

# Chapter 6. Restricted Isometry Property

I-Liang Chern

October 13, 2016

# Restricted Isometry Property

## Definition

Given  $m \times N$  matrix  $\mathbf{A}$ , its  $s$ th restricted isometry constant  $\delta_s$  is the smallest constant  $\delta$  such that

$$(1 - \delta)\|\mathbf{x}\|^2 \leq \|\mathbf{A}\mathbf{x}\|^2 \leq (1 + \delta)\|\mathbf{x}\|^2 \quad \forall \mathbf{x} \in \Sigma_s \quad (0.1)$$

## Lemma

$$\delta_s = \max_{|S| \leq s} \|\mathbf{A}_S^* \mathbf{A}_S - Id\|_{2 \rightarrow 2}^2.$$

1. Proof. For  $x \in \Sigma_s$ ,

$$\|Ax\|^2 = \langle A_S x, A_S x \rangle = \langle A_S^* A_S x, x \rangle$$

$$\|Ax\|^2 - \|x\|^2 = \langle (A_S^* A_S - Id)x, x \rangle.$$

$$\delta_s = \max_{|S| \leq s} \sup_{\text{supp } x=S} \frac{|\|Ax\|^2 - \|x\|^2|}{\|x\|^2} = \max_{|S| \leq s} \|A_S^* A_S - Id\|_{2 \rightarrow 2}^2$$

2. Remark.  $A_S^* A_S - Id$  is a self-adjoint matrix. Its spectrum satisfies

$$\sigma(A_S^* A_S) \subset [\lambda_{\min}, \lambda_{\max}].$$

We then have

$$\|A_S^* A_S - Id\|_{2 \rightarrow 2} = \max\{|\lambda_{\max} - 1|, |\lambda_{\min} - 1|\}.$$

# Mutual incoherence and RIP

Connection between MI and RIP:

$$\delta_s \leq \mu_1(s-1) \leq (s-1)\mu.$$

Proof. Recall the theorem:

**Theorem.** We have: for all  $s$ -sparse vector  $x$

$$(1 - \mu_1(s-1)) \|x\|_2^2 \leq \|Ax\|_2^2 \leq (1 + \mu_1(s-1)) \|x\|_2^2.$$

Equivalently, the spectrum

$$\sigma(A_S^* A_S) \subset [1 - \mu_1(s-1), 1 + \mu_1(s-1)]$$

for all  $S$  with  $|S| \leq s$ . Thus,

$$\max\{|\lambda_{\min} - 1|, |\lambda_{\max} - 1|\} \leq \mu_1(s-1).$$

## Proposition

Suppose  $u \in \Sigma_s$  and  $v \in \Sigma_t$  and  $\text{supp } u \cap \text{supp } v = \emptyset$ . Then

$$|\langle Au, Av \rangle| \leq \delta_{s+t} \|u\| \|v\|.$$

Proof.

1. Let  $S = \text{supp } u \cup \text{supp } v$ . We have  $u_S = u$ ,  $v_S = v$ .
2. Since  $\text{supp } u \cap \text{supp } v = \emptyset$ , we have  $\langle u_S, v_S \rangle = 0$ .

$$\begin{aligned} |\langle Au, Av \rangle| &= |\langle A_S u_S, A_S v_S \rangle - \langle u_S, v_S \rangle| = |\langle (A_S^* A_S - Id) u_S, v_S \rangle| \\ &\leq \|A_S^* A_S - Id\|_{2 \rightarrow 2} \|u_S\| \|v_S\| \leq \delta_{s+t} \|u\| \|v\|. \end{aligned}$$

Remark. This means that if  $\text{supp } u \cap \text{supp } v = \emptyset$ , then  $\langle Au, Av \rangle$  will be small.

# RIP and Exact Recovery via Basis Pursuit

## Theorem

If  $\delta_{2s} \leq 1/3$ , then every  $x \in \Sigma_s$  is the unique solution of

$$(P1) \quad \min \|z\|_1 \quad \text{subject to } Az = Ax.$$

Key ideas of the proof.

- ▶ Goal: show  $\exists \rho < 1$  such that  $\|v_S\|_1 \leq \rho \|v_{\bar{S}}\|_1$  for all  $v \in N(A)$ .
- ▶ Estimate  $\|v\|_1$  in terms of  $\|v\|_2$ .
- ▶ Estimate  $\|v\|_2$  through  $\|Av\|_2^2$ . Use RIP.

