C^2(\overline{\Omega})$  and  $0 < \beta \ll 1$ : chosen later.

**First Step.** Set  $w := ue^{s\varphi}$  and  $Pw := e^{s\varphi}(r(x)\partial_t^2 - \Delta)(e^{-s\varphi}w) \implies$

Installed system with weight:

$$Pw = e^{s\varphi} F, \quad \int_{Q_{\pm}} |u|^2 e^{2s\varphi} dxdt = \int_{Q_{\pm}} |w|^2 dxdt, \quad \text{etc.,}$$

$$\implies \text{lower estimate of } \|Pw\|_{L^2(Q_{\pm})}^2 = \int_{Q_{\pm}} |(r\partial_t^2 - \Delta)u|^2 e^{2s\varphi} dxdt.$$

Decompose  $P = P_1 + P_2$  suitably.

**Second Step.**  $\|Pw\|_{L^2(Q_\pm)}^2 = \|P_1 w + P_2 w\|_{L^2(Q_\pm)}^2 \geq 2(P_1 w, P_2 w)_{L^2(Q_\pm)}.$

Then

- integartion by parts
- salvage  $s^3 \|w\|_{L^2(Q_\pm)}^2 + s \|\nabla_{x,t} w\|_{L^2(Q_\pm)}^2$
- $s > 0$ : large,  $\beta > 0$ : small  $\implies s = o(s^3)$ ,  $\beta = o(1)$ , etc.  $\implies$  Absorb any terms of lower orders in  $s$  and larger orders in  $\beta$ .

$\implies$  estimate (II).

However we can obtain:

$$(P_1 w, P_2 w)_{L^2(Q_\pm)} \geq Cs \int_{Q_\pm} (\nabla r \cdot \nabla \varphi) |\partial_t w|^2 dxdt + \dots + [\text{boundary terms}]!$$

However,  $(\nabla r \cdot \nabla \varphi) > 0$  does not hold even for  $r \equiv 1 \implies$  no estimates of  $|\partial_t w|^2$ .

**Third Step: Auxiliary estimate.** (not necessary for first-order equations)

$[Pw = Fe^{s\varphi}] \times (-sw)$  (usual energy estimate for wave equation)  $\implies$  **estimate (III).**

(II) +  $\theta \times$  (III)  $\implies$  We can salvage  $s^3 \|w\|_{L^2(Q_\pm)}^2 + s \|\nabla_{x,t} w\|_{L^2(Q_\pm)}^2$ .

For salvage, we need condition on  $r$  and choice of  $d$  in  $\varphi(x, t) = d(x) - \beta t^2$ .

Consider  $r(x)\partial_t^2 u - \Delta u - B(x, t) \cdot \nabla_{x,t} u - c(x, t)u = F$  in  $Q_{\pm}$  where  $r \in C^2(\overline{Q_{\pm}})$ ,  $> 0$  and  $B, c \in L^\infty(Q_{\pm})$ . Let  $\sigma_0 > 0$  be a constant such that  $(\partial_i \partial_j d)_{1 \leq i, j \leq d} \geq \sigma_0$  on  $\overline{\Omega}$ .

**Condition on  $r$ .**

$$\left\{ \begin{array}{l} 0 < \theta < 2, \quad \frac{(\nabla r \cdot \nabla d)}{r(x)} > -\theta \sigma_0, \\ (\nabla(|\nabla d|^2) \cdot \nabla d) + \theta \sigma_0 |\nabla d|^2 > 0 \quad \text{on } \overline{\Omega}. \end{array} \right.$$

Set  $\varphi(x, t) := d(x) - \beta t^2$  with  $0 < \beta \ll 1$ .

**Theorem 3.1.**

$$\begin{aligned} \int_{Q_{\pm}} (s|\nabla_{x,t} u|^2 + s^3|u|^2)e^{2s\varphi} dxdt &\leq C \int_{Q_{\pm}} |F|^2 e^{2s\varphi} + C \int_{\partial\Omega \times (-T, T)} (s|\partial_{x,t} u|^2 + s^3|u|^2)e^{2s\varphi} dSdt \\ &\quad + C \int_{\Omega} (s|\nabla_{x,t} u(x, \pm T)|^2 + s^3|u(x, \pm T)|^2)e^{2s\varphi(x, T)} dx \end{aligned}$$

for all large  $s > 0$ .

