

Asymptotically sharp bound for the column subset selection problem

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Outline

- 1 Problem setup
- 2 Our contributions
 - Our first result
 - Our second result

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The column subset selection problem

The column subset selection problem (CSSP) refers the task of using the column submatrix to approximate the column space of a given matrix \mathbf{A} .

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Given a matrix $\mathbf{A} = [\mathbf{a}_1, \dots, \mathbf{a}_d] \in \mathbb{R}^{n \times d}$ and a positive integer k , **the column subset selection problem (CSSP)** aims to find a subset $S \subset \{1, \dots, d\}$ of size k , such that the approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_\xi$ is minimized, where $\xi = 2$ or F denotes the spectral or Frobenius norm, respectively.

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$\mathbf{A}_S \in \mathbb{R}^{n \times k}$: the column submatrix of \mathbf{A} consisting of columns indexed in the k -subset $S \subset \{1, \dots, d\}$.

$\mathbf{A}_S^\dagger \in \mathbb{R}^{k \times n}$: the Moore-Penrose pseudoinverse of \mathbf{A}_S

$\mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A} \in \mathbb{R}^{n \times d}$: a low rank approximation to \mathbf{A} by projecting all the columns of \mathbf{A} to the column space of \mathbf{A}_S .

$\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A} \in \mathbb{R}^{n \times d}$: the residual error matrix.

Why we consider CSSP?

Advantages of CSSP

- take advantage of the sparsity of the input matrix
- make the computed results easy to interpret in terms of the input matrix.

Applications

- machine learning
- scientific computing
- signal processing
- summarizing population genetics
- testing electronic circuits
- recommendation systems
- ...

In this talk I will mainly focus on the spectral norm version of the CSSP.

The spectral norm version of CSSP

Given a matrix $\mathbf{A} \in \mathbb{R}^{n \times d}$ and a positive integer $k \leq \text{rank}(\mathbf{A})$, we aim to find a k -subset $S \subset [d] := \{1, \dots, d\}$ such that the approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2$ is minimized over all possible $\binom{d}{k}$ choices for the k -subsets S .

The CSSP is shown to be NP-hard.

We mainly focus on finding a k -subset S such that the approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2$ is well upper bounded.

Historical background

Historical background

Prior work mainly focuses on finding a k -subset $S \subset [d]$ such that the approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2$ satisfies **the multiplicative bound**

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq p(k, d) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2,$$

where $p(k, d) > 1$ is a function on k and d , and $\mathbf{A}_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^\top$ is the best rank k approximation.

Historical background

- The algorithm (Gu and Eisenstat, 1996) based on rank-revealing QR decomposition gives an efficient deterministic algorithm with the multiplicative bound

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq (1 + c^2 k(d - k)) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2.$$

- The algorithm (Deshpande and Rademacher, 2010) based on the volume sampling, i.e., picking a subset $S \subset [d]$ with probability proportional to $\det[\mathbf{A}_S^\top \mathbf{A}_S]$, outputs a k -subset $S \subset [d]$ such that

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq (d - k)(k + 1) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2.$$

- A two-stage algorithm (Boutsidis, Drineas and Magdon-Ismail, 2014) combining RRQR based algorithms and k -leverage score sampling outputs a k -subset $S \subset [d]$ such that

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq O(k^{\frac{3}{2}} (d - k)^{\frac{1}{2}} \log k) \|\mathbf{A} - \mathbf{A}_k\|_2^2.$$

- The algorithm (Belhadji, Bardenet and Chainais, 2020) based on the projection determinantal point process outputs a k -subset $S \subset [d]$ such that

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq (1 + k(\tilde{d} - k)) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2,$$

where \tilde{d} is the number of the nonzero k -leverage scores.

Overall, the existing multiplicative bounds on $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2$ are $O(k(d-k)) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2$ and $O(k^{\frac{3}{2}}(d-k)^{\frac{1}{2}}) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2$.