## Proof.

1. By the Null space property, we should show: for any  $v \in N(A)$ ,  
 $\|v_S\|_1 < \|v_{\bar{S}}\|_1$ , or equivalently  $\|v_S\|_1 < \frac{1}{2}\|v\|_1$ .
2. We show stronger statement: (use  $\|v_S\|_1 \leq \sqrt{s}\|v_S\|_2$ )

$$\|v_S\|_2 \leq \frac{\rho}{2\sqrt{s}}\|v\|_1, \quad \rho = \frac{2\delta_{2s}}{1-\delta_{2s}} < 1 \quad (\text{if } \delta_{2s} < 1/3).$$

3. Define index set  $S_0, S_1, \dots$ , each size is  $s$ .  $S_0$  is the index set of the  $s$  largest entries of  $|v|$ ,  $S_1$  is the next  $s$  largest, and so on. Thus,  $v = v_{S_0} + v_{S_1} + \dots$ , and  $Av_{S_0} = -\sum_{k \geq 1} Av_{S_k}$ .

4.

$$\begin{aligned} \|v_{S_0}\|^2 &\leq \frac{1}{1-\delta_{2s}} \|Av_{S_0}\|^2 = \frac{1}{1-\delta_{2s}} \langle Av_{S_0}, -\sum_{k \geq 1} Av_{S_k} \rangle \\ &\leq \frac{\delta_{2s}}{1-\delta_{2s}} \|v_{S_0}\| \sum_{k \geq 1} \|v_{S_k}\| \leq \frac{\rho}{2} \|v_{S_0}\| \sum_{k \geq 1} \frac{\|v_{S_{k-1}}\|_1}{\sqrt{s}} \leq \frac{\rho}{2\sqrt{s}} \|v_{S_0}\| \|v\|_1. \end{aligned}$$

5. Here, we use a lemma: If  $u, v$  are  $s$ -sparse and  $\max |u_i| \leq \min |v_j|$ , then  $\|u\|_2 \leq \frac{1}{\sqrt{s}}\|v\|_1$ .

$$\frac{\|u\|_2}{\sqrt{s}} = \left( \frac{1}{s} \sum_{i=1}^s |u_i|^2 \right)^{1/2} \leq \max |u_i| \leq \min |v_j| \leq \frac{1}{s} \sum_{j=1}^s |v_j|.$$

# RIP and robust recovery via basis pursuit

## Theorem

Given  $m \times N$  matrix  $A$ . Suppose  $\delta_{2s}(A) \leq \frac{4}{\sqrt{41}} \approx 0.6246$ ,  
Then for any  $x$  and  $y$  with  $\|Ax - y\|_2 \leq \eta$ , a solution  $x^\#$  of

$$(P_{1,\eta}) \quad \min \|z\|_1 \quad \text{subject to } \|Az - y\|_2 \leq \eta$$

has estimates

$$\|x^\# - x\|_1 \leq C\sigma_s(x)_1 + D\sqrt{s}\eta$$

$$\|x^\# - x\|_2 \leq \frac{C}{\sqrt{s}}\sigma_s(x)_1 + D\eta$$

with  $C$  and  $D$  depending on  $\delta_{2s}$ .



## Proof. 1

1. Given  $v$  and  $s$ , we define index sets  $S_0, S_1, \dots$  according to magnitude of  $v_i$  of  $v$  as before. We want to show  $\|v_{S_0}\|_2 \leq \frac{\rho}{\sqrt{s}} \|v_{S_0}\|_1 + \tau \|Av\|_2$ .
2. Define  $t$  such that  $\|Av_{S_0}\|^2 = (1+t)\|v_{S_0}\|^2$ , where  $|t| \leq \delta_s$ .
3. We claim  $|\langle Av_{S_0}, Av_{S_k} \rangle| \leq \sqrt{\delta_{2s}^2 - t^2} \|v_{S_0}\| \|v_{S_k}\|$  for  $k \geq 1$ .  
Take  $u = v_{S_0} / \|v_{S_0}\|$ ,  $w = e^{i\theta} v_{S_k} / \|v_{S_k}\|$ ,  $\theta$  is chosen so that  $|\langle Au, Aw \rangle| = \operatorname{Re} \langle Au, Aw \rangle$ . Notice  $\operatorname{supp} u \cap \operatorname{supp} w = \emptyset \Rightarrow \langle u, w \rangle = 0$ .

$$\begin{aligned}
 2|\langle Au, Aw \rangle| &= \frac{1}{\alpha + \beta} (\|A(\alpha u + w)\|^2 - \|A(\beta u - w)\|^2 - (\alpha^2 - \beta^2) \|Au\|^2) \\
 &\leq \frac{1}{\alpha + \beta} ((1 + \delta_{2s}) \|\alpha u + w\|^2 - (1 - \delta_{2s}) \|\beta u - w\|^2 - (\alpha^2 - \beta^2)(1+t) \|u\|^2) \\
 &= \frac{1}{\alpha + \beta} ((1 + \delta_{2s})(\alpha^2 + 1) - (1 - \delta_{2s})(\beta^2 + 1) - (\alpha^2 - \beta^2)(1+t)) \\
 &= \frac{1}{\alpha + \beta} (\alpha^2(\delta_{2s} - t) + \beta^2(\delta_{2s} + t) + 2\delta_{2s}).
 \end{aligned}$$

Choose  $\alpha = (\delta_{2s} + t) / \sqrt{\delta_{2s} - t^2}$ ,  $\beta = (\delta_{2s} - t) / \sqrt{\delta_{2s} - t^2}$ , we prove the claim.