**Case 1.  $r \equiv 1$ :** Consider  $\frac{\partial^2 u}{t} - \Delta u + (\text{l.o.t}) = F$ .

Set  $\varphi(x, t) = |x - x_0|^2 - \beta t^2$  with  $x_0 \notin \bar{\Omega}$  and  $0 < \beta < 1$ .

Then  $\sigma_0 = 2$  and

$$\nabla(|\nabla d|^2) \cdot \nabla d + \theta \sigma_0 |\nabla d|^2 = (16 + 8\theta)|x - x_0|^2 > 0 \text{ by } x_0 \notin \bar{\Omega}.$$

**Case 2.  $\partial_1 r \geq \exists \delta_0 > 0$  on  $\bar{\Omega}$ .**

Set  $d(x) = \alpha(x_1 - \ell)^2 + |x'|^2$ , where  $x := (x_1, x')$ ,  $x' = (x_2, \dots, x_d)$ , and  $\alpha \gg 1$ ,  $\ell \gg 1$ .

Then

$$\frac{(\nabla r \cdot \nabla d)}{r} = 2\alpha(x_1 - \ell) \frac{\partial_1 r}{r} + \frac{(\nabla_{x'} r \cdot \nabla_{x'} d)}{r} \geq C\alpha\delta_0 - C_1 > 0.$$

Case 3: local Carleman estimate near convex boundary point. Let

(i)  $\Omega$  is convex near  $(0, a)$  with  $a > 0$ .

(ii)  $\partial_2 r(x) \geq 0$  for  $x$  near  $(0, a)$ .

Set  $d(x) = \frac{x^2}{N^2} + \frac{x^2}{(a-\delta)^2}$  with  $N \gg 1$  and  $0 < \delta \ll 1$ . Then Carleman estimate (Theorem 3.1) holds.

We can apply to inverse source problem.

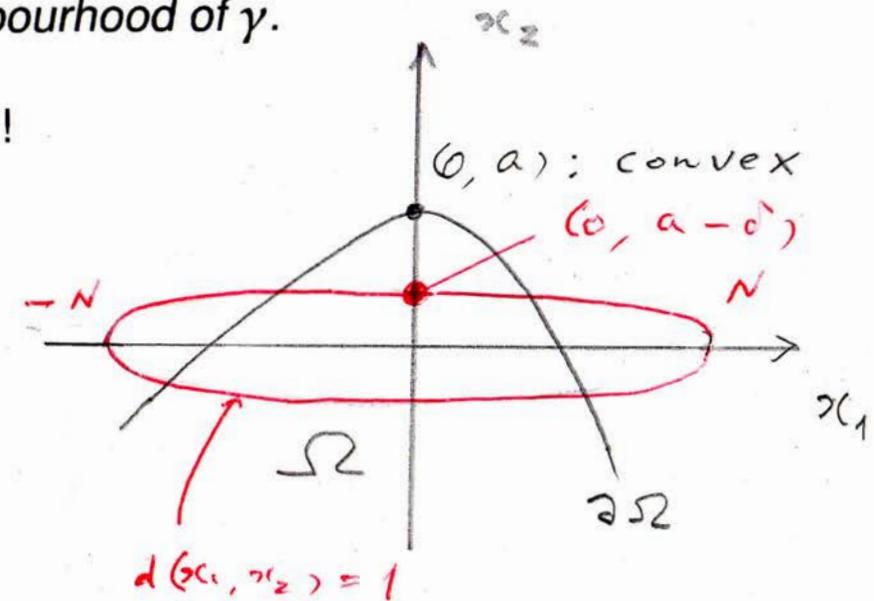
Set  $\gamma = \partial\Omega \cap \{x; |x - (0, a)| < \varepsilon\}$  with small  $\varepsilon > 0$ .