The existing multiplicative bounds have the following drawbacks:

- Note that the approximation error does not exceed $\|\mathbf{A}\|_2^2$, i.e.,

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 = \|(\mathbf{I}_n - \mathbf{A}_S \mathbf{A}_S^\dagger) \mathbf{A}\|_2^2 \leq \|\mathbf{A}\|_2^2.$$

However, the existing multiplicative bounds might be larger than $\|\mathbf{A}\|_2^2$ if $\|\mathbf{A} - \mathbf{A}_k\|_2^2 = \sigma_{k+1}^2$ is large enough.

- The existing multiplicative bounds are far from optimal. The lower bound on the approximation error is shown to be $\frac{d}{k} \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2$, so there is a large gap between the lower bound and the existing multiplicative bounds.

There is also a bulk of papers focus on deriving the following **relative-error bounds**:

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2 \leq (1 + \varepsilon) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2,$$

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2 \leq \|\mathbf{A} - \mathbf{A}_k\|_2 + \varepsilon \|\mathbf{A}\|_2,$$

where $\varepsilon > 0$ is a given error parameter.

To achieve the relative error bound, the size of S often needs to be larger than k and it is dependent on the error parameter ε .

In this talk, I mainly focus on the case when the size of S is given as input, so the discussion of the relative-error bounds is beyond the scope of this talk.

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Our first result is an asymptotically sharp bound on the approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2$.

Reformulate the CSSP

For each subset $S \subset [d] = \{1, \dots, d\}$, we define the degree d polynomial

$$p_S(x) := \det[x \cdot \mathbf{I}_d - (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})^\top (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})].$$

A simple observation is that

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 = \maxroot p_S(x).$$

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A simple observation is that

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 = \maxroot p_S(x).$$

Then we can reformulate the spectral norm version of CSSP as follows.

The spectral norm version of CSSP

Given a matrix $\mathbf{A} \in \mathbb{R}^{n \times d}$ and a positive integer $k \leq \text{rank}(\mathbf{A})$, we aim to find a polynomial $p_{\hat{S}}(x)$ in the set $\{p_S(x)\}_{S \subset [d], |S|=k}$, such that the largest root of $p_{\hat{S}}(x)$ is minimized.

Lemma 1 (Jian-Feng Cai, Zhiqiang Xu, Zili Xu)

Let \mathbf{A} be a matrix in $\mathbb{R}^{n \times d}$. Then for each positive integer $k \leq \text{rank}(\mathbf{A})$, there exists a k -subset $\hat{S} \subset [d]$ such that $\text{rank}(\mathbf{A}_{\hat{S}}) = k$ and

$$\maxroot p_{\hat{S}}(x) \leq \maxroot \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \cdot p_S(x).$$

We next estimate the largest root of our expected polynomial.

Lemma 2 (Jian-Feng Cai, Zhiqiang Xu, Zili Xu)

Let $\mathbf{A} \in \mathbb{R}^{n \times d}$ be a matrix of rank $t \leq \min\{d, n\}$. Let λ_i be the i -th largest eigenvalue value of $\mathbf{A}^T \mathbf{A}$. Assume that $\lambda_t < \lambda_1$. Define $\alpha := \frac{t}{\sum_{i=1}^t \lambda_i^{-1}}$ and $\beta := \frac{\lambda_t^{-1} - \alpha^{-1}}{\lambda_t^{-1} - \lambda_1^{-1}} \in [0, 1]$. If $\beta \cdot t \leq k < t$, we have

$$\max_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \cdot p_S(\mathbf{x}) \leq \frac{1}{1 + \mathbf{c}_A \cdot \gamma_{A,k}} \cdot \|\mathbf{A}\|_2^2,$$

where $\mathbf{c}_A := \|\mathbf{A}\|_2^2 / \alpha - 1 > 0$ and $\gamma_{A,k} := \left(\sqrt{\frac{k}{t}} - \sqrt{\frac{\beta}{1-\beta} \cdot \left(1 - \frac{k}{t}\right)} \right)^2 \in [0, 1]$.