## Cont. 2

4

$$\begin{aligned} \|Av_{S_0}\|^2 &= \left\langle Av_{S_0}, A\left(v - \sum_{k \geq 1} v_{S_k}\right) \right\rangle \leq \|Av_{S_0}\| \|Av\| + \sum_{k \geq 1} \sqrt{\delta_{2s}^2 - t^2} \|v_{S_0}\| \|v_{S_k}\| \\ &= \|v_{S_0}\| \left[ \sqrt{1+t} \|Av\| + \sqrt{\delta_{2s}^2 - t^2} \sum_{k \geq 1} \|v_{S_k}\| \right] \end{aligned}$$

5 We will use a lemma: Suppose  $\{a_i\}_{i=1}^s$  is nonnegative decreasing sequence.

Then

$$\|a\|_2 \leq \frac{\|a\|_1}{\sqrt{s}} + \frac{\sqrt{s}}{4} (a_1 - a_s).$$

$$\begin{aligned} \sum_{k \geq 1} \|v_{S_k}\| &\leq \sum_{k \geq 1} \left( \frac{1}{\sqrt{s}} \|v_{S_k}\|_1 + \frac{\sqrt{s}}{4} (v_k^+ - v_k^-) \right) \\ &\leq \frac{1}{\sqrt{s}} \|v_{S_0}\|_1 + \frac{\sqrt{s}}{4} v_1^+ \leq \frac{1}{\sqrt{s}} \|v_{S_0}\|_1 + \frac{1}{4} \|v_{S_0}\| \end{aligned}$$

Here, we use  $v_1^+ \leq \frac{1}{s} \|v_{S_0}\|_1 \leq \frac{1}{\sqrt{s}} \|v_{S_0}\|_2$ .

### Cont. 3

6 Replacing  $\|Av_{S_0}\|^2$  by  $(1+t)\|v_{S_0}\|^2$  in 4, and plug 5 into 4, we get

$$\begin{aligned}(1+t)\|v_{S_0}\| &\leq \sqrt{1+t}\|Av\| + \sqrt{\delta_{2s}^2 - t^2} \left( \frac{1}{\sqrt{s}} \|v_{\overline{S_0}}\|_1 + \frac{1}{4} \|v_{S_0}\| \right) \\ &\leq (1+t) \left( \frac{1}{\sqrt{1+t}} \|Av\| + \frac{\delta_{2s}}{\sqrt{s}\sqrt{1-\delta_{2s}^2}} \|v_{\overline{S_0}}\|_1 + \frac{\delta_{2s}}{4\sqrt{1-\delta_{2s}^2}} \|v_{S_0}\| \right)\end{aligned}$$

Here, we use  $|t| \leq \delta_s \leq \delta_{2s}$  and  $(\delta_{2s}^2 - t^2)/(1+t)^2 \leq \delta_{2s}^2/(1-\delta_{2s}^2)$ .

$$\|v_{S_0}\| \leq \frac{\delta_{2s}}{\sqrt{1-\delta_{2s}^2} - \delta_{2s}/4} \frac{\|v_{\overline{S_0}}\|_1}{\sqrt{s}} + \frac{\sqrt{1+\delta_{2s}}}{\sqrt{1-\delta_{2s}^2} - \delta_{2s}/4} \|Av\|$$

7 Now, we take

$$\rho := \frac{\delta_{2s}}{\sqrt{1-\delta_{2s}^2} - \delta_{2s}/4} < 1,$$

which is equivalent to  $41\delta_{2s}^2 < 16$ .