Theorem 3.2 (local uniqueness near convex boundary point).

Let  $r(x)\partial_t^2 u = \Delta u + R(x, t)f(x)$ ,  $u(\cdot, 0) = \partial_t u(\cdot, 0) = 0$  and  $R(\cdot, 0) > 0$  on  $\overline{\Omega}$ . Assume that  $u = \partial_\nu u = 0$  on  $\gamma \times (0, T)$ . Then  $f = 0$  in some neighbourhood of  $\gamma$ .

Remark.  $\partial_2 r \geq 0$  is essential condition for uniqueness!

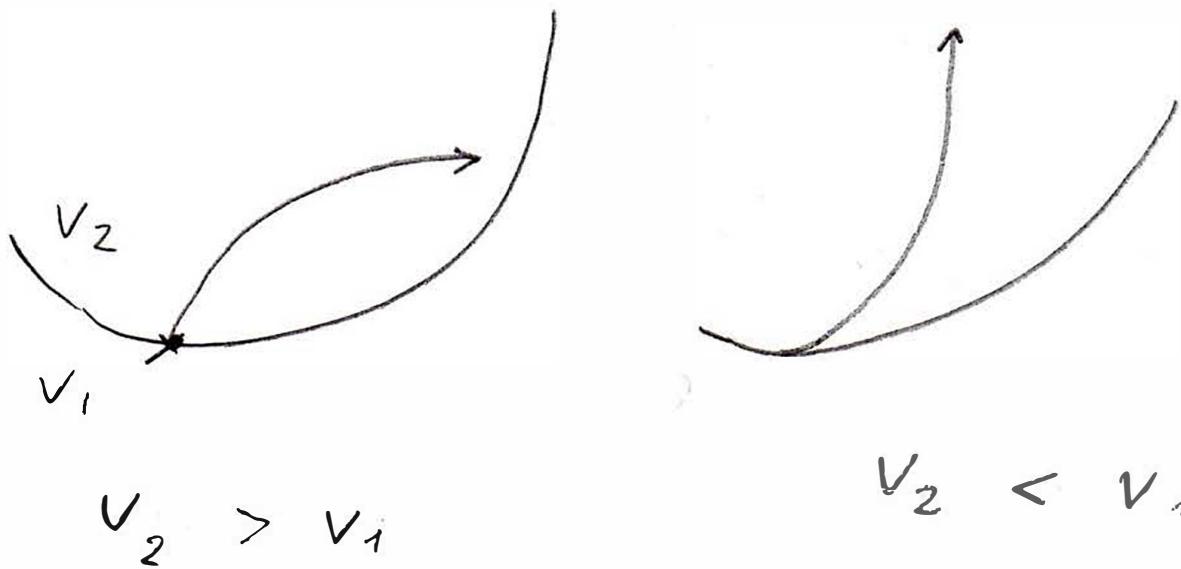
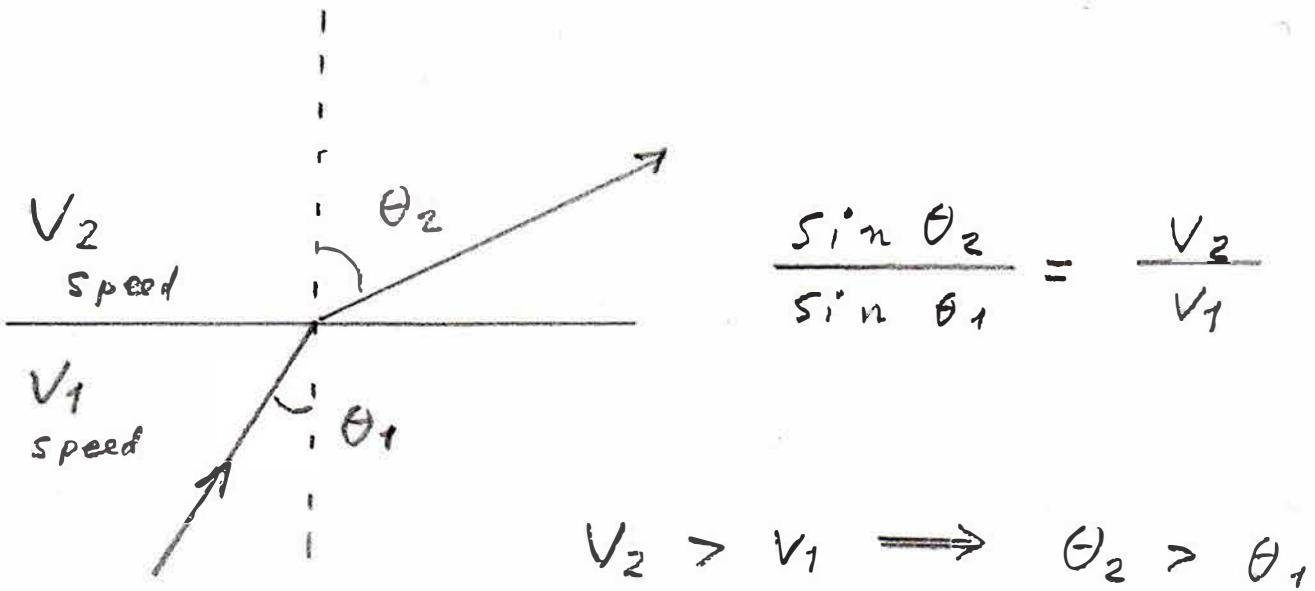
↔ Snell law