Our main results

Theorem A (Jian-Feng Cai, Zhiqiang Xu, Zili Xu)

Let $\mathbf{A} = [\mathbf{a}_1, \dots, \mathbf{a}_d] \in \mathbb{R}^{n \times d}$ be a matrix of rank $t \leq \min\{d, n\}$. For each $1 \leq i \leq t$, let λ_i be the i -th largest eigenvalue value of $\mathbf{A}^\top \mathbf{A}$. Assume that $\lambda_t < \lambda_1$. Define $\alpha := \frac{t}{\sum_{i=1}^t \lambda_i^{-1}}$ and $\beta := \frac{\lambda_t^{-1} - \alpha^{-1}}{\lambda_t^{-1} - \lambda_1^{-1}}$. Then for any positive integer k satisfying $\beta \cdot t \leq k < t$, there exists a subset $S \subset [d]$ of size k such that $\text{rank}(\mathbf{A}_S) = k$ and

$$\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2 \leq \frac{1}{1 + \mathbf{c}_A \cdot \gamma_{A,k}} \cdot \|\mathbf{A}\|_2^2, \quad (1)$$

where $\mathbf{c}_A := \|\mathbf{A}\|_2^2 / \alpha - 1 > 0$ and $\gamma_{A,k} := (\sqrt{\frac{k}{t}} - \sqrt{\frac{\beta}{1-\beta} \cdot (1 - \frac{k}{t})})^2 \in [0, 1]$.

- $\gamma_{A,k}$ is increasing in k , so $\frac{1}{1 + \mathbf{c}_A \cdot \gamma_{A,k}}$ is decreasing in k . As k increases from $\beta \cdot t$ to t , our bound in (1) decreases from $\|\mathbf{A}\|_2^2$ to α .
- The quantity α is a sharp upper bound on the minimal approximation error $\|\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A}\|_2^2$ for $|S| = t - 1$.
- A deterministic polynomial-time algorithm that achieves the bound in (1) is designed.

Comparison to the multiplicative bounds

Advantages:

- Our bound is strictly less than $\|\mathbf{A}\|_2^2$, while the multiplicative bounds $O(k(d-k)) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2$ and $O(k^{\frac{3}{2}}(d-k)^{\frac{1}{2}}) \cdot \|\mathbf{A} - \mathbf{A}_k\|_2^2$ might be larger than $\|\mathbf{A}\|_2^2$.
- Our bound is asymptotically sharp when the matrix $\mathbf{A} \in \mathbb{R}^{n \times d}$ obeys a spectral power-law decay.

Overview of the proof

Proof of Lemma 1

Recall that we define $p_S(x) := \det[x \cdot \mathbf{I}_d - (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})^\top (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})]$ for each subset $S \subset [d]$.

Lemma 1 (Jian-Feng Cai, Zhiqiang Xu, Zili Xu)

Let $\mathbf{A} \in \mathbb{R}^{n \times d}$ be a matrix of rank $t \leq \min\{d, n\}$. Then for each positive integer $k \leq t$, there exists a subset $\hat{S} \subset [d]$ of size k such that $\text{rank}(\mathbf{A}_{\hat{S}}) = k$ and

$$\max_{\text{root}} p_{\hat{S}}(x) \leq \max_{\text{root}} \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \cdot p_S(x). \quad (2)$$

Proof of Lemma 1

A key observation is the following formula

$$\begin{aligned} & k! \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \rho_S(\mathbf{x}) \\ &= \sum_{i_1=1}^d \sum_{i_2 \notin \{i_1\}} \sum_{i_3 \notin \{i_1, i_2\}} \cdots \sum_{i_k \notin \{i_1, \dots, i_{k-1}\}} \det[\mathbf{A}_{\{i_1, \dots, i_k\}}^T \mathbf{A}_{\{i_1, \dots, i_k\}}] \rho_{\{i_1, \dots, i_k\}}(\mathbf{x}). \end{aligned}$$

Our proof of Lemma 1 is algorithmic:

Based on the above formula, we design a greedy algorithm which iteratively add columns to \hat{S} , and we show that the output \hat{S} of our greedy algorithm satisfies (2).