Proof of the lemma: Suppose  $\{a_i\}_{i=1}^s$  is nonnegative decreasing sequence. Then

$$\|a\|_2 \leq \frac{\|a\|_1}{\sqrt{s}} + \frac{\sqrt{s}}{4}(a_1 - a_s).$$

1. Equivalent statement (due to homogeneity)

$$\left. \begin{array}{l} a_1 \geq a_2 \geq \dots \geq a_s \geq 0 \\ \frac{1_1 + a_2 + \dots + a_s}{\sqrt{s}} + \frac{\sqrt{s}}{4} a_1 \leq 1 \end{array} \right\} \Rightarrow \sqrt{a_1^2 + a_2^2 + \dots + a_s^2} + \frac{\sqrt{s}}{4} a_s \leq 1.$$

So we aim at the optimization problem:

$$\max f(a_1, \dots, a_s) := \sqrt{a_1^2 + a_2^2 + \dots + a_s^2} + \frac{\sqrt{s}}{4} a_s$$

over the convex polytope

$$\left\{ a_1 \geq a_2 \geq \dots \geq a_s \text{ and } \frac{1_1 + a_2 + \dots + a_s}{\sqrt{s}} + \frac{\sqrt{s}}{4} a_1 \leq 1 \right\}$$

2. The boundary occurs at  $s$  equalities. There are the following possibilities

- ▶  $a_1 = \dots = a_s = 0$ : this leads to  $f(a_1, \dots, a_s) = 0$ .
- ▶  $(a_1 + \dots + a_s)/\sqrt{s} + \sqrt{s}a_1/4 = 1$  and  $a_1 = \dots = a_k > a_{k+1} = \dots = a_s = 0$  for some  $1 \leq k \leq s - 1$ : in this case,  $a_1 = \dots = a_k = 4\sqrt{s}/(4k + s)$  and  $f(a_1, \dots, a_s) = 4\sqrt{ks}/(4k + s) \leq 1$ .
- ▶  $(a_1 + \dots + a_s)/\sqrt{s} + \sqrt{s}a_1/4 = 1$  and  $a_1 = \dots = a_s > 0$ : in this case,  $a_1 = \dots = a_s = 4/(5\sqrt{s})$  and  $f(a_1, \dots, a_s) = 4/5 + 1/5 = 1$ .

# Restricted Isometry Property

- ▶ **Def.** For  $s, t > 0$ , define

$$\delta_s := \max_{S \subset [N], |S| \leq s} \|A_S^* A_S - I\|$$

$$\theta_{s,t} := \max\{\|A_T^* A_S\| \mid |S| \leq s, |T| \leq t, S \cap T = \emptyset\}$$

- ▶  $\delta_s \leq \mu_1(s-1) \leq (s-1)\mu$   
(i.e. mutual incoherence  $\Rightarrow$  RIP)
- ▶  $\theta_{s,t} \leq \delta_{s+t}$ ,  $\delta_{2s} \leq \delta_s + \theta_{s,s}$
- ▶  $A$  satisfies RIP of order  $s$  if  $\delta_s$  is small.
- ▶ **Thms.** BP, OMP, IHP are successful if

BP	IHP	HTP	OMP
$\delta_{2s} < 0.6248$	$\delta_{3s} < 0.5773$	$\delta_{3s} < 0.5773$	$\delta_{13s} < 0.1666$

# Sharp RIP bound

## Theorem

*Basis Pursuit can recover  $s$ -sparse vector  $x$  from the measurement data  $y = Ax$  if*

$$\delta_s + \theta_{s,s} < 1$$

*This condition is sharp.*

- ▶ Cai, T. & Zhang, A. (2013). Sharp RIP bound for sparse signal and low-rank matrix recovery. *Applied and Computational Harmonic Analysis* 35, 74-93.
- ▶ Cai, T. T. & Zhang, A. (2013). Compressed sensing and affine rank minimization under restricted isometry. *IEEE Transactions on Signal Processing* 61, 3279-3290.
- ▶ Tony Cai: <http://www-stat.wharton.upenn.edu/~tcai/>

# Lower bound and upper bound of $\delta_s$

- ▶ Theorem 6.8: lower bound of  $\delta_s$ : One has

$$\delta_s \geq \sqrt{\frac{cs}{m}}$$

provided  $N \geq Cm$  and  $\delta_s \leq \delta_*$ .

- ▶ Proposition 6.2: upper bound of  $\delta_s$ :

$$\delta_s \leq (s-1)\mu$$

- ▶ Proposition 5.13: Best upper bound of  $\mu \sim 1/\sqrt{m}$ . Hence we get

$$\delta_s \leq \frac{cs}{\sqrt{m}}$$

- ▶ There are plenty room between  $\sqrt{\frac{cs}{m}}$  and  $\frac{cs}{\sqrt{m}}$ .



## Relation between $\delta_s$ and $m(s)$

- ▶ Corollary 10.8 (necessary condition): Let  $A$  be a  $m \times N$  matrix. If  $\delta_s(A) \leq \delta (= 0.6246)$ , then necessarily

$$m \geq C_\delta s \ln(eN/s).$$

- ▶ In Chapter 9, we shall show:  
If  $m \geq C\delta^{-2}s \ln(eN/s)$ , then certain matrices with high probability satisfy  $\delta_s \leq \delta$ .