**Remark.**  $\partial_2 r \geq 0$  means wave speed is increasing inward to  $\Omega$  and is essential condition for uniqueness!

⇐ Snell law

## Snell law



Signal:  
easy to return

possibly no return

How essential is  $\frac{(\nabla r \cdot \nabla d)}{r} > -2\sigma_0$ ?

Recall  $\varphi(x, t) = d(x) - \beta t^2$ : weight of Carleman estimate and  $(\partial_i \partial_j d)_{1 \leq i, j \leq d} \geq \sigma_0$  on  $\overline{\Omega}$ .

We have an example of hyperbolic equation rejecting Carleman estimate if

$$\frac{(\nabla r \cdot \nabla d)}{r} \leq -4\sigma_0$$

← We can prove by Kumano-go (1963).

However his example has not been understood related to the impossibility of Carleman estimates in terms of

$$\frac{(\nabla r \cdot \nabla d)}{r} \leq -4\sigma_0.$$

Example of hyperbolic equation not admitting Carleman estimates. Let  $\Omega := \{\frac{1}{2} < |x| < 2\}$  and  $r(x) := |x|^{-4}$ . Then solution  $u$  to

$$\partial_t^2 u = |x|^4 \Delta u + \exists b(x, t) \partial_t u + \exists c(x, t) u \quad \text{in } \Omega \times (0, T)$$

satisfies  $u(x, t) = 0$  for  $1 \leq |x| < 2$  and  $t \in \mathbb{R}$ , but  $u(x, t) \neq 0$  for  $\frac{1}{2} < |x| < 1$  and  $t \in \mathbb{R}$ .

This non-uniqueness implies no Carleman estimates.

#### §4. Inverse source problem for transmission wave equation

Discontinuous  $a(x)$ : important in geophysics  $\Leftarrow$  Mohorovičić discontinuity in Earth

Let  $\overline{\Omega_2} \subset \Omega_1$ .

Let  $u_1 := u|_{\Omega_1 \setminus \Omega_2}$  and  $u_2 := u|_{\Omega_2}$  satisfy

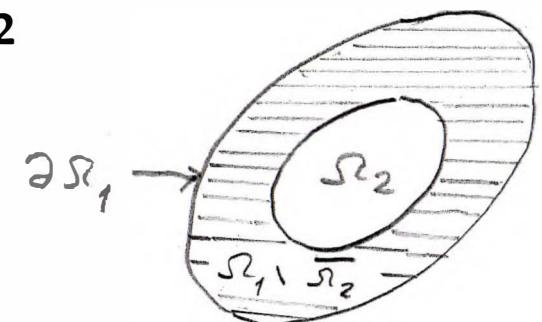
$$\frac{\partial^2 u}{t} = \operatorname{div}(a(x)\nabla u) + F(x, t) \quad \text{in } \Omega_1 \times (0, T),$$

where  $a \in C^2(\overline{\Omega_2})$  and  $a \in C^2(\overline{\Omega_1 \setminus \Omega_2})$