Proof of Lemma 1

Our greedy algorithm (iteratively select k columns from $\mathbf{A} \in \mathbb{R}^{n \times d}$):

Step 1 Set $\hat{S} = \emptyset$. Observe that

$$\begin{aligned}
& k! \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \rho_S(\mathbf{x}) \\
= & \sum_{i_1=1}^d \sum_{i_2 \notin \{i_1\}} \sum_{i_3 \notin \{i_1, i_2\}} \cdots \sum_{i_k \notin \{i_1, \dots, i_{k-1}\}} \det[\mathbf{A}_{\{i_1, \dots, i_k\}}^T \mathbf{A}_{\{i_1, \dots, i_k\}}] \rho_{\{i_1, \dots, i_k\}}(\mathbf{x}) \\
=: & \sum_{i_1=1}^d \mathbf{f}_{i_1}(\mathbf{x}).
\end{aligned}$$

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 =: & \sum_{i_1=1}^d \mathbf{f}_{i_1}(\mathbf{x}).
 \end{aligned}$$

We next investigate the interlacing property of the polynomials $\mathbf{f}_1(\mathbf{x}), \dots, \mathbf{f}_d(\mathbf{x})$.

The method of interlacing polynomials

Definition of interlacing

Let $g(x) = a_0 \cdot \prod_{i=1}^{d-1} (x - a_i)$ and $f(x) = b_0 \cdot \prod_{i=1}^d (x - b_i)$ be two real-rooted polynomials. We say that $g(x)$ **interlaces** $f(x)$ if

$$b_1 \leq a_1 \leq b_2 \leq a_2 \leq \dots \leq a_{d-1} \leq b_d.$$

Definition of common interlacing

We say that real-rooted degree d polynomials $f_1(x), \dots, f_m(x)$ have a **common interlacing** if there exists a polynomial $g(x)$ such that $g(x)$ interlaces $f_i(x)$ for each $i \in \{1, \dots, m\}$.

Figure 1: $g(x)$ interlaces $f(x)$

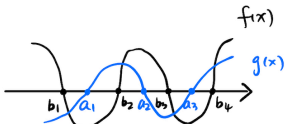
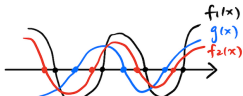


Figure 2: $f_1(x)$ and $f_2(x)$ have a common interlacing



The method of interlacing polynomials

The method of interlacing polynomials is a useful tool to **control the largest root of polynomials**.

Theorem (Marcus-Spielman-Srivastava, 2014)

Let $\mathcal{F} = \{f_1(x), \dots, f_m(x)\}$ be a collection of real-rooted polynomials with the same degree and positive leading coefficients.

If $f_1(x), \dots, f_m(x)$ have a common interlacing, then there exists an integer $i \in \{1, \dots, m\}$ such that

$$\maxroot f_i(x) \leq \maxroot \sum_{i=1}^m f_i(x). \quad (3)$$

- The above theorem basically says that the largest root of the expected polynomial provides an upper bound on the smallest largest root of $f_i(x)$.
- If $f_1(x), \dots, f_m(x)$ fail to have a common interlacing, then (3) may not hold. For example, consider the case where $f_1(x) = (x + 5)(x - 9)(x - 10)$ and $f_2(x) = (x + 6)(x - 1)(x - 8)$. The largest root of $f_1(x) + f_2(x)$ is approximately 7.4.

Proof of Lemma 1

Our greedy algorithm (iteratively select k columns from $\mathbf{A} \in \mathbb{R}^{n \times d}$):

Step 1: $\hat{S} = \emptyset$. Observe that

$$\begin{aligned}
 k! \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] p_S(x) &= \sum_{i_1=1}^d \sum_{i_2 \notin \{i_1\}} \sum_{i_3 \notin \{i_1, i_2\}} \cdots \sum_{i_k \notin \{i_1, \dots, i_{k-1}\}} \det[\mathbf{A}_{\{i_1, \dots, i_k\}}^T \mathbf{A}_{\{i_1, \dots, i_k\}}] p_{\{i_1, \dots, i_k\}}(x) \\
 &=: \sum_{i_1=1}^d f_{i_1}(x).
 \end{aligned}$$

We prove that the polynomials $f_1(x), \dots, f_d(x)$ have a common interlacing.

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 &=: \sum_{i_1=1}^d f_{i_1}(\mathbf{x}).
 \end{aligned}$$

We prove that the polynomials $f_1(\mathbf{x}), \dots, f_d(\mathbf{x})$ have a common interlacing.

Then there exists an integer $j_1 \in [d]$ such that

$$\maxroot f_{j_1}(\mathbf{x}) \leq \maxroot \sum_{i_1=1}^d f_{i_1}(\mathbf{x}) = \maxroot \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] p_S(\mathbf{x}).$$

Then we set $\hat{S} = \{j_1\}$.

Proof of Lemma 1

Step 2: $\hat{S} = \{j_1\}$. Observe that

$$\begin{aligned}
 f_{j_1}(x) &= \sum_{i_2 \notin \{j_1\}} \sum_{i_3 \notin \{j_1, i_2\}} \cdots \sum_{i_k \notin \{j_1, i_2, \dots, i_{k-1}\}} \det[\mathbf{A}_{\{j_1, i_2, \dots, i_k\}}^T \mathbf{A}_{\{j_1, i_2, \dots, i_k\}}] p_{\{j_1, i_2, \dots, i_k\}}(x) \\
 &=: \sum_{i_2 \notin \{j_1\}} g_{i_2}(x).
 \end{aligned}$$

Proof of Lemma 1

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We prove that the polynomials $g_{i_2}(x), \forall i_2 \notin \{j_1\}$ have a common interlacing.

Proof of Lemma 1

Step 2: $\hat{S} = \{j_1\}$. Observe that

$$\begin{aligned}
 f_{j_1}(x) &= \sum_{i_2 \notin \{j_1\}} \sum_{i_3 \notin \{j_1, i_2\}} \cdots \sum_{i_k \notin \{j_1, i_2, \dots, i_{k-1}\}} \det[\mathbf{A}_{\{j_1, i_2, \dots, i_k\}}^T \mathbf{A}_{\{j_1, i_2, \dots, i_k\}}] p_{\{j_1, i_2, \dots, i_k\}}(x) \\
 &=: \sum_{i_2 \notin \{j_1\}} g_{i_2}(x).
 \end{aligned}$$

We prove that the polynomials $g_{i_2}(x), \forall i_2 \notin \{j_1\}$ have a common interlacing.

Then there exists $j_2 \notin \{j_1\}$ such that

$$\maxroot g_{j_2}(x) \leq \maxroot \sum_{i_2 \notin \{j_1\}} g_{i_2}(x) = \maxroot f_{j_1}(x) \stackrel{\text{by Step 1}}{\leq} \maxroot \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] p_S(x).$$

Then we set $\hat{S} = \{j_1, j_2\}$.

Repeat the above argument for another $k - 2$ times.

Proof of Lemma 1

Step k: $\hat{S} = \{j_1, \dots, j_{k-1}\}$. We prove that the polynomials

$$\det[\mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}^T \mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}] \rho_{\{j_1, \dots, j_{k-1}, i_k\}}(\mathbf{x}), \forall i_k \notin \{j_1, \dots, j_{k-1}\}$$

have a common interlacing.

Proof of Lemma 1

Step k: $\hat{S} = \{j_1, \dots, j_{k-1}\}$. We prove that the polynomials

$$\det[\mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}^T \mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}] p_{\{j_1, \dots, j_{k-1}, i_k\}}(\mathbf{x}), \forall i_k \notin \{j_1, \dots, j_{k-1}\}$$

have a common interlacing.

Then there exists $j_k \notin \{j_1, \dots, j_{k-1}\}$ such that

$$\begin{aligned} \max_{\text{root}} p_{\{j_1, \dots, j_{k-1}, j_k\}}(\mathbf{x}) &\leq \max_{\text{root}} \sum_{i_k \notin \{j_1, \dots, j_{k-1}\}} \det[\mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}^T \mathbf{A}_{\{j_1, \dots, j_{k-1}, i_k\}}] p_{\{j_1, \dots, j_{k-1}, i_k\}}(\mathbf{x}) \\ &\stackrel{\text{by Step k-1}}{\leq} \dots \stackrel{\text{by Step 1}}{\leq} \max_{\text{root}} \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] p_S(\mathbf{x}). \end{aligned}$$

Then we set $\hat{S} = \{j_1, j_2, \dots, j_k\}$. This finishes the proof of Lemma 1.