Transmission condition:  $u_1 = u_2$  and  $a_1 \partial_\nu u_1 = a_2 \partial_\nu u_2$  on  $\partial\Omega_2$

Here  $\nu$ : outward normal vector to  $\partial\Omega_2$ ,

$a_1 := a|_{\Omega_1 \setminus \Omega_2}$  and  $a_2 := a|_{\Omega_2}$ .



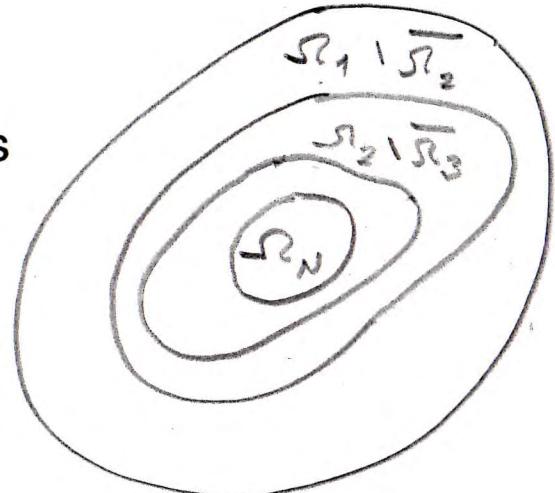
## Main results

Let  $\Omega_N \subset \overline{\Omega_{N-1}} \subset \dots \subset \Omega_2 \subset \Omega_1 \subset \mathbb{R}^n$ : convex bounded domains

such that  $\Omega_k \subset \Omega_{k-1}$  for  $k = 2, \dots, N$ ,

$a_k > 0$ ,  $k = 1, 2, \dots, N$  be constants.

Transmission wave equation:



$$\left\{ \begin{array}{l} \frac{\partial^2}{t^2} y_k = a_k \Delta y_k + R(x, t) f(x), \quad 0 < t < T, \\ x \in \Omega_k \setminus \overline{\Omega_{k+1}} \quad \text{if } k = 1, 2, \dots, N-1, \quad x \in \Omega_N \quad \text{if } k = N, \\ y_{k-1} = y_k, \quad a_{k-1} \partial_\nu y_{k-1} = a_k \partial_\nu y_k \quad \text{on } \partial\Omega_k, \quad k = 2, \dots, N, \\ \text{zero Dirichlet boundary condition on } \partial\Omega_1 \text{ and zero initial condition.} \end{array} \right.$$

$\Omega_k$ ,  $a_k$  and  $R(x, t)$ : given.

Inverse source problem.

Determine  $f(x)$ ,  $x \in \Omega_1$  by  $y_1|_{\partial\Omega_1 \times (0, T)}$ ,  $\nabla y_1|_{\partial\Omega_1 \times (0, T)}$ .

Theorem 4.1 (uniqueness).

Let  $a_k > 0$ ,  $1 \leq k \leq N$  and  $R(x, 0) \neq 0$  for  $x \in \overline{\Omega_1}$ ,  $R \in H^1(0, T; L^\infty(\Omega_1))$ .

Then  $\exists T > 0, \exists t_0 \in (0, T)$  such that

$y_1 = |\nabla y_1| = 0$  on  $\partial\Omega_1 \times (0, T)$  implies  $f = 0$  in  $\Omega_1$  and  $y = 0$  in  $\Omega_1 \times (0, T - t_0)$ .

Henceforth set  $y := y_k$  in  $\Omega_k \setminus \Omega_{k+1}$ ,  $k = 1, \dots, N-1$ ,  $y := y_N$  in  $\Omega_N$

Theorem 4.2 (global Lipschitz stability).