Polynomial Selection Problem

The method of interlacing polynomials is a useful tool for the **Polynomial Selection Problem**.

Polynomial Selection Problem

Let $\mathcal{F} = \{f_1(x), \dots, f_m(x)\}$ be a collection of degree d polynomials with positive leading coefficients. Each polynomial in \mathcal{F} is real-rooted, i.e., all of the coefficients and roots are real numbers. We aim to select a polynomial $f_i(x)$ from \mathcal{F} such that the largest root of $f_i(x)$ is as small as possible.

When m is large, it is very inefficient to calculate the largest root of each polynomial and then compare them to choose the smallest one.

Polynomial Selection Problem

The method of interlacing polynomials is a useful tool for the **Polynomial Selection Problem**.

Polynomial Selection Problem

Let $\mathcal{F} = \{f_1(x), \dots, f_m(x)\}$ be a collection of degree d polynomials with positive leading coefficients. Each polynomial in \mathcal{F} is real-rooted, i.e., all of the coefficients and roots are real numbers. We aim to select a polynomial $f_i(x)$ from \mathcal{F} such that the largest root of $f_i(x)$ is as small as possible.

When m is large, it is very inefficient to calculate the largest root of each polynomial and then compare them to choose the smallest one.

Example 1: Spectral norm version of CSSP

Let $\mathcal{F} = \{p_S(x)\}_{S \subset [d], |S|=k}$, where

$$p_S(x) := \det[x \cdot \mathbf{I}_d - (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})^T (\mathbf{A} - \mathbf{A}_S \mathbf{A}_S^\dagger \mathbf{A})].$$

We aim to find a polynomial $p_{\hat{S}}(x)$ in \mathcal{F} , such that the largest root of $p_{\hat{S}}(x)$ is minimized.

Polynomial Selection Problem

Example 2: Matrix Spencer Conjecture

For all matrices $\mathbf{A}_1, \dots, \mathbf{A}_n \in \mathbb{R}^{d \times d}$ with $\|\mathbf{A}_i\|_2 \leq 1$, there exists $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n) \in \{\pm 1\}^n$ such that $\|\sum_{i=1}^n \varepsilon_i \mathbf{A}_i\|_2 \leq O(\sqrt{n \log(d/n)})$.

An equivalent statement is as follows.

Let $\mathcal{F} = \{f_\varepsilon(x)\}_{\varepsilon \in \{\pm 1\}^n}$, where

$$f_\varepsilon(x) := \det[x \cdot \mathbf{I}_d - (\sum_{i=1}^n \varepsilon_i \mathbf{A}_i)^T (\sum_{i=1}^n \varepsilon_i \mathbf{A}_i)].$$

There exists a polynomial $f_{\hat{\varepsilon}}(x)$ in \mathcal{F} , such that the largest root of $f_{\hat{\varepsilon}}(x)$ is $O(n \log(d/n))$.

Recently some special cases of Matrix Spencer Conjecture is proved by using the method of interlacing polynomials.

Proof of Lemma 2: Estimate the largest root of the expected polynomial

Lemma 3

Let \mathbf{A} be a matrix in $\mathbb{R}^{n \times d}$. For any nonnegative integer k , we have

$$k! \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \cdot p_S(x) = (-1)^k \cdot \mathcal{R}_d \cdot \partial_x^k \cdot \mathcal{R}_d \det[x \cdot \mathbf{I}_d - \mathbf{A}^T \mathbf{A}],$$

where operator \mathcal{R}_d is defined as $\mathcal{R}_d f(x) := x^d \cdot f(\frac{1}{x})$ for any degree d polynomial $f(x)$.

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Observe that, if all roots of a degree d polynomial $f(x)$ are positive, then

$$\maxroot \mathcal{R}_d f(x) = \frac{1}{\minroot f(x)} \quad (4)$$

Combining Lemma 3 and (4), we obtain

$$\maxroot \sum_{S \subset [d], |S|=k} \det[\mathbf{A}_S^T \mathbf{A}_S] \cdot p_S(x) = \frac{1}{\minroot \partial_x^k \cdot \mathcal{R}_d \det[x \cdot \mathbf{I}_d - \mathbf{A}^T \mathbf{A}]}$$

Proof of Lemma 2

The following lemma shows how the largest root of a univariate polynomial shrink after taking derivatives.

Lemma (Ravichandran 2020)

Assume that $p(x) = \prod_{i=1}^t (x - \lambda_i)$ is a real-rooted polynomial of degree t , where $\lambda_i \in [0, 1]$ for each $i \in [t]$. Let $\gamma = \frac{1}{t} \sum_{i=1}^t \lambda_i$. Then, for each $k \geq \gamma \cdot t$,

$$\maxroot \partial_x^k p(x) \leq \left(\sqrt{\gamma \cdot \frac{k}{t}} + \sqrt{(1 - \gamma) \cdot \left(1 - \frac{k}{t}\right)} \right)^2.$$

With some slight modification, we are able to use this lemma to estimate $\minroot \partial_x^k \cdot \mathcal{R}_d \det[x \cdot \mathbf{I}_d - \mathbf{A}^T \mathbf{A}]$ and prove Lemma 2.

Outline

- 1 Problem setup
- 2 Our contributions
 - Our first result
 - Our second result

Our second result

Our second results

We show that our method also works in the context of the column partition problem .

The column partition problem

Given a matrix $\mathbf{A} \in \mathbb{R}^{n \times d}$ and a positive integer $r \geq 2$, **the column partition problem** aims to find an r partition $S_1 \sqcup \dots \sqcup S_r = [d]$ such that the following residual

$$\max_{1 \leq i \leq r} \|\mathbf{A} - \mathbf{A}_{S_i^c} \mathbf{A}_{S_i}^\dagger \mathbf{A}\|_2$$

is minimized over all possible r partitions of $[d]$. Here, we use S^c to denote the complement of a subset S of $[d]$.

Our results

We show that our method also works in the context of the column partition problem .

Theorem B

Assume that $n \geq d > 1$. Let $\mathbf{A} \in \mathbb{R}^{n \times d}$ be a matrix of rank d . For each $j \in \{1, \dots, d\}$, let λ_j be the j -th largest eigenvalue value of $\mathbf{A}^T \mathbf{A}$. Define

$$\alpha := \max_{1 \leq j \leq d} \mathbf{a}_j^T (\mathbf{I}_n - \mathbf{A}_{\{1, \dots, d\} \setminus \{j\}} \mathbf{A}_{\{1, \dots, d\} \setminus \{j\}}^\dagger) \mathbf{a}_j \quad \text{and} \quad \beta := \frac{\lambda_d^{-1} - \alpha^{-1}}{\lambda_d^{-1} - \lambda_1^{-1}}.$$

Then for any integer $r \geq 2$ satisfying that $\beta \leq \frac{(r-1)^2}{r^2}$, there exists an r partition $S_1 \sqcup \dots \sqcup S_r = \{1, \dots, d\}$ such that

$$\|\mathbf{A} - \mathbf{A}_{S_i} \mathbf{A}_{S_i}^\dagger \mathbf{A}\|_2^2 \leq \frac{1}{\gamma_{\mathbf{A}, r} + (1 - \gamma_{\mathbf{A}, r}) \cdot \frac{\lambda_1}{\lambda_d}} \cdot \|\mathbf{A}\|_2^2, \quad \forall i \in [r], \quad (5)$$

where $\gamma_{\mathbf{A}, r} := \left(\sqrt{\frac{1}{r} - \frac{\beta}{r-1}} + \sqrt{\beta} \right)^2 \in [1/r, 1]$.

Thanks for your attention!