Let  $0 < a_1 < a_2 < \dots < a_N$  and  $R(x, 0) \neq 0$  for  $x \in \overline{\Omega_1}$ ,  $R \in H^2(0, T; L^\infty(\Omega_1))$ . Then  $\exists T_0 > 0, \exists C > 0$  such that

$$C^{-1} \|\partial_\nu \partial_t y_1\|_{L^2(\partial\Omega_1 \times (0, T_0))} \leq \|f\|_{L^2(\Omega)} \leq C \|\partial_\nu \partial_t y_1\|_{L^2(\partial\Omega_1 \times (0, T_0))}$$

for any  $f \in L^2(\Omega_1)$ .

## Remarks

- Bellassoued and Yamamoto (2017): global Carleman estimate for  $N$ -layer **one-dimensional** transmission wave equation
- Baudouin-Mercado-Osses (in Inverse Problems 2007): proved Global Lipschitz stability if  $a_1 < a_2$  for 2-layer case. suggested that assumption  $a_1 < a_2$  is essential in view of Snell's refraction law:  $a_1 > a_2$  may cause trapping of rays so that the uniqueness might fail, **but this is not correct.**
- $a_1 < a_2$  is necessary for global Carleman estimate over the whole domain  $\Omega_1$ . We do not use such global Carleman estimate here.  
⇒ **Assumption  $a_1 < a_2$  is unnecessary for uniqueness.**

## Key

1. Carleman estimate ⇒ uniqueness (Theorem 1)
2. Observability inequality + uniqueness ⇒ global Lipschitz stability (Theorem 2)

## §5. Recent result for Schrödinger equation

Imanuvilov-Yamamoto (2023): ArXiv 2212.13650

$$\sqrt{-1}\partial_t u = \sum_{i,j=1}^d \partial_i(a_{ij}(x)\partial_j u) + \sum_{k=1}^d b_k(x)\partial_k u + c(x, t)u,$$

where  $a_{ij} = a_{ji}$ : real-valued,  $\in C^1(\bar{\Omega})$ , uniformly elliptic,

$b_j \in W^{1,\infty}(\Omega)$ ,  $c \in L^\infty(\Omega)$ : complex-valued.

We consider only

**Unique continuation.** Let  $\Gamma \subset \partial\Omega$  be arbitrarily chosen subboundary and  $T > 0$  be arbitrary.  
 $u = \partial_\nu u = 0$  on  $\Gamma \times (0, T)$  implies  $u \equiv 0$  in  $\Omega \times (0, T)$ ?

**Remark.**  $\Gamma \supsetneq$  (half of  $\partial\Omega$ )  $\Rightarrow$  Yes and observability inequality.

Carleman estimate directly does not produce unique continuation without geometric conditions on  $\Gamma$ .

**Theorem 5.1.** Let  $\Gamma \subset \partial\Omega$ ,  $T > 0$  be arbitrarily chosen. Let  $u \in C([0, T]; H^2(\Omega))$  satisfy

$$\sqrt{-1}\partial_t u = \sum_{i,j=1}^d \partial_i(a_{ij}(x)\partial_j u) + \sum_{k=1}^d b_k(x)\partial_k u + c(x, t)u.$$

If  $u = \partial_\nu u = 0$  on  $\Gamma \times (0, T)$ , then  $u = 0$  in  $\Omega \times (0, T)$ .

**Key of Proof.** Enough to consider  $\sqrt{-1}\partial_t u = \Delta u$ . Then

$$w(x, t) := \int_0^T K(t, \tau)u(x, \tau)d\tau$$

where  $K \in C^\infty([-1, 1] \times [0, T])$  satisfies

$$\begin{cases} \sqrt{-1}\partial_\tau K - \partial_t^2 K(t, \tau) = 0, & -1 < t < 1, 0 < \tau < T, \\ K(-1, \tau) = \psi(\tau) \in C_0^\infty(0, T), & K(\cdot, 0) = K(\cdot, T) = 0. \end{cases}$$

⇒ We reduces to the unique continuation for elliptic equation  $\partial_t^2 w + \Delta w = 0$ .

**Thank you very much